## CONTENTS

1 Driver for VM Emulated Devices .......................................................... 2  
  1.1 Validated Hypervisors ................................................................. 2  
  1.2 Recommended Guest Operating System in Virtual Machine .............. 2  
  1.3 Setting Up a KVM Virtual Machine ........................................... 2  
  1.4 Known Limitations of Emulated Devices .................................. 4  

2 IXGBE Driver .................................................................................. 5  
  2.1 Vector PMD for IXGBE ............................................................... 5  

3 I40E/IXGBE/IGB Virtual Function Driver .......................................... 8  
  3.1 SR-IOV Mode Utilization in a DPDK Environment ......................... 8  
  3.2 Setting Up a KVM Virtual Machine Monitor ................................. 14  
  3.3 DPDK SR-IOV PMD PF/VF Driver Usage Model ......................... 18  
  3.4 SR-IOV (PF/VF) Approach for Inter-VM Communication ........... 18  

4 MLX4 poll mode driver library .......................................................... 20  
  4.1 Implementation details .............................................................. 20  
  4.2 Features and limitations ............................................................ 20  
  4.3 Configuration ............................................................................ 21  
  4.4 Prerequisites ............................................................................. 22  
  4.5 Usage example ........................................................................ 24  

5 Poll Mode Driver for Emulated Virtio NIC ......................................... 26  
  5.1 Virtio Implementation in DPDK .................................................... 26  
  5.2 Features and Limitations of virtio PMD ..................................... 26  
  5.3 Prerequisites ............................................................................ 27  
  5.4 Virtio with kni vhost Back End .................................................. 27  
  5.5 Virtio with qemu virtio Back End ............................................... 30  

6 Poll Mode Driver for Paravirtual VMXNET3 NIC ................................. 31  
  6.1 VMXNET3 Implementation in the DPDK .................................... 31  
  6.2 Features and Limitations of VMXNET3 PMD ............................... 32  
  6.3 Prerequisites ............................................................................ 32  
  6.4 VMXNET3 with a Native NIC Connected to a vSwitch ............. 33  
  6.5 VMXNET3 Chaining VMs Connected to a vSwitch .................... 33  

7 Libpcap and Ring Based Poll Mode Drivers ....................................... 37  
  7.1 Using the Drivers from the EAL Command Line ......................... 37
CHAPTER ONE

DRIVER FOR VM EMULATED DEVICES

The DPDK EM poll mode driver supports the following emulated devices:

- qemu-kvm emulated Intel® 82540EM Gigabit Ethernet Controller (qemu e1000 device)
- VMware* emulated Intel® 82545EM Gigabit Ethernet Controller
- VMware emulated Intel® 8274L Gigabit Ethernet Controller.

1.1 Validated Hypervisors

The validated hypervisors are:

- KVM (Kernel Virtual Machine) with Qemu, version 0.14.0
- KVM (Kernel Virtual Machine) with Qemu, version 0.15.1
- VMware ESXi 5.0, Update 1

1.2 Recommended Guest Operating System in Virtual Machine

The recommended guest operating system in a virtualized environment is:

- Fedora* 18 (64-bit)

For supported kernel versions, refer to the DPDK Release Notes.

1.3 Setting Up a KVM Virtual Machine

The following describes a target environment:

- Host Operating System: Fedora 14
- Hypervisor: KVM (Kernel Virtual Machine) with Qemu version, 0.14.0
- Guest Operating System: Fedora 14
- Linux Kernel Version: Refer to the DPDK Getting Started Guide
- Target Applications: testpmd

The setup procedure is as follows:
1. Download qemu-kvm-0.14.0 from http://sourceforge.net/projects/kvm/files/qemu-kvm/ and install it in the Host OS using the following steps:

When using a recent kernel (2.6.25+) with kvm modules included:

```
tar xzf qemu-kvm-release.tar.gz
cd qemu-kvm-release
./configure --prefix=/usr/local/kvm
make
sudo make install
sudo /sbin/modprobe kvm-intel
```

When using an older kernel or a kernel from a distribution without the kvm modules, you must download (from the same link), compile and install the modules yourself:

```
tar xzf kvm-kmod-release.tar.bz2
cd kvm-kmod-release
./configure
make
sudo make install
sudo /sbin/modprobe kvm-intel
```

Note that qemu-kvm installs in the /usr/local/bin directory.

For more details about KVM configuration and usage, please refer to: http://www.linux-kvm.org/page/HOWTO1.

2. Create a Virtual Machine and install Fedora 14 on the Virtual Machine. This is referred to as the Guest Operating System (Guest OS).

3. Start the Virtual Machine with at least one emulated e1000 device.

**Note:** The Qemu provides several choices for the emulated network device backend. Most commonly used is a TAP networking backend that uses a TAP networking device in the host. For more information about Qemu supported networking backends and different options for configuring networking at Qemu, please refer to:

— http://www.linux-kvm.org/page/Networking
— http://qemu.weilnetz.de/qemu-doc.html

For example, to start a VM with two emulated e1000 devices, issue the following command:

```
/usr/local/kvm/bin/qemu-system-x86_64 -cpu host -smp 4 -hda qemu1.raw -m 1024
-net nic,model=e1000,vlan=1,macaddr=DE:AD:1E:00:00:01
-net tap,vlan=1,ifname=tapvm01,script=no,downscript=no
-net nic,model=e1000,vlan=2,macaddr=DE:AD:1E:00:00:02
-net tap,vlan=2,ifname=tapvm02,script=no,downscript=no
```

where:

— -m = memory to assign
— -smp = number of smp cores
— -hda = virtual disk image

This command starts a new virtual machine with two emulated 82540EM devices, backed up with two TAP networking host interfaces, tapvm01 and tapvm02.

5. Log in to the guest OS and check that the expected emulated devices exist:

```
# lspci -d 8086:100e
00:04.0 Ethernet controller: Intel Corporation 82540EM Gigabit Ethernet Controller (rev 03)
00:05.0 Ethernet controller: Intel Corporation 82540EM Gigabit Ethernet Controller (rev 03)
```

6. Install the DPDK and run testpmd.

### 1.4 Known Limitations of Emulated Devices

The following are known limitations:

1. The Qemu e1000 RX path does not support multiple descriptors/buffers per packet. Therefore, `rte_mbuf` should be big enough to hold the whole packet. For example, to allow testpmd to receive jumbo frames, use the following:

   ```
   testpmd [options] --mbuf-size=<your-max-packet-size>
   ```

2. Qemu e1000 does not validate the checksum of incoming packets.
Vector PMD uses Intel® SIMD instructions to optimize packet I/O. It improves load/store bandwidth efficiency of L1 data cache by using a wider SSE/AVX register 1 (1). The wider register gives space to hold multiple packet buffers so as to save instruction number when processing bulk of packets.

There is no change to PMD API. The RX/TX handler are the only two entries for vPMD packet I/O. They are transparently registered at runtime RX/TX execution if all condition checks pass.

1. To date, only an SSE version of IX GBE vPMD is available. To ensure that vPMD is in the binary code, ensure that the option CONFIG_RTE_IXGBE_INC_VECTOR=y is in the configure file.

Some constraints apply as pre-conditions for specific optimizations on bulk packet transfers. The following sections explain RX and TX constraints in the vPMD.

### 2.1.1 RX Constraints

**Prerequisites and Pre-conditions**

The following prerequisites apply:

- To enable vPMD to work for RX, bulk allocation for Rx must be allowed.
- The RTE_LIBRTE_IXGBE_RX_ALLOW_BULK_ALLOC=y configuration MACRO must be set before compiling the code.

Ensure that the following pre-conditions are satisfied:

- `rxq->rx_free_thresh >= RTE_PMD_IXGBE_RX_MAX_BURST`
- `rxq->rx_free_thresh < rxq->nb rx_desc`
- `(rxq->nb rx_desc % rxq->rx_free_thresh) == 0`
- `rxq->nb rx_desc < (IXGBE_MAX_RING_DESC - RTE_PMD_IXGBE_RX_MAX_BURST)`

These conditions are checked in the code.

Scattered packets are not supported in this mode. If an incoming packet is greater than the maximum acceptable length of one “mbuf” data size (by default, the size is 2 KB), vPMD for RX would be disabled.
By default, IXGBE_MAX_RING_DESC is set to 4096 and RTE_PMD_IXGBE_RX_MAX_BURST is set to 32.

