Intel Accelerator Functional Unit Simulation Environment Quick Start User Guide

Updated for Intel® Acceleration Stack for Intel® Xeon® CPU with FPGAs: 2.0
1. Intel Accelerator Functional Unit (AFU) Simulation Environment (ASE) Quick Start User Guide

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1. Intel Accelerator Functional Unit (AFU) Simulation Environment (ASE) Quick Start User Guide

The Intel® Accelerator Functional Unit (AFU) Simulation Environment (ASE) is a hardware and software co-simulation environment for any Intel FPGA Programmable Acceleration Card (Intel FPGA PAC).

This software co-simulation environment currently supports the following Intel FPGA PACs:
- Intel Programmable Acceleration Card with Intel Arria® 10 GX FPGA
- Intel FPGA Programmable Acceleration Card D5005

The ASE provides a transactional model for the Core Cache Interface (CCI-P) protocol and a memory model for the FPGA-attached local memory.

The ASE also validates Accelerator Functional Unit (AFU) compliance to the following protocols and APIs:
- The CCI-P protocol specification
- The Avalon® Memory Mapped (Avalon-MM) Interface Specification
- The Open Programmable Acceleration Engine (OPAE)

This document describes how to simulate a sample AFU using the ASE environment. Refer to the Intel Accelerator Functional Unit (AFU) Simulation Environment (ASE) User Guide for comprehensive details on ASE capabilities and internal architecture.

Note: This document applies to the Intel Acceleration Stack for Intel Xeon® CPU with FPGAs version 2.0. For information about older versions, refer to the ASE Quick Start User Guide Archives on page 10.

<table>
<thead>
<tr>
<th>Table 1. Acceleration Stack for Intel Xeon CPU with FPGAs Glossary</th>
</tr>
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<tbody>
<tr>
<td>Term</td>
</tr>
<tr>
<td>Intel Acceleration Stack for Intel Xeon CPU with FPGAs</td>
</tr>
<tr>
<td>Acceleration Stack</td>
</tr>
<tr>
<td>A collection of software, firmware and tools that provides performance-optimized connectivity between an Intel FPGA and an Intel Xeon processor.</td>
</tr>
<tr>
<td>Intel FPGA Programmable Acceleration Card (Intel FPGA PAC)</td>
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<tr>
<td>Intel FPGA PAC</td>
</tr>
<tr>
<td>PCIe® FPGA accelerator card. Contains an FPGA Interface Manager (FIM) that pairs with an Intel Xeon processor over a PCIe bus.</td>
</tr>
<tr>
<td>Intel Xeon Scalable Platform with Integrated FPGA</td>
</tr>
<tr>
<td>Integrated FPGA Platform</td>
</tr>
<tr>
<td>Intel Xeon plus FPGA platform with the Intel Xeon and an FPGA in a single package and sharing a coherent cache of memory via Ultra Path Interconnect (UPI).</td>
</tr>
</tbody>
</table>

*Other names and brands may be claimed as the property of others.
1.1. System Requirements

Here are the system requirements for ASE version 2.0:

- A 64-bit Linux operating system. This release validated the following operating systems:
  - RHEL 7.6 with Linux kernel 3.10
- One of the following simulators:
  - 64-bit Synopsys* VCS-MX-2016.06-SP2-1 RTL Simulator
  - 64-bit Mentor Graphics* Modelsim SE Simulator (Version 10.5c)
  - 64-bit Mentor Graphics QuestaSim Simulator (Version 10.5c)
- C compiler: GCC 4.7.0 or above
- CMake: version 2.8.12 or above
- GNU C Library: version 2.17 or above
- Python: version 2.7
- Intel Quartus® Prime Pro Edition (18.1.2 version)\(^{(1)}\)

\(^{(1)}\) The required version is installed with the Acceleration Stack for Development version.
1.2. Setting Up the Environment

You must set up your simulation environment and install the OPAE software before running the ASE.

1. Set the following environment variables for your simulation software:
   - **For VCS:**
     
     ```
     $ export VCS_HOME=<path to VCS installation directory>
     $ export PATH=$VCS_HOME/bin:$PATH
     ```
     
     The VCS installation directory structure is as follows:
     ```
     admin bin etc gnu include linux mmc susx64 vcfla wqcommon
     amd64 doc flexml gui install.log linuxx64 packages susx64 verific wms
     ```
     
     Make sure your system has a valid VCS license.
   - **For Modelsim SE/QuestaSim:**
     
     ```
     $ export MTI_HOME=<path to Modelsim installation directory>
     $ export PATH=$MTI_HOME/linux_x86_64/:$MTI_HOME/bin/:$PATH
     ```
     
     The Modelsim/Questa installation directory structure is as follows:
     ```
     ave bin gcc32 gc4.c gc4-3.3-linx ise some.sre Linux LICENSE mpl2 path src
     ```
     
     Make sure your system has a valid Modelsim SE/QuestaSim license.
   - **For Intel Quartus Prime Pro Edition:**
     
     ```
     $ export QUARTUS_HOME=<path to Intel Quartus Prime Pro Edition installation directory>
     ```
     
     The Intel Quartus Prime installation directory structure is as follows:
     ```
     adm bin cusp common dsp_builder extlibs32 linuxx64 qdesigns sosc_builder
     ```
     
     2. Export:
     
     ```
     $ export LM_LICENSE_FILE=<Quartus Prime License>
     ```
     
     3. Extract the runtime archive file, and install OPAE libraries, binaries, include files, and ASE libraries as described in the *Installing the OPAE Software* chapter in the appropriate Intel FPGA PAC Quick Start User Guide.

