

This chapter describes the electric characteristics, switching characteristics, and I/O timing for Cyclone[®] III LS devices. A glossary is also included for your reference.

Electrical Characteristics

The following sections provide information about the absolute maximum ratings, recommended operating conditions, DC characteristics, and other specifications for Cyclone III LS devices.

Operating Conditions

When Cyclone III LS devices are implemented in a system, they are rated according to a set of defined parameters. To maintain the highest possible performance and reliability of Cyclone III LS devices, you must consider the operating requirements in this chapter. Cyclone III LS devices are offered in commercial and industrial grades. Commercial devices are offered in -7 (fastest) and -8 speed grades. Industrial devices are offered only in -7 speed grade.



In this chapter, a prefix associated with the operating temperature range is attached to the speed grades—commercial with a “C” prefix; industrial with an “I” prefix. For example, commercial devices are described as C7 and C8 per respective speed grades. Industrial devices are described as I7.

Absolute Maximum Ratings

Absolute maximum ratings define the maximum operating conditions for Cyclone III LS devices. The values are based on experiments conducted with the device and theoretical modeling of breakdown and damage mechanisms. The functional operation of the device is not implied at these conditions. Table 2-1 lists the absolute maximum ratings for Cyclone III LS devices.



Conditions beyond those listed in Table 2-1 may cause permanent damage to the device. Additionally, device operation at the absolute maximum ratings for extended periods of time may have adverse effects on the device. All parameters representing voltages are measured with respect to ground.

Table 2-1. Cyclone III LS Devices Absolute Maximum Ratings ⁽¹⁾ (Part 1 of 2)

| Symbol | Parameter | Min | Max | Unit |
|--------------------|-----------------------------------|------|-----|------|
| V _{CCINT} | Supply voltage for internal logic | -0.5 | 1.8 | V |
| V _{CCIO} | Supply voltage for output buffers | -0.5 | 3.9 | V |

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Table 2-1. Cyclone III LS Devices Absolute Maximum Ratings ⁽¹⁾ (Part 2 of 2)

| Symbol | Parameter | Min | Max | Unit |
|----------------------------|--|------|-------|------|
| V_{CCA} | Supply (analog) voltage for PLL regulator | -0.5 | 3.75 | V |
| V_{CCD_PLL} | Supply (digital) voltage for PLL | -0.5 | 1.8 | V |
| V_{CCBAT} ⁽²⁾ | Battery back-up power supply for design security volatile key register | -0.5 | 3.75 | V |
| V_I | DC input voltage | -0.5 | 3.95 | V |
| I_{OUT} | DC output current, per pin | -25 | 40 | mA |
| V_{ESDHBM} | Electrostatic discharge voltage using the human body model | — | ±2000 | V |
| V_{ESDCDM} | Electrostatic discharge voltage using the charged device model | — | ±500 | V |
| T_{STG} | Storage temperature | -65 | 150 | °C |
| T_J | Operating junction temperature | -40 | 125 | °C |

Notes to Table 2-1:

- (1) Supply voltage specifications apply to voltage readings taken at the device pins with respect to ground, not at the power supply.
- (2) V_{CCBAT} is tied to Power-on reset (POR). If the V_{CCBAT} is below 1.2 V, the device will not power up.

Maximum Allowed Overshoot or Undershoot Voltage

During transitions, input signals may overshoot to the voltage listed in [Table 2-2](#) and undershoot to -2.0 V for a magnitude of currents less than 100 mA and for periods shorter than 20 ns.

[Table 2-2](#) lists the maximum allowed input overshoot voltage and the duration of the overshoot voltage as a percentage over the lifetime of the device. The maximum allowed overshoot duration is specified as percentage of high-time over the lifetime of the device.