**Feature not Supported by RX Vector PMD**

Some features are not supported when trying to increase the throughput in vPMD. They are:

- IEEE1588
- FDIR
- Header split
- RX checksum off load

Other features are supported using optional MACRO configuration. They include:

- HW VLAN strip
- HW extend dual VLAN
- Enabled by RX_OLFLAGS (RTE_IXGBE_RX_OLFLAGS_DISABLE=n)

To guarantee the constraint, configuration flags in dev_conf.rxmode will be checked:

- hw_vlan_strip
- hw_vlan_extend
- hw_ip_checksum
- header_split
- dev_conf

fdir_conf->mode will also be checked.

**RX Burst Size**

As vPMD is focused on high throughput, it assumes that the RX burst size is equal to or greater than 32 per burst. It returns zero if using nb_pkt < 32 as the expected packet number in the receive handler.

**2.1.2 TX Constraint**

**Prerequisite**

The only prerequisite is related to tx_rs_thresh. The tx_rs_thresh value must be greater than or equal to RTE_PMD_IXGBE_TX_MAX_BURST, but less or equal to RTE_IXGBE_TX_MAX_FREE_BUF_SZ. Consequently, by default the tx_rs_thresh value is in the range 32 to 64.
Feature not Supported by RX Vector PMD

TX vPMD only works when txq_flags is set to IXGBE_SIMPLE_FLAGS. This means that it does not support TX multi-segment, VLAN offload and TX csum offload. The following MACROS are used for these three features:

- ETH_TXQ_FLAGS_NOMULTSEGS
- ETH_TXQ_FLAGS_NOVLANOFFL
- ETH_TXQ_FLAGS_NOXSUMSCTP
- ETH_TXQ_FLAGS_NOXSUMUDP
- ETH_TXQ_FLAGS_NOXSUMTCP

2.1.3 Sample Application Notes

testpmd

By default, using CONFIG_RTE_IXGBE_RX_OLFLAGS_DISABLE=n:

```
./x86_64-native-linuxapp-gcc/app/testpmd -c 300 -n 4 -- -i --burst=32 --rxfreet=32 --mbcache=2
```

When CONFIG_RTE_IXGBE_RX_OLFLAGS_DISABLE=y, better performance can be achieved:

```
./x86_64-native-linuxapp-gcc/app/testpmd -c 300 -n 4 -- -i --burst=32 --rxfreet=32 --mbcache=2
```

l3fwd

When running l3fwd with vPMD, there is one thing to note. In the configuration, ensure that port_conf.rxmode.hw_ip_checksum=0. Otherwise, by default, RX vPMD is disabled.

load_balancer

As in the case of l3fwd, set configure port_conf.rxmode.hw_ip_checksum=0 to enable vPMD. In addition, for improved performance, use -bsz “(32,32),(64,64),(32,32)” in load_balancer to avoid using the default burst size of 144.
CHAPTER THREE

I40E/IXGBE/IGB VIRTUAL FUNCTION DRIVER

Supported Intel® Ethernet Controllers (see the DPDK Release Notes for details) support the following modes of operation in a virtualized environment:

- **SR-IOV mode**: Involves direct assignment of part of the port resources to different guest operating systems using the PCI-SIG Single Root I/O Virtualization (SR IOV) standard, also known as “native mode” or “pass-through” mode. In this chapter, this mode is referred to as IOV mode.

- **VMDq mode**: Involves central management of the networking resources by an IO Virtual Machine (IOVM) or a Virtual Machine Monitor (VMM), also known as software switch acceleration mode. In this chapter, this mode is referred to as the Next Generation VMDq mode.

### 3.1 SR-IOV Mode Utilization in a DPDK Environment

The DPDK uses the SR-IOV feature for hardware-based I/O sharing in IOV mode. Therefore, it is possible to partition SR-IOV capability on Ethernet controller NIC resources logically and expose them to a virtual machine as a separate PCI function called a “Virtual Function”. Refer to Fig. 3.1.

Therefore, a NIC is logically distributed among multiple virtual machines (as shown in Fig. 3.1), while still having global data in common to share with the Physical Function and other Virtual Functions. The DPDK fm10kvf, i40evf, igbvf or ixgbevf as a Poll Mode Driver (PMD) serves for the Intel® 82576 Gigabit Ethernet Controller, Intel® Ethernet Controller I350 family, Intel® 82599 10 Gigabit Ethernet Controller NIC, Intel® Fortville 10/40 Gigabit Ethernet Controller NIC’s virtual PCI function, or PCIe host-interface of the Intel Ethernet Switch FM10000 Series. Meanwhile the DPDK Poll Mode Driver (PMD) also supports “Physical Function” of such NIC’s on the host.

The DPDK PF/VF Poll Mode Driver (PMD) supports the Layer 2 switch on Intel® 82576 Gigabit Ethernet Controller, Intel® Ethernet Controller I350 family, Intel® 82599 10 Gigabit Ethernet Controller, and Intel® Fortville 10/40 Gigabit Ethernet Controller NICs so that guest can choose it for inter virtual machine traffic in SR-IOV mode.

For more detail on SR-IOV, please refer to the following documents:

- SR-IOV provides hardware based I/O sharing
- PCI-SIG-Single Root I/O Virtualization Support on IA
- Scalable I/O Virtualized Servers
Figure 3.1: Virtualization for a Single Port NIC in SR-IOV Mode
3.1.1 Physical and Virtual Function Infrastructure

The following describes the Physical Function and Virtual Functions infrastructure for the supported Ethernet Controller NICs.

Virtual Functions operate under the respective Physical Function on the same NIC Port and therefore have no access to the global NIC resources that are shared between other functions for the same NIC port.

A Virtual Function has basic access to the queue resources and control structures of the queues assigned to it. For global resource access, a Virtual Function has to send a request to the Physical Function for that port, and the Physical Function operates on the global resources on behalf of the Virtual Function. For this out-of-band communication, an SR-IOV enabled NIC provides a memory buffer for each Virtual Function, which is called a “Mailbox”.

The PCIE host-interface of Intel Ethernet Switch FM10000 Series VF infrastructure

In a virtualized environment, the programmer can enable a maximum of 64 Virtual Functions (VF) globally per PCIE host-interface of the Intel Ethernet Switch FM10000 Series device. Each VF can have a maximum of 16 queue pairs. The Physical Function in host could be only configured by the Linux* fm10k driver (in the case of the Linux Kernel-based Virtual Machine [KVM]), DPDK PMD PF driver doesn’t support it yet.

For example,

- Using Linux* fm10k driver:

```bash
rmmod fm10k (To remove the fm10k module)
insmod fm10k.ko max_vfs=2,2 (To enable two Virtual Functions per port)
```

Virtual Function enumeration is performed in the following sequence by the Linux* pci driver for a dual-port NIC. When you enable the four Virtual Functions with the above command, the four enabled functions have a Function# represented by (Bus#, Device#, Function#) in sequence starting from 0 to 3. However:

- Virtual Functions 0 and 2 belong to Physical Function 0
- Virtual Functions 1 and 3 belong to Physical Function 1

Note: The above is an important consideration to take into account when targeting specific packets to a selected port.

Intel® Fortville 10/40 Gigabit Ethernet Controller VF Infrastructure

In a virtualized environment, the programmer can enable a maximum of 128 Virtual Functions (VF) globally per Intel® Fortville 10/40 Gigabit Ethernet Controller NIC device. Each VF can have a maximum of 16 queue pairs. The Physical Function in host could be either configured by the Linux* i40e driver (in the case of the Linux Kernel-based Virtual Machine [KVM]) or by DPDK PMD PF driver. When using both DPDK PMD PF/VF drivers, the whole NIC will be taken over by DPDK based application.

For example,

- Using Linux* i40e driver:
Network Interface Controller Drivers, Release 2.0.0

```
rmmod i40e (To remove the i40e module)
insmod i40e.ko max_vfs=2,2 (To enable two Virtual Functions per port)
```

- **Using the DPDK PMD PF i40e driver:**
  
  **Kernel Params:** iommu=pt, intel_iommu=on

  ```
  modprobe uio
  insmod igb_uio
  ./dpdk_nic_bind.py -b igb_uio bb:ss.f
  echo 2 > /sys/bus/pci/devices/0000:bb:ss.f/max_vfs (To enable two VFs on a specific PCI device)
  ```

  Launch the DPDK testpmd/example or your own host daemon application using the DPDK PMD library.