Your environment must be set up correctly to configure and build an AFU. In particular, you must install the OPAE Software Development Kit (SDK) properly. OPAE SDK scripts must be on PATH and include files and libraries that must be available to the C compiler. In addition, you must ensure that the OPAE_PLATFORM_ROOT environment variable is set. Refer to *Installing the OPAE Software Package* for more information.

To ensure that the OPAE SDK and ASE are properly installed, in a shell, confirm that your PATH includes `afu_sim_setup`.

**Related Information**
- Intel Accelerator Functional Unit (AFU) Simulation Environment (ASE) User Guide
- Installing the OPAE Software Package
1.3. Simulating hello_afu in Client-Server Mode

The hello_afu example is a simple AFU template that demonstrates the primary CCI-P interface. The RTL satisfies the minimum requirements of an AFU, responding to memory-mapped I/O reads to return the device feature header and the AFU's UUID.

Figure 1. hello_afu Directory Tree

```
+ hello_afu
  + bin
    + hello_afu.gbs
  + hw
    + rtl
      + afu.sv
      + ccip_interface_reg.sv
      + ccip_std_afu.sv
      + filelist.txt
      + hello_afu.json
  + sw
    + hello_afu.c
    + Makefile
    + README
```

Note: This document uses `<AFU example>` to refer to an example design directory, such as hello_afu in the figure above.

The software demonstrates the minimum requirements to attach to an FPGA using the OPAE. The RTL demonstrates the minimum requirements to satisfy the OPAE driver and the hello_afu example software.

filelist.txt specifies the files for RTL simulation and synthesis.

To successfully configure and build the AFU samples, your environment must be set up correctly, as described in Setting Up the Environment.

Related Information

- Intel Accelerator Functional Unit (AFU) Simulation Environment (ASE) User Guide
- Setting Up the Environment on page 5
- Developing AFUs with the OPAE SDK
  In the Accelerator Functional Unit (AFU) Developer’s Guide
1.3.1. Simulation in Client-Server Mode

The following example flow introduces the basic ASE scripts. You can simulate all examples with the ASE, except `eth_e2e_e10`.

Simulation requires two software processes: one process for RTL simulation and a second process to run the connected software. To construct an RTL simulation environment, run the following in `$OPAE_PLATFORM_ROOT/hw/samples/hello_afu`:

```
$ afu_sim_setup --source hw/rtl/filelist.txt build_sim
```

This command constructs an ASE environment in the `build_sim` subdirectory.

To build and run the simulator:

```
$ cd build_sim
$ make
$ make sim
```

The simulator prints a message that it is ready for simulation. It also prints a message prompting you to set the `ASE_WORKDIR` environment variable.

Open another shell for software simulation. To build and run the software in the new shell:

```
$ cd $OPAE_PLATFORM_ROOT
$ export ASE_WORKDIR=$OPAE_PLATFORM_ROOT/hw/samples/hello_afu/build_sim/work
$ cd $OPAE_PLATFORM_ROOT/hw/samples/hello_afu/sw
$ make clean
$ make USE_ASE=1
$ ./hello_afu
```

**Note:**

The specific pathname for `ASE_WORKDIR` may vary. Use the pathname provided by the simulator prompt.

The software and simulator run, log transactions, and exit.

1.3.1.1. Simulation Log Files

The simulation work directory stores the waveform, CCI-P transactions, and simulation log files.

Complete the following steps to view the waveform database:

1. Change to the directory in which you executed the `make sim` command.
2. Type:

```
$ make wave
```

The `make wave` command, invokes the waveform viewer.
1.3.1.2. Design Declarations

The following files and directories define the AFU simulation:

- $OPAE_PLATFORM_ROOT/hw/samples/<AFU example>/hw/rtl/filelist.txt specifies RTL sources.
- <AFU example> is the example directory as shown in the hello_afu Directory Tree figure.
- filelist.txt lists SystemVerilog, VHDL, and the AFU JavaScript Object Notation (.json) file.
- The AFU .json describes the interfaces the AFU requires. It also includes a UUID to identify the AFU once downloaded to an FPGA.
- hw/rtl/hello_afu.json defines ccip_std_afu as the top-level interface by setting afu-top-interface to ccip_std_afu. ccip_std_afu is the base CCI-P interface including clocks, reset, and CCI-P TX and RX structures. More advanced examples define other interface options.
- The .json file declares the AFU UUID. An OPAE script generates the UUID. The RTL loads the UUID from afu_json_info.vh.
- sw/Makefile generates afu_json_info.h. Software loads the UUID from afu_json_info.h.