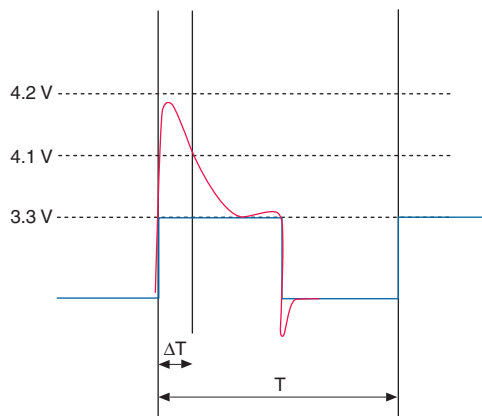
 A DC signal is equivalent to 100% of the duty cycle. For example, a signal that overshoots to 4.2 V can only be at 4.2 V for 10.74% over the lifetime of the device; for a device lifetime of 10 years, this is equivalent to 10.74% of ten years, which is 12.89 months.

Table 2–2. Cyclone III LS Devices Maximum Allowed Overshoot During Transitions over a 10-Year Time Frame

| Symbol | Parameter | Condition | Overshoot Duration as % of High Time | Unit |
|--------|------------------|-----------------------|--------------------------------------|------|
| V_i | AC Input Voltage | $V_i = 3.95\text{ V}$ | 100 | % |
| | | $V_i = 4.0\text{ V}$ | 95.67 | % |
| | | $V_i = 4.05\text{ V}$ | 55.24 | % |
| | | $V_i = 4.10\text{ V}$ | 31.97 | % |
| | | $V_i = 4.15\text{ V}$ | 18.52 | % |
| | | $V_i = 4.20\text{ V}$ | 10.74 | % |
| | | $V_i = 4.25\text{ V}$ | 6.23 | % |
| | | $V_i = 4.30\text{ V}$ | 3.62 | % |
| | | $V_i = 4.35\text{ V}$ | 2.1 | % |
| | | $V_i = 4.40\text{ V}$ | 1.22 | % |
| | | $V_i = 4.45\text{ V}$ | 0.71 | % |
| | | $V_i = 4.50\text{ V}$ | 0.41 | % |
| | | $V_i = 4.60\text{ V}$ | 0.14 | % |
| | | $V_i = 4.70\text{ V}$ | 0.047 | % |

Figure 2–1 shows the methodology to determine the overshoot duration. In this example, overshoot voltage is shown in red and is present on the input pin of the Cyclone III LS device at over 4.1 V but below 4.2 V. From Table 2–1, for an overshoot of 4.1 V, the percentage of high time for the overshoot can be as high as 31.97% over a 10-year period. Percentage of high time is calculated as $(\Delta T)/T \times 100$. This 10-year period assumes the device is always turned on with 100% I/O toggle rate and 50% duty cycle signal. For lower I/O toggle rates and situations in which the device is in an idle state, lifetimes are increased.

Figure 2–1. Cyclone III LS Devices Overshoot Duration



Recommended Operating Conditions

This section lists the functional operation limits for AC and DC parameters for Cyclone III LS devices.

The steady-state voltage and current values expected from Cyclone III LS devices are provided in Table 2-3. All supplies must be strictly monotonic without plateaus.

Table 2-3. Cyclone III LS Devices Recommended Operating Conditions (1), (2)