- **Using the DPDK PMD PF ixgbe driver to enable VF RSS:**
  
  Same steps as above to install the modules of uio, igb_uio, specify max_vfs for PCI device, and launch the DPDK testpmd/example or your own host daemon application using the DPDK PMD library.

  The available queue number (at most 4) per VF depends on the total number of pool, which is determined by the max number of VF at PF initialization stage and the number of queue specified in config:

  - If the max number of VF is set in the range of 1 to 32:
    
    If the number of rxq is specified as 4 (e.g. `–rxq 4` in testpmd), then there are totally 32 pools (ETH_32_POOLS), and each VF could have 4 or less (e.g. 2) queues;
    
    If the number of rxq is specified as 2 (e.g. `–rxq 2` in testpmd), then there are totally 32 pools (ETH_32_POOLS), and each VF could have 2 queues;

  - If the max number of VF is in the range of 33 to 64:
    
    If the number of rxq is 4 (`–rxq 4` in testpmd), then error message is expected as rxq is not correct at this case;
    
    If the number of rxq is 2 (`–rxq 2` in testpmd), then there is totally 64 pools (ETH_64_POOLS), and each VF have 2 queues;

  On host, to enable VF RSS functionality, rx mq mode should be set as ETH_MQ_RX_VMDQ_RSS or ETH_MQ_RX_RSS mode, and SRIOV mode should be activated (max_vfs >= 1). It also needs config VF RSS information like hash function, RSS key, RSS key length.

  ```
  testpmd -c 0xffff -n 4 -- --coremask=<core-mask> --rxq=4 --txq=4 -i
  ```

  The limitation for VF RSS on Intel® 82599 10 Gigabit Ethernet Controller is: The hash and key are shared among PF and all VF, the RETA table with 128 entries is also shared among PF and all VF; So it could not to provide a method to query the hash and reta content per VF on guest, while, if possible, please query them on host(PF) for the shared RETA information.

  Virtual Function enumeration is performed in the following sequence by the Linux* pci driver for a dual-port NIC. When you enable the four Virtual Functions with the above command, the four enabled functions have a Function# represented by (Bus#, Device#, Function#) in sequence starting from 0 to 3. However:

3.1. SR-IOV Mode Utilization in a DPDK Environment
• Virtual Functions 0 and 2 belong to Physical Function 0
• Virtual Functions 1 and 3 belong to Physical Function 1

Note: The above is an important consideration to take into account when targeting specific packets to a selected port.

**Intel® 82599 10 Gigabit Ethernet Controller VF Infrastructure**

The programmer can enable a maximum of 63 Virtual Functions and there must be one Physical Function per Intel® 82599 10 Gigabit Ethernet Controller NIC port. The reason for this is that the device allows for a maximum of 128 queues per port and a virtual/physical function has to have at least one queue pair (RX/TX). The current implementation of the DPDK ixgbevf driver supports a single queue pair (RX/TX) per Virtual Function. The Physical Function in host could be either configured by the Linux* ixgbe driver (in the case of the Linux Kernel-based Virtual Machine [KVM]) or by DPDK PMD PF driver. When using both DPDK PMD PF/VF drivers, the whole NIC will be taken over by DPDK based application.

For example,

• Using Linux* ixgbe driver:

```bash
rmmod ixgbe (To remove the ixgbe module)
insmod ixgbe max_vfs=2,2 (To enable two Virtual Functions per port)
```

• Using the DPDK PMD PF ixgbe driver:

  Kernel Params: iommu=pt, intel_iommu=on

  ```bash
  modprobe uio
  insmod igb_uio
  ./dpdk_nic_bind.py -b igb_uio bb:ss.f
  echo 2 > /sys/bus/pci/devices/0000:bb:ss.f/max_vfs (To enable two VFs on a specific PCI device)
  ```

  Launch the DPDK testpmd/example or your own host daemon application using the DPDK PMD library.

  Virtual Function enumeration is performed in the following sequence by the Linux* pci driver for a dual-port NIC. When you enable the four Virtual Functions with the above command, the four enabled functions have a Function# represented by (Bus#, Device#, Function#) in sequence starting from 0 to 3. However:

  • Virtual Functions 0 and 2 belong to Physical Function 0
  • Virtual Functions 1 and 3 belong to Physical Function 1

Note: The above is an important consideration to take into account when targeting specific packets to a selected port.

**Intel® 82576 Gigabit Ethernet Controller and Intel® Ethernet Controller I350 Family VF Infrastructure**

In a virtualized environment, an Intel® 82576 Gigabit Ethernet Controller serves up to eight virtual machines (VMs). The controller has 16 TX and 16 RX queues. They are generally
referred to (or thought of) as queue pairs (one TX and one RX queue). This gives the controller 16 queue pairs.

A pool is a group of queue pairs for assignment to the same VF, used for transmit and receive operations. The controller has eight pools, with each pool containing two queue pairs, that is, two TX and two RX queues assigned to each VF.

In a virtualized environment, an Intel® Ethernet Controller I350 family device serves up to eight virtual machines (VMs) per port. The eight queues can be accessed by eight different VMs if configured correctly (the i350 has 4x1GbE ports each with 8T X and 8 RX queues), that means, one Transmit and one Receive queue assigned to each VF.

For example,

- Using Linux® igb driver:
  ```
  rmmod igb (To remove the igb module)
  insmod igb max_vfs=2,2 (To enable two Virtual Functions per port)
  ```

- Using Intel® DPDK PMD PF igb driver:
  ```
  Kernel Params: iommu=pt, intel_iommu=on
  modprobe uio
  ```
  ```
  insmod igb_uio
  ./dpdk_nic_bind.py -b igb_uio bb:ss.f
  echo 2 > /sys/bus/pci/devices/0000\:bb\:ss.f/max_vfs (To enable two VFs on a specific pci device)
  ```
  ```
  Launch DPDK testpmd/example or your own host daemon application using the DPDK PMD library.
  ```

Virtual Function enumeration is performed in the following sequence by the Linux® pci driver for a four-port NIC. When you enable the four Virtual Functions with the above command, the four enabled functions have a Function# represented by (Bus#, Device#, Function#) in sequence, starting from 0 to 7. However:

- Virtual Functions 0 and 4 belong to Physical Function 0
- Virtual Functions 1 and 5 belong to Physical Function 1
- Virtual Functions 2 and 6 belong to Physical Function 2
- Virtual Functions 3 and 7 belong to Physical Function 3

**Note:** The above is an important consideration to take into account when targeting specific packets to a selected port.

### 3.1.2 Validated Hypervisors

The validated hypervisor is:

- KVM (Kernel Virtual Machine) with Qemu, version 0.14.0

However, the hypervisor is bypassed to configure the Virtual Function devices using the Mailbox interface, the solution is hypervisor-agnostic. Xen® and VMware® (when SR-IOV is supported) will also be able to support the DPDK with Virtual Function driver support.

### 3.1. SR-IOV Mode Utilization in a DPDK Environment
3.1.3 Expected Guest Operating System in Virtual Machine

The expected guest operating systems in a virtualized environment are:

- Fedora* 14 (64-bit)
- Ubuntu* 10.04 (64-bit)

For supported kernel versions, refer to the DPDK Release Notes.

3.2 Setting Up a KVM Virtual Machine Monitor

The following describes a target environment:

- Host Operating System: Fedora 14
- Hypervisor: KVM (Kernel Virtual Machine) with Qemu version 0.14.0
- Guest Operating System: Fedora 14
- Linux Kernel Version: Refer to the DPDK Getting Started Guide
- Target Applications: l2fwd, l3fwd-vf

The setup procedure is as follows:

1. Before booting the Host OS, open BIOS setup and enable Intel® VT features.
2. While booting the Host OS kernel, pass the intel_iommu=on kernel command line argument using GRUB. When using DPDK PF driver on host, pass the iommu=pt kernel command line argument in GRUB.
3. Download qemu-kvm-0.14.0 from http://sourceforge.net/projects/kvm/files/qemu-kvm/ and install it in the Host OS using the following steps:

   When using a recent kernel (2.6.25+) with kvm modules included:

   ```bash
tar xzf qemu-kvm-release.tar.gz
cd qemu-kvm-release
./configure --prefix=/usr/local/kvm
make
sudo make install
```

   When using an older kernel, or a kernel from a distribution without the kvm modules, you must download (from the same link), compile and install the modules yourself:

   ```bash
tar xjf kvm-kmod-release.tar.bz2
cd kvm-kmod-release
./configure
make
sudo make install
```

qemu-kvm installs in the /usr/local/bin directory.