1.3.1.3. Troubleshooting Client-Server Simulation

If the afu_sim_setup command fails, confirm that:

- afu_sim_setup is on your PATH. afu_sim_setup should be in /usr/bin or in <opae install path> if you built OPAE from source files.
- You have Python version 2.7 or higher installed.

If you are unable to build and execute the simulator, it is likely that you did not install your RTL simulation tool properly.

When you try to build and run the software, if you see an "Error enumerating AFCs" message, you omitted setting USE_ASE=1 on the make command line. The software is searching for a physical FPGA device. To recover, repeat the steps from the make clean command.

1.4. AFU Examples

Table 2. AFU Examples

<table>
<thead>
<tr>
<th>AFU</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>hello_mem_afu</td>
<td>hello_mem_afu demonstrates an AFU that builds a simple state machine to access memory. The state machine is capable of several access patterns to local memory directly attached to FPGA pins, such as DDR4 DIMMs. This memory is distinct from the host memory accessed over CCI-P. The host manages the hello_mem_afu controller state machine using memory-mapped I/O (MMIO) requests to control and status registers (CSRs).</td>
</tr>
<tr>
<td>hello_intr_afu</td>
<td>hello_intr_afu demonstrates the application interrupt feature in the ASE.</td>
</tr>
</tbody>
</table>

continued...
### AFU Description

<table>
<thead>
<tr>
<th>AFU</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>dma_afu (2)</td>
<td>dma_afu demonstrates a DMA Basic Building Block for host to FPGA, FPGA to host, and FPGA to FPGA memory transfers. When simulating this AFU, the buffer size used for DMA transfer is small to keep the simulation time reasonable. For more information, refer to the DMA Accelerator Functional Unit (AFU) User Guide.</td>
</tr>
<tr>
<td>nlb_mode_0</td>
<td>nlb_mode_0 is a CCI-P system demonstrating the memory copy test. $OPAE_PLATFORM_ROOT/sw/opae-&lt;release_number&gt;/sample/hello_fpga.c includes nlb_mode_0.</td>
</tr>
<tr>
<td>streaming_dma</td>
<td>streaming_dma demonstrates how to transfer data between host memory and an FPGA streaming port. For more information, refer to the Streaming DMA Accelerator Functional Unit (AFU) User Guide.</td>
</tr>
<tr>
<td>hello_afu</td>
<td>hello_afu is a simple AFU that demonstrates the primary CCI-P interface. The RTL satisfies the bare minimum requirements of an AFU, responding to MMIO reads to return the device feature header and the AFU's UUID.</td>
</tr>
</tbody>
</table>

### Related Information

- DMA Accelerator Functional Unit (AFU) User Guide
  
  For information on how to compile and execute the dma_afu.

- Streaming DMA Accelerator Functional Unit (AFU) User Guide
  
  For information on how to compile and execute the streaming_dma_afu.

### 1.5. Troubleshooting

If the following error appears during simulation, correct it by following the steps below.

#### Error Message

```
# [SIM] An ASE instance is probably still running in current directory  
# [SIM] Check for PID 28816  
# [SIM] Simulation will exit... you may use a SIGKILL to kill the simulation process.  
# [SIM] Also check if .ase_ready.pid file is removed before proceeding.
```

#### Solution

1. Type `pkill ase_simv` to kill zombie simulation processes and remove any temporary files left behind by failed simulation processes or lock ups.

2. Delete the `.ase_ready.pid` file, found in the `$ASE_WORKDIR` directory.
1.6. ASE Quick Start User Guide Archives

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<thead>
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<th>Intel Acceleration Stack Version</th>
<th>User Guide</th>
</tr>
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<tbody>
<tr>
<td>1.2</td>
<td>Intel Accelerator Functional Unit (AFU) Simulation Environment (ASE) Quick Start User Guide</td>
</tr>
<tr>
<td>1.1</td>
<td>Intel Accelerator Functional Unit (AFU) Simulation Environment (ASE) Quick Start User Guide</td>
</tr>
<tr>
<td>1.0</td>
<td>Intel Accelerator Functional Unit (AFU) Simulation Environment (ASE) Quick Start User Guide</td>
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## 1.7. Document Revision History for ASE Quick Start User Guide

<table>
<thead>
<tr>
<th>Document Version</th>
<th>Intel Acceleration Stack Version</th>
<th>Changes</th>
</tr>
</thead>
</table>
| 2019.08.05       | 2.0                              | • Updated the Intel Quartus Prime Pro Edition version in System Requirements.  
|                  |                                  | • Added the `hello_afu` in AFU Examples.  
|                  |                                  | • Removed information about simulating in regression mode.  
|                  |                                  | • Added a new section: ASE Quick Start User Guide Archives.  |
| 2018.12.04       | 1.2                              | Added Ubuntu support.  |
| 2018.08.06       | 1.1                              | Updated the system requirements, directory structure and corresponding filenames.  |
| 2018.04.10       | 1.0                              | Initial release.  |