For more details about KVM configuration and usage, please refer to:

4. Create a Virtual Machine and install Fedora 14 on the Virtual Machine. This is referred to as the Guest Operating System (Guest OS).

5. Download and install the latest ixgbe driver from:

6. In the Host OS
   
   When using Linux kernel ixgbe driver, unload the Linux ixgbe driver and reload it with the max_vfs=2,2 argument:

   ```
   rmmod ixgbe
   modprobe ixgbe max_vfs=2,2
   ```

   When using DPDK PMD PF driver, insert DPDK kernel module igb_uio and set the number of VF by sysfs max_vfs:

   ```
   modprobe uio
   insmod igb_uio
   ./dpdk_nic_bind.py -b igb_uio 02:00.0 02:00.1 0e:00.0 0e:00.1
   ```

   ```
   echo 2 > /sys/bus/pci/devices/0000:02:00.0/max_vfs
   echo 2 > /sys/bus/pci/devices/0000:02:00.1/max_vfs
   echo 2 > /sys/bus/pci/devices/0000:0e:00.0/max_vfs
   echo 2 > /sys/bus/pci/devices/0000:0e:00.1/max_vfs
   ```

   **Note:** You need to explicitly specify number of vfs for each port, for example, in the command above, it creates two vfs for the first two ixgbe ports.

Let say we have a machine with four physical ixgbe ports:

<table>
<thead>
<tr>
<th>Device</th>
<th>Address</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000:02:00.0</td>
<td></td>
</tr>
<tr>
<td>0000:02:00.1</td>
<td></td>
</tr>
<tr>
<td>0000:0e:00.0</td>
<td></td>
</tr>
<tr>
<td>0000:0e:00.1</td>
<td></td>
</tr>
</tbody>
</table>

The command above creates two vfs for device 0000:02:00.0:

```
ls -alrt /sys/bus/pci/devices/0000:02:00.0/virt*  
lrwxrwxrwx. 1 root root 0 Apr 13 05:40 /sys/bus/pci/devices/0000:02:00.0/virtfn1 -> ../0000:02:10.2  
lrwxrwxrwx. 1 root root 0 Apr 13 05:40 /sys/bus/pci/devices/0000:02:00.0/virtfn0 -> ../0000:02:10.0
```

It also creates two vfs for device 0000:02:00.1:

```
ls -alrt /sys/bus/pci/devices/0000:02:00.1/virt*  
lrwxrwxrwx. 1 root root 0 Apr 13 05:40 /sys/bus/pci/devices/0000:02:00.1/virtfn1 -> ../0000:02:10.3  
lrwxrwxrwx. 1 root root 0 Apr 13 05:40 /sys/bus/pci/devices/0000:02:00.1/virtfn0 -> ../0000:02:10.1
```

7. List the PCI devices connected and notice that the Host OS shows two Physical Functions (traditional ports) and four Virtual Functions (two for each port). This is the result of the previous step.

8. Insert the pci_stub module to hold the PCI devices that are freed from the default driver using the following command (see http://www.linux-kvm.org/page/How_to_assign_devices_with_VT-d_in_KVM Section 4 for more information):

3.2. Setting Up a KVM Virtual Machine Monitor
Network Interface Controller Drivers, Release 2.0.0

```
sudo /sbin/modprobe pci-stub
```

Unbind the default driver from the PCI devices representing the Virtual Functions. A script to perform this action is as follows:

```
echo "8086 10ed" > /sys/bus/pci/drivers/pci-stub/new_id
echo 0000:08:10.0 > /sys/bus/pci/devices/0000:08:10.0/driver/unbind
echo 0000:08:10.0 > /sys/bus/pci/drivers/pci-stub/bind
```

where, 0000:08:10.0 belongs to the Virtual Function visible in the Host OS.

9. Now, start the Virtual Machine by running the following command:

```
/usr/local/kvm/bin/qemu-system-x86_64 -m 4096 -smp 4 -boot c -hda lucid.qcow2 -device pci-assign,host=08:10.0
```

where:

- `-m` = memory to assign
- `-smp` = number of smp cores
- `-boot` = boot option
- `-hda` = virtual disk image
- `-device = device to attach`

**Note:**

- The `pci-assign,host=08:10.0` value indicates that you want to attach a PCI device to a Virtual Machine and the respective (Bus:Device.Function) numbers should be passed for the Virtual Function to be attached.

- qemu-kvm-0.14.0 allows a maximum of four PCI devices assigned to a VM, but this is qemu-kvm version dependent since qemu-kvm-0.14.1 allows a maximum of five PCI devices.

- qemu-system-x86_64 also has a `-cpu` command line option that is used to select the cpu_model to emulate in a Virtual Machine. Therefore, it can be used as:

```
/usr/local/kvm/bin/qemu-system-x86_64 -cpu ?
(to list all available cpu_models)
```

```
/usr/local/kvm/bin/qemu-system-x86_64 -m 4096 -cpu host -smp 4 -boot c -hda lucid.qcow2 -device pci-assign,host=08:10.0
```

(to use the same cpu_model equivalent to the host cpu)

For more information, please refer to: [http://wiki.qemu.org/Features/CPUModels](http://wiki.qemu.org/Features/CPUModels).

10. Install and run DPDK host app to take over the Physical Function. Eg.

```
make install T=x86_64-native-linuxapp-gcc
./x86_64-native-linuxapp-gcc/app/testpmd -c f -n 4 -- -i
```

11. Finally, access the Guest OS using vncviewer with the localhost:5900 port and check the lspci command output in the Guest OS. The virtual functions will be listed as available for use.

12. Configure and install the DPDK with an x86_64-native-linuxapp-gcc configuration on the Guest OS as normal, that is, there is no change to the normal installation procedure.
Note: If you are unable to compile the DPDK and you are getting "error: CPU you selected does not support x86-64 instruction set", power off the Guest OS and start the virtual machine with the correct -cpu option in the qemu- system-x86_64 command as shown in step 9. You must select the best x86_64 cpu_model to emulate or you can select host option if available.

Note: Run the DPDK l2fwd sample application in the Guest OS with Hugepages enabled. For the expected benchmark performance, you must pin the cores from the Guest OS to the Host OS (taskset can be used to do this) and you must also look at the PCI Bus layout on the board to ensure you are not running the traffic over the QPI Interface.

Note:

- The Virtual Machine Manager (the Fedora package name is virt-manager) is a utility for virtual machine management that can also be used to create, start, stop and delete virtual machines. If this option is used, step 2 and 6 in the instructions provided will be different.
- virsh, a command line utility for virtual machine management, can also be used to bind and unbind devices to a virtual machine in Ubuntu. If this option is used, step 6 in the instructions provided will be different.
- The Virtual Machine Monitor (see Fig. 3.2) is equivalent to a Host OS with KVM installed as described in the instructions.

Figure 3.2: Performance Benchmark Setup
3.3 DPDK SR-IOV PMD PF/VF Driver Usage Model

3.3.1 Fast Host-based Packet Processing

Software Defined Network (SDN) trends are demanding fast host-based packet handling. In a virtualization environment, the DPDK VF PMD driver performs the same throughput result as a non-VT native environment.

With such host instance fast packet processing, lots of services such as filtering, QoS, DPI can be offloaded on the host fast path.

Fig. 3.3 shows the scenario where some VMs directly communicate externally via a VFs, while others connect to a virtual switch and share the same uplink bandwidth.

![Figure 3.3: Fast Host-based Packet Processing](image)

3.4 SR-IOV (PF/VF) Approach for Inter-VM Communication

Inter-VM data communication is one of the traffic bottle necks in virtualization platforms. SR-IOV device assignment helps a VM to attach the real device, taking advantage of the bridge in the NIC. So VF-to-VF traffic within the same physical port (VM0<->VM1) have hardware acceleration. However, when VF crosses physical ports (VM0<->VM2), there is no such hardware bridge. In this case, the DPDK PMD PF driver provides host forwarding between such VMs.

Fig. 3.4 shows an example. In this case an update of the MAC address lookup tables in both the NIC and host DPDK application is required.
In the NIC, writing the destination of a MAC address belongs to another cross device VM to the PF specific pool. So when a packet comes in, its destination MAC address will match and forward to the host DPDK PMD application.

In the host DPDK application, the behavior is similar to L2 forwarding, that is, the packet is forwarded to the correct PF pool. The SR-IOV NIC switch forwards the packet to a specific VM according to the MAC destination address which belongs to the destination VF on the VM.

Figure 3.4: Inter-VM Communication
CHAPTER
FOUR

MLX4 POLL MODE DRIVER LIBRARY

The MLX4 poll mode driver library (librte_pmd_mlx4) implements support for Mellanox ConnectX-3 EN 10/40 Gbps adapters as well as their virtual functions (VF) in SR-IOV context.

Information and documentation about this family of adapters can be found on the Mellanox website. Help is also provided by the Mellanox community.

There is also a section dedicated to this poll mode driver.

Note: Due to external dependencies, this driver is disabled by default. It must be enabled manually by setting CONFIG_RTE_LIBRTE_MLX4_PMD=y and recompiling DPDK.

4.1 Implementation details

Most Mellanox ConnectX-3 devices provide two ports but expose a single PCI bus address, thus unlike most drivers, librte_pmd_mlx4 registers itself as a PCI driver that allocates one Ethernet device per detected port.

For this reason, one cannot white/blacklist a single port without also white/blacklisting the others on the same device.

Besides its dependency on libibverbs (that implies libmlx4 and associated kernel support), librte_pmd_mlx4 relies heavily on system calls for control operations such as querying/updating the MTU and flow control parameters.

For security reasons and robustness, this driver only deals with virtual memory addresses. The way resources allocations are handled by the kernel combined with hardware specifications that allow it to handle virtual memory addresses directly ensure that DPDK applications cannot access random physical memory (or memory that does not belong to the current process).

This capability allows the PMD to coexist with kernel network interfaces which remain functional, although they stop receiving unicast packets as long as they share the same MAC address.

Compiling librte_pmd_mlx4 causes DPDK to be linked against libibverbs.

4.2 Features and limitations

- RSS, also known as RCA, is supported. In this mode the number of configured RX queues must be a power of two.
• VLAN filtering is supported.
• Link state information is provided.
• Promiscuous mode is supported.
• All multicast mode is supported.
• Multiple MAC addresses (unicast, multicast) can be configured.
• Scattered packets are supported for TX and RX.
• RSS hash key cannot be modified.
• Hardware counters are not implemented (they are software counters).
• Checksum offloads are not supported yet.

4.3 Configuration

4.3.1 Compilation options

These options can be modified in the .config file.

- **CONFIG_RTE_LIBRTE_MLX4_PMD** (default n)
  Toggle compilation of librte_pmd_mlx4 itself.

- **CONFIG_RTE_LIBRTE_MLX4_DEBUG** (default n)
  Toggle debugging code and stricter compilation flags. Enabling this option adds additional run-time checks and debugging messages at the cost of lower performance.

- **CONFIG_RTE_LIBRTE_MLX4_SGE_WR_N** (default 4)
  Number of scatter/gather elements (SGEs) per work request (WR). Lowering this number improves performance but also limits the ability to receive scattered packets (packets that do not fit a single mbuf). The default value is a safe tradeoff.

- **CONFIG_RTE_LIBRTE_MLX4_MAX_INLINE** (default 0)
  Amount of data to be inlined during TX operations. Improves latency but lowers throughput.

- **CONFIG_RTE_LIBRTE_MLX4_TX_MP_CACHE** (default 8)
  Maximum number of cached memory pools (MPs) per TX queue. Each MP from which buffers are to be transmitted must be associated to memory regions (MRs). This is a slow operation that must be cached.
  This value is always 1 for RX queues since they use a single MP.

- **CONFIG_RTE_LIBRTE_MLX4_SOFT_COUNTERS** (default 1)
  Toggle software counters. No counters are available if this option is disabled since hardware counters are not supported.
4.3.2 Environment variables

- **MLX4_INLINE_RECV_SIZE**
  A nonzero value enables inline receive for packets up to that size. May significantly improve performance in some cases but lower it in others. Requires careful testing.

4.3.3 Run-time configuration

- The only constraint when RSS mode is requested is to make sure the number of RX queues is a power of two. This is a hardware requirement.
- librte_pmd_mlx4 brings kernel network interfaces up during initialization because it is affected by their state. Forcing them down prevents packets reception.
- `ethtool` operations on related kernel interfaces also affect the PMD.

4.3.4 Kernel module parameters

The `mlx4_core` kernel module has several parameters that affect the behavior and/or the performance of librte_pmd_mlx4. Some of them are described below.

- **num_vfs** (integer or triplet, optionally prefixed by device address strings)
  Create the given number of VFs on the specified devices.

- **log_num_mgm_entry_size** (integer)
  Device-managed flow steering (DMFS) is required by DPDK applications. It is enabled by using a negative value, the last four bits of which have a special meaning.
  - `-1`: force device-managed flow steering (DMFS).
  - `-7`: configure optimized steering mode to improve performance with the following limitation: Ethernet frames with the port MAC address as the destination cannot be received, even in promiscuous mode. Additional MAC addresses can still be set by `rte_eth_dev_mac_addr_addr()`.

4.4 Prerequisites

This driver relies on external libraries and kernel drivers for resources allocations and initialization. The following dependencies are not part of DPDK and must be installed separately:

- **libibverbs**
  User space verbs framework used by librte_pmd_mlx4. This library provides a generic interface between the kernel and low-level user space drivers such as libmlx4.
  It allows slow and privileged operations (context initialization, hardware resources allocations) to be managed by the kernel and fast operations to never leave user space.

- **libmlx4**
  Low-level user space driver library for Mellanox ConnectX-3 devices, it is automatically loaded by libibverbs.
This library basically implements send/receive calls to the hardware queues.

- **Kernel modules** (mlnx-ofed-kernel)

  They provide the kernel-side verbs API and low level device drivers that manage actual hardware initialization and resources sharing with user space processes.

  Unlike most other PMDs, these modules must remain loaded and bound to their devices:
  - mlx4_core: hardware driver managing Mellanox ConnectX-3 devices.
  - mlx4_en: Ethernet device driver that provides kernel network interfaces.
  - mlx4_ib: InfiniBand device driver.
  - ib_uverbs: user space driver for verbs (entry point for libibverbs).

- **Firmware update**

  Mellanox OFED releases include firmware updates for ConnectX-3 adapters.

  Because each release provides new features, these updates must be applied to match the kernel modules and libraries they come with.

  **Note:** Both libraries are BSD and GPL licensed. Linux kernel modules are GPL licensed.

Currently supported by DPDK:

- Mellanox OFED **2.4-1**.
- Firmware version **2.33.5000** and higher.

### 4.4.1 Getting Mellanox OFED

While these libraries and kernel modules are available on OpenFabrics Alliance’s website and provided by package managers on most distributions, this PMD requires Ethernet extensions that may not be supported at the moment (this is a work in progress).

Mellanox OFED includes the necessary support and should be used in the meantime. For DPDK, only libibverbs, libmlx4, mlnx-ofed-kernel packages and firmware updates are required from that distribution.

**Note:** Several versions of Mellanox OFED are available. Installing the version this DPDK release was developed and tested against is strongly recommended. Please check the pre-requisites.

### 4.4.2 Getting libibverbs and libmlx4 from DPDK.org

Based on Mellanox OFED, optimized libibverbs and libmlx4 versions can be optionally downloaded from DPDK.org:

http://www.dpdk.org/download/mlx4

Some enhancements are done for better performance with DPDK applications and are not merged upstream yet.
Since it is partly achieved by tuning compilation options to disable features not needed by DPDK, linking these libraries statically and avoid system-wide installation is the preferred method.

Installation documentation is available from the above link.

### 4.5 Usage example

This section demonstrates how to launch testpmd with Mellanox ConnectX-3 devices managed by librte_pmd mlx4.

1. Load the kernel modules:
   
   ```
   modprobe -a ib_uverbs mlx4_en mlx4_core mlx4_ib
   ```

   **Note:** User space I/O kernel modules (uio and igb_uio) are not used and do not have to be loaded.

2. Make sure Ethernet interfaces are in working order and linked to kernel verbs. Related sysfs entries should be present:
   
   ```
   ls -d /sys/class/net/*/device/infiniband_verbs/uverbs* | cut -d / -f 5
   ```

   **Example output:**

   ```
   eth2
   eth3
   eth4
   eth5
   ```

3. Optionally, retrieve their PCI bus addresses for whitelisting:
   
   ```
   {
   for intf in eth2 eth3 eth4 eth5; 
   do 
       (cd "/sys/class/net/${intf}/device" && pwd -P); 
   done; 
   } | sed -n
   ```

   **Example output:**

   ```
   -w 0000:83:00.0
   -w 0000:83:00.0
   -w 0000:84:00.0
   -w 0000:84:00.0
   ```

   **Note:** There are only two distinct PCI bus addresses because the Mellanox ConnectX-3 adapters installed on this system are dual port.

4. Request huge pages:
   
   ```
   echo 1024 > /sys/kernel/mm/hugepages/hugepages-2048kB/nr_hugepages/nr_hugepages
   ```

5. Start testpmd with basic parameters:
Example output:

```plaintext
[...] EAL: PCI device 0000:83:00.0 on NUMA socket 1
EAL: probe driver: 15b3:1007 librte_pmd_mlx4
PMD: librte_pmd_mlx4: PCI information matches, using device "mlx4_0" (VF: false)
PMD: librte_pmd_mlx4: 2 port(s) detected
PMD: librte_pmd_mlx4: port 1 MAC address is 00:02:c9:b5:b7:50
PMD: librte_pmd_mlx4: port 2 MAC address is 00:02:c9:b5:b7:51
EAL: PCI device 0000:84:00.0 on NUMA socket 1
EAL: probe driver: 15b3:1007 librte_pmd_mlx4
PMD: librte_pmd_mlx4: PCI information matches, using device "mlx4_1" (VF: false)
PMD: librte_pmd_mlx4: 2 port(s) detected
PMD: librte_pmd_mlx4: port 1 MAC address is 00:02:c9:b5:ba:b0
PMD: librte_pmd_mlx4: port 2 MAC address is 00:02:c9:b5:ba:b1
Interactive-mode selected
Configuring Port 0 (socket 0)
PMD: librte_pmd_mlx4: 0x867d60: TX queues number update: 0 -> 2
PMD: librte_pmd_mlx4: 0x867d60: RX queues number update: 0 -> 2
Port 0: 00:02:C9:B5:B7:50
Configuring Port 1 (socket 0)
PMD: librte_pmd_mlx4: 0x867da0: TX queues number update: 0 -> 2
PMD: librte_pmd_mlx4: 0x867da0: RX queues number update: 0 -> 2
Port 1: 00:02:C9:B5:B7:51
Configuring Port 2 (socket 0)
PMD: librte_pmd_mlx4: 0x867de0: TX queues number update: 0 -> 2
PMD: librte_pmd_mlx4: 0x867de0: RX queues number update: 0 -> 2
Port 2: 00:02:C9:B5:BA:B0
Configuring Port 3 (socket 0)
PMD: librte_pmd_mlx4: 0x867e20: TX queues number update: 0 -> 2
PMD: librte_pmd_mlx4: 0x867e20: RX queues number update: 0 -> 2
Port 3: 00:02:C9:B5:BA:B1
Checking link statuses...
Port 0 Link Up - speed 10000 Mbps - full-duplex
Port 1 Link Up - speed 40000 Mbps - full-duplex
Port 2 Link Up - speed 10000 Mbps - full-duplex
Port 3 Link Up - speed 40000 Mbps - full-duplex
Done
testpmd>
```
POLL MODE DRIVER FOR EMULATED VIRTIO NIC

Virtio is a para-virtualization framework initiated by IBM, and supported by KVM hypervisor. In the Data Plane Development Kit (DPDK), we provide a virtio Poll Mode Driver (PMD) as a software solution, comparing to SRIOV hardware solution, for fast guest VM to guest VM communication and guest VM to host communication.

Vhost is a kernel acceleration module for virtio qemu backend. The DPDK extends kni to support vhost raw socket interface, which enables vhost to directly read/write packets from/to a physical port. With this enhancement, virtio could achieve quite promising performance.

In future release, we will also make enhancement to vhost backend, releasing peak performance of virtio PMD driver.

For basic qemu-KVM installation and other Intel EM poll mode driver in guest VM, please refer to Chapter “Driver for VM Emulated Devices”.

In this chapter, we will demonstrate usage of virtio PMD driver with two backends, standard qemu vhost back end and vhost kni back end.

5.1 Virtio Implementation in DPDK

For details about the virtio spec, refer to Virtio PCI Card Specification written by Rusty Russell.

As a PMD, virtio provides packet reception and transmission callbacks virtio_recv_pkts and virtio_xmit_pkts.

In virtio_recv_pkts, index in range \([vq->vq_used_cons_idx, vq->vq_ring.used->idx)\) in vring is available for virtio to burst out.

In virtio_xmit_pkts, same index range in vring is available for virtio to clean. Virtio will enqueue to be transmitted packets into vring, advance the vq->vq_ring.avail->idx, and then notify the host back end if necessary.

5.2 Features and Limitations of virtio PMD

In this release, the virtio PMD driver provides the basic functionality of packet reception and transmission.

- It supports merge-able buffers per packet when receiving packets and scattered buffer per packet when transmitting packets. The packet size supported is from 64 to 1518.
- It supports multicast packets and promiscuous mode.
• The descriptor number for the RX/TX queue is hard-coded to be 256 by qemu. If given a different descriptor number by the upper application, the virtio PMD generates a warning and fall back to the hard-coded value.

• Features of mac/vlan filter are supported, negotiation with vhost/backend are needed to support them. When backend can’t support vlan filter, virtio app on guest should disable vlan filter to make sure the virtio port is configured correctly. E.g. specify ‘--disable-hw-vlan’ in testpmd command line.

• RTE_PKTMBUF_HEADROOM should be defined larger than sizeof(struct virtio_net_hdr), which is 10 bytes.

• Virtio does not support runtime configuration.

• Virtio supports Link State interrupt.

• Virtio supports software vlan stripping and inserting.

• Virtio supports using port IO to get PCI resource when uio/igb_uio module is not available.

5.3 Prerequisites

The following prerequisites apply:

• In the BIOS, turn VT-x and VT-d on

• Linux kernel with KVM module; vhost module loaded and ioeventfd supported. Qemu standard backend without vhost support isn’t tested, and probably isn’t supported.

5.4 Virtio with kni vhost Back End

This section demonstrates kni vhost back end example setup for Phy-VM Communication.

Host2VM communication example

1. Load the kni kernel module:

   insmod rte_kni.ko

Other basic DPDK preparations like hugepage enabling, uio port binding are not listed here. Please refer to the DPDK Getting Started Guide for detailed instructions.

2. Launch the kni user application:

   examples/kni/build/app/kni -c 0xf -n 4 -- -p 0x1 -l 0x1 -o 0x2

This command generates one network device vEth0 for physical port. If specify more physical ports, the generated network device will be vEth1, vEth2, and so on.

For each physical port, kni creates two user threads. One thread loops to fetch packets from the physical NIC port into the kni receive queue. The other user thread loops to send packets in the kni transmit queue.
Figure 5.1: Host2VM Communication Example Using kni vhost Back End

Host2VM communication example
For each physical port, kni also creates a kernel thread that retrieves packets from the kni receive queue, place them onto kni's raw socket's queue and wake up the vhost kernel thread to exchange packets with the virtio virt queue.

For more details about kni, please refer to Chapter 24 “Kernel NIC Interface”.

3. Enable the kni raw socket functionality for the specified physical NIC port, get the generated file descriptor and set it in the qemu command line parameter. Always remember to set ioeventfd_on and vhost_on.

Example:

```
echo 1 > /sys/class/net/vEth0/sock_en
fd=cat /sys/class/net/vEth0/sock_fd
exec qemu-system-x86_64 -enable-kvm -cpu host \
  -m 2048 -smp 4 -name dpdk-test1-vm1 \
  -drive file=/data/DPDKVMS/dpdk-vm.img \
  -netdev tap, fd=$fd,id=mynet_kni, script=no,vhost=on \
  -device virtio-net-pci,netdev=mynet_kni,bus=pci.0,addr=0x3,ioeventfd=on \
  -vnc:1 -daemonize
```

In the above example, virtio port 0 in the guest VM will be associated with vEth0, which in turns corresponds to a physical port, which means received packets come from vEth0, and transmitted packets is sent to vEth0.

4. In the guest, bind the virtio device to the uio_pci_generic kernel module and start the forwarding application. When the virtio port in guest bursts rx, it is getting packets from the raw socket's receive queue. When the virtio port bursts tx, it is sending packet to the tx_q.

```
modprobe uio
echo 512 > /sys/devices/system/node/node0/hugepages/hugepages-2048kB/nr_hugepages
modprobe uio_pci_generic
python tools/dpdk_nic_bind.py -b uio_pci_generic 00:03.0
```

We use testpmd as the forwarding application in this example.

```
[root@localhost isg_cid-dpdk1#] $ testpmd -c 1 -n 4 --disable-gfx=1
4 --disable-gfx=1
Interactive mode selected
Configuring Port 0 (socket -1)
Warning: mb_desc(512) is not equal to vq size (256), fall to vq size
Test1
Test2
Test3
Warning: mb_desc(128) is not equal to vq size (256), fall to vq size
Checking link status...
Port 0 Link Up - speed 10000000000 Mbps - full-duplex
```

5. Use IXIA packet generator to inject a packet stream into the KNI physical port.

The packet reception and transmission flow path is:

IXIA packet generator->82599 PF->KNI rx queue->KNI raw socket queue->Guest VM virtio port 0 rx burst->Guest VM virtio port 0 tx burst-> KNI tx queue->82599 PF-> IXIA packet generator
5.5 Virtio with qemu virtio Back End

In this example, the packet reception flow path is:

IXIA packet generator->82599 PF->Linux Bridge->TAP0's socket queue-> Guest VM virtio port 0 rx burst-> Guest VM 82599 VF port1 tx burst-> IXIA packet generator

The packet transmission flow is:

IXIA packet generator-> Guest VM 82599 VF port1 rx burst-> Guest VM virtio port 0 tx burst-> tap -> Linux Bridge->82599 PF-> IXIA packet generator
CHAPTER SIX

POLL MODE DRIVER FOR PARAVIRTUAL VMXNET3 NIC

The VMXNET3 adapter is the next generation of a paravirtualized NIC, introduced by VMware* ESXi. It is designed for performance and is not related to VMXNET or VMXENET2. It offers all the features available in VMXNET2, and adds several new features such as, multi-queue support (also known as Receive Side Scaling, RSS), IPv6 offloads, and MSI/MSI-X interrupt delivery. Because operating system vendors do not provide built-in drivers for this card, VMware Tools must be installed to have a driver for the VMXNET3 network adapter available. One can use the same device in a DPDK application with VMXNET3 PMD introduced in DPDK API.

Currently, the driver provides basic support for using the device in a DPDK application running on a guest OS. Optimization is needed on the backend, that is, the VMware* ESXi vmkernel switch, to achieve optimal performance end-to-end.

In this chapter, two setups with the use of the VMXNET3 PMD are demonstrated:

1. Vmxnet3 with a native NIC connected to a vSwitch
2. Vmxnet3 chaining VMs connected to a vSwitch

6.1 VMXNET3 Implementation in the DPDK

For details on the VMXNET3 device, refer to the VMXNET3 driver's vmxnet3 directory and support manual from VMware*.

For performance details, refer to the following link from VMware:

As a PMD, the VMXNET3 driver provides the packet reception and transmission callbacks, vmxnet3_recv_pkts and vmxnet3_xmit_pkts. It does not support scattered packet reception as part of vmxnet3_recv_pkts and vmxnet3_xmit_pkts. Also, it does not support scattered packet reception as part of the device operations supported.

The VMXNET3 PMD handles all the packet buffer memory allocation and resides in guest address space and it is solely responsible to free that memory when not needed. The packet buffers and features to be supported are made available to hypervisor via VMXNET3 PCI configuration space BARs. During RX/TX, the packet buffers are exchanged by their GPAs, and the hypervisor loads the buffers with packets in the RX case and sends packets to vSwitch in the TX case.

The VMXNET3 PMD is compiled with vmxnet3 device headers. The interface is similar to that of the other PMDs available in the DPDK API. The driver pre-allocates the packet buffers and loads the command ring descriptors in advance. The hypervisor fills those packet buffers on
packet arrival and write completion ring descriptors, which are eventually pulled by the PMD. After reception, the DPDK application frees the descriptors and loads new packet buffers for the coming packets. The interrupts are disabled and there is no notification required. This keeps performance up on the RX side, even though the device provides a notification feature.

In the transmit routine, the DPDK application fills packet buffer pointers in the descriptors of the command ring and notifies the hypervisor. In response the hypervisor takes packets and passes them to the vSwitch. It writes into the completion descriptors ring. The rings are read by the PMD in the next transmit routine call and the buffers and descriptors are freed from memory.

### 6.2 Features and Limitations of VMXNET3 PMD

In release 1.6.0, the VMXNET3 PMD provides the basic functionality of packet reception and transmission. There are several options available for filtering packets at VMXNET3 device level including:

1. MAC Address based filtering:
   - Unicast, Broadcast, All Multicast modes - SUPPORTED BY DEFAULT
   - Multicast with Multicast Filter table - NOT SUPPORTED
   - Promiscuous mode - SUPPORTED
   - RSS based load balancing between queues - SUPPORTED

2. VLAN filtering:
   - VLAN tag based filtering without load balancing - SUPPORTED

**Note:**
- Release 1.6.0 does not support separate headers and body receive cmd_ring and hence, multiple segment buffers are not supported. Only cmd_ring_0 is used for packet buffers, one for each descriptor.
- Receive and transmit of scattered packets is not supported.
- Multicast with Multicast Filter table is not supported.

### 6.3 Prerequisites

The following prerequisites apply:

- Before starting a VM, a VMXNET3 interface to a VM through VMware vSphere Client must be assigned. This is shown in the figure below.

**Note:** Depending on the Virtual Machine type, the VMware vSphere Client shows Ethernet adaptors while adding an Ethernet device. Ensure that the VM type used offers a VMXNET3 device. Refer to the VMware documentation for a listed of VMs.

**Note:** Follow the *DPDK Getting Started Guide* to setup the basic DPDK environment.
Figure 6.1: Assigning a VMXNET3 interface to a VM using VMware vSphere Client

**Note:** Follow the *DPDK Sample Application’s User Guide*, L2 Forwarding/L3 Forwarding and TestPMD for instructions on how to run a DPDK application using an assigned VMXNET3 device.

### 6.4 VMXNET3 with a Native NIC Connected to a vSwitch

This section describes an example setup for Phy-vSwitch-VM-Phy communication.

**Note:** Other instructions on preparing to use DPDK such as, hugepage enabling, uio port binding are not listed here. Please refer to *DPDK Getting Started Guide and DPDK Sample Application’s User Guide* for detailed instructions.

The packet reception and transmission flow path is:

| Packet generator | 82576 | VMware ESXi vSwitch | VMXNET3 device | Guest VM VMXNET3 port 0 rx burst | Guest VM 82599 VF port 0 tx burst | 82599 VF | Packet generator |

### 6.5 VMXNET3 Chaining VMs Connected to a vSwitch

The following figure shows an example VM-to-VM communication over a Phy-VM-vSwitch-VM-Phy communication channel.

**Note:** When using the L2 Forwarding or L3 Forwarding applications, a destination MAC address needs to be written in packets to hit the other VM’s VMXNET3 interface.
Figure 6.2: VMXNET3 with a Native NIC Connected to a vSwitch
Figure 6.3: VMXNET3 Chaining VMs Connected to a vSwitch
In this example, the packet flow path is:

```
Packet generator -> 82599 VF
   -> Guest VM 82599 port 0 rx burst
   -> Guest VM VMXNET3 port 1 tx burst
   -> VMXNET3 device
   -> VMware ESXi vSwitch
   -> VMXNET3 device
   -> Guest VM VMXNET3 port 0 rx burst
   -> Guest VM 82599 VF port 1 tx burst
   -> 82599 VF
   -> Packet generator
```
LIBPCAP AND RING BASED POLL MODE DRIVERS

In addition to Poll Mode Drivers (PMDs) for physical and virtual hardware, the DPDK also includes two pure-software PMDs. These two drivers are:

- A libpcap-based PMD (librte_pmd_pcap) that reads and writes packets using libpcap, both from files on disk, as well as from physical NIC devices using standard Linux kernel drivers.
- A ring-based PMD (librte_pmd_ring) that allows a set of software FIFOs (that is, rte_ring) to be accessed using the PMD APIs, as though they were physical NICs.

Note: The libpcap-based PMD is disabled by default in the build configuration files, owing to an external dependency on the libpcap development files which must be installed on the board. Once the libpcap development files are installed, the library can be enabled by setting CONFIG_RTE_LIBRTE_PMD_PCAP=y and recompiling the Intel® DPDK.

7.1 Using the Drivers from the EAL Command Line

For ease of use, the DPDK EAL also has been extended to allow pseudo-Ethernet devices, using one or more of these drivers, to be created at application startup time during EAL initialization.

To do so, the –vdev= parameter must be passed to the EAL. This takes take options to allow ring and pcap-based Ethernet to be allocated and used transparently by the application. This can be used, for example, for testing on a virtual machine where there are no Ethernet ports.

7.1.1 Libpcap-based PMD

Pcap-based devices can be created using the virtual device –vdev option. The device name must start with the eth_pcap prefix followed by numbers or letters. The name is unique for each device. Each device can have multiple stream options and multiple devices can be used. Multiple device definitions can be arranged using multiple –vdev. Device name and stream options must be separated by commas as shown below:

```bash
$RTE_TARGET/app/testpmd -c f -n 4 --vdev='eth_pcap0,stream_opt0=..,stream_opt1=.' --vdev='eth
```
Device Streams

Multiple ways of stream definitions can be assessed and combined as long as the following two rules are respected:

- A device is provided with two different streams - reception and transmission.
- A device is provided with one network interface name used for reading and writing packets.

The different stream types are:

- **rx_pcap**: Defines a reception stream based on a pcap file. The driver reads each packet within the given pcap file as if it was receiving it from the wire. The value is a path to a valid pcap file.
  
  \[ \text{rx}_\text{pcap}=/\text{path/to/file.pcap} \]

- **tx_pcap**: Defines a transmission stream based on a pcap file. The driver writes each received packet to the given pcap file. The value is a path to a pcap file. The file is overwritten if it already exists and it is created if it does not.
  
  \[ \text{tx}_\text{pcap}=/\text{path/to/file.pcap} \]

- **rx_iface**: Defines a reception stream based on a network interface name. The driver reads packets coming from the given interface using the Linux kernel driver for that interface. The value is an interface name.
  
  \[ \text{rx}_\text{iface}=\text{eth0} \]

- **tx_iface**: Defines a transmission stream based on a network interface name. The driver sends packets to the given interface using the Linux kernel driver for that interface. The value is an interface name.
  
  \[ \text{tx}_\text{iface}=\text{eth0} \]

- **iface**: Defines a device mapping a network interface. The driver both reads and writes packets from and to the given interface. The value is an interface name.
  
  \[ \text{iface}=\text{eth0} \]

Examples of Usage

Read packets from one pcap file and write them to another:

\[ \text{RTE\_TARGET/app/testpmd} -\text{c '0xf'} -\text{n 4 --vdev 'eth_pcap0,rx_pcap=/path/to/file_rx.pcap,tx_pcap=/path/to/file_tx.pcap} \]

Read packets from a network interface and write them to a pcap file:

\[ \text{RTE\_TARGET/app/testpmd} -\text{c '0xf'} -\text{n 4 --vdev 'eth_pcap0,rx_iface=eth0,tx_pcap=/path/to/file_tx.pcap} \]

Read packets from a pcap file and write them to a network interface:

\[ \text{RTE\_TARGET/app/testpmd} -\text{c '0xf'} -\text{n 4 --vdev 'eth_pcap0,rx_pcap=/path/to/file_rx.pcap,tx_iface=eth1} \]

Forward packets through two network interfaces:

\[ \text{RTE\_TARGET/app/testpmd} -\text{c '0xf'} -\text{n 4 --vdev 'eth_pcap0,iface=eth0 --vdev='eth_pcap1;iface=eth1} \]
Using libpcap-based PMD with the testpmd Application

One of the first things that testpmd does before starting to forward packets is to flush the RX streams by reading the first 512 packets on every RX stream and discarding them. When using a libpcap-based PMD this behavior can be turned off using the following command line option:

```
--no-flush-rx
```

It is also available in the runtime command line:

```
set flush_rx on/off
```

It is useful for the case where the rx_pcap is being used and no packets are meant to be discarded. Otherwise, the first 512 packets from the input pcap file will be discarded by the RX flushing operation.

```
$RTE_TARGET/app/testpmd -c 0xf -n 4 --vdev 'eth_pcap0,rx_pcap=/path/to/file_rx.pcap,tx_pcap=/path/to/file_tx.pcap' -- --port-topology=chained --no-flush-rx
```

7.1.2 Rings-based PMD

To run a DPDK application on a machine without any Ethernet devices, a pair of ring-based rte_ethdevs can be used as below. The device names passed to the --vdev option must start with eth_ring and take no additional parameters. Multiple devices may be specified, separated by commas.

```
./testpmd -c E -n 4 --vdev=eth_ring0 --vdev=eth_ring1 --
EAL: Detected lcore 1 as core 1 on socket 0
...
Interactive-mode selected
Configuring Port 0 (socket 0)
Configuring Port 1 (socket 0)
Checking link statuses...
Port 0 Link Up - speed 10000 Mbps - full-duplex
Port 1 Link Up - speed 10000 Mbps - full-duplex
Done
testpmd> start tx_first
io packet forwarding - CRC stripping disabled - packets/burst=16
nb forwarding cores=1 - nb forwarding ports=2
RX queues=1 - RX desc=128 - RX free threshold=0
RX threshold registers: pthresh=0 hthresh=0 wthresh=4
TX queues=1 - TX desc=512 - TX free threshold=0
TX threshold registers: pthresh=36 hthresh=0 wthresh=0
TX RS bit threshold=0 - TXQ flags=0x0
testpmd> stop
Telling cores to stop...
Waiting for lcores to finish...
```

7.1. Using the Drivers from the EAL Command Line
7.1.3 Using the Poll Mode Driver from an Application

Both drivers can provide similar APIs to allow the user to create a PMD, that is, `rte_ethdev` structure, instances at run-time in the end-application, for example, using `rte_eth_from_rings()` or `rte_eth_from_pcaps()` APIs. For the rings-based PMD, this functionality could be used, for example, to allow data exchange between cores using rings to be done in exactly the same way as sending or receiving packets from an Ethernet device. For the libpcap-based PMD, it allows an application to open one or more pcap files and use these as a source of packet input to the application.

Usage Examples

To create two pseudo-Ethernet ports where all traffic sent to a port is looped back for reception on the same port (error handling omitted for clarity):

```c
struct rte_ring *r1, *r2;
int port1, port2;

r1 = rte_ring_create("R1", 256, SOCKET0,RING_F_SP_ENQ|RING_F_SC_DEQ);
r2 = rte_ring_create("R2", 256, SOCKET0, RING_F_SP_ENQ|RING_F_SC_DEQ);

/* create an ethdev where RX and TX are done to/from r1, and * another from r2 */
port1 = rte_eth_from_rings(r1, 1, r1, 1, SOCKET0);
port2 = rte_eth_from_rings(r2, 1, r2, 1, SOCKET0);
```

To create two pseudo-Ethernet ports where the traffic is switched between them, that is, traffic sent to port 1 is read back from port 2 and vice-versa, the final two lines could be changed as below:

```c
port1 = rte_eth_from_rings(r1, 1, r2, 1, SOCKET0);
port2 = rte_eth_from_rings(r2, 1, r1, 1, SOCKET0);
```

This type of configuration could be useful in a pipeline model, for example, where one may want to have inter-core communication using pseudo Ethernet devices rather than raw rings, for reasons of API consistency.

Enqueuing and dequeuing items from an `rte_ring` using the rings-based PMD may be slower than using the native rings API. This is because DPDK Ethernet drivers make use of function pointers to call the appropriate enqueue or dequeue functions, while the `rte_ring` specific functions are direct function calls in the code and are often inlined by the compiler.

Once an ethdev has been created, for either a ring or a pcap-based PMD, it should be configured and started in the same way as a regular Ethernet device, that is, by calling `rte_eth_dev_configure()` to set the number of receive and transmit queues, then calling `rte_eth_rx_queue_setup()` / `tx_queue_setup()` for each of those queues.
and finally calling rte_eth_dev_start() to allow transmission and reception of packets to begin.

Figures
Fig. 3.1 Virtualization for a Single Port NIC in SR-IOV Mode
Fig. 3.2 Performance Benchmark Setup
Fig. 3.3 Fast Host-based Packet Processing
Fig. 3.4 Inter-VM Communication
Fig. 5.1 Host2VM Communication Example Using kni vhost Back End
Fig. 5.3 Host2VM Communication Example Using qemu vhost Back End
Fig. 6.1 Assigning a VMXNET3 interface to a VM using VMware vSphere Client
Fig. 6.2 VMXNET3 with a Native NIC Connected to a vSwitch
Fig. 6.3 VMXNET3 Chaining VMs Connected to a vSwitch