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|--|--------------------|------------|-----|------------|------|
| V_{CCINT} (3) | Supply voltage for internal logic | — | 1.15 | 1.2 | 1.25 | V |
| V_{CCIO} (3), (7) | Supply voltage for output buffers, 3.3-V operation | — | 3.135 | 3.3 | 3.465 | V |
| | Supply voltage for output buffers, 3.0-V operation | — | 2.85 | 3.0 | 3.15 | V |
| | Supply voltage for output buffers, 2.5-V operation | — | 2.375 | 2.5 | 2.625 | V |
| | Supply voltage for output buffers, 1.8-V operation | — | 1.71 | 1.8 | 1.89 | V |
| | Supply voltage for output buffers, 1.5-V operation | — | 1.425 | 1.5 | 1.575 | V |
| | Supply voltage for output buffers, 1.2-V operation | — | 1.14 | 1.2 | 1.26 | V |
| V_{CCA} (3) | Supply (analog) voltage for PLL regulator | — | 2.375 | 2.5 | 2.625 | V |
| V_{CCD_PLL} (3) | Supply (digital) voltage for PLL | — | 1.15 | 1.2 | 1.25 | V |
| V_{CCBAT} (4) | Battery back-up power supply for design security volatile key register | — | 1.2 | 3.0 | 3.3 | V |
| V_I | Input voltage | — | -0.5 | — | 3.6 | V |
| V_O | Output voltage | — | 0 | — | V_{CCIO} | V |
| T_J | Operating junction temperature | For commercial use | 0 | — | 85 | °C |
| | | For industrial use | -40 | — | 100 | °C |
| t_{RAMP} | Power supply ramptime | Standard POR (5) | 50 μ s | — | 50 ms | — |
| | | Fast POR (6) | 50 μ s | — | 3 ms | — |
| I_{Diode} | Magnitude of DC current across PCI-clamp diode when enabled | — | — | — | 10 | mA |

Notes to Table 2-3:

- (1) V_{CCIO} for all I/O banks must be powered up during device operation. All V_{CCA} pins must be powered to 2.5 V (even when you do not use phase locked-loops [PLLs]), and must be powered up and powered down at the same time.
- (2) V_{CCD_PLL} must always be connected to V_{CCINT} through a decoupling capacitor and ferrite bead.
- (3) V_{CC} must rise monotonically.
- (4) V_{CCBAT} is tied to POR. If the V_{CCBAT} is below 1.2 V, the device will not power up.
- (5) POR time for Standard POR ranges from 50 to 200 ms. Each individual power supply must reach the recommended operating range within 50 ms.
- (6) POR time for Fast POR ranges from 3 to 9 ms. Each individual power supply must reach the recommended operating range within 3 ms.
- (7) All input buffers are powered by the V_{CCIO} supply.

DC Characteristics

This section lists the I/O leakage current, pin capacitance, on-chip termination (OCT) tolerance, and bus hold specifications for Cyclone III LS devices.

Supply Current

Supply current is the current the device draws after the device is configured with no inputs or outputs toggling and no activity in the device. Use the Excel-based Early Power Estimator (EPE) to get the supply current estimates for your design because these currents vary largely with the resources you use. Table 2-4 lists the I/O pin leakage current for Cyclone III LS devices.


 For more information about power estimation tools, refer to the *PowerPlay Early Power Estimator User Guide* and the *PowerPlay Power Analysis* chapter in the *Quartus II Handbook*.

Table 2-4. Cyclone III LS Devices I/O Pin Leakage Current ^{(1), (2)}

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|----------|------------------------------------|-------------------------------|-----|-----|-----|---------|
| I_I | Input Pin Leakage Current | $V_I = V_{CCIO_{MAX}}$ to 0 V | -10 | — | 10 | μA |
| I_{OZ} | Tri-stated I/O Pin Leakage Current | $V_O = V_{CCIO_{MAX}}$ to 0 V | -10 | — | 10 | μA |

Notes to Table 2-4:

- (1) This value is specified for normal device operation. The value varies during device power-up. This applies for all V_{CCIO} settings (3.3, 3.0, 2.5, 1.8, 1.5, and 1.2 V).
- (2) The 10 μA I/O leakage current limit is applicable when the internal clamping diode is off. A higher current can be observed when the diode is on.

Bus Hold

Bus hold retains the last valid logic state after the source driving it either enters the high impedance state or is removed. Each I/O pin has an option to enable bus hold in user mode. Bus hold is always disabled in configuration mode.

Table 2-5 lists the bus hold specifications for Cyclone III LS devices. Also listed are the input pin capacitances and OCT tolerance specifications.

Table 2-5. Cyclone III LS Devices Bus Hold Parameters ⁽¹⁾

| Parameter | Condition | V_{CCIO} (V) | | | | | | | | | | | | Unit |
|-----------------------------------|-----------------------------|----------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|---------|
| | | 1.2 | | 1.5 | | 1.8 | | 2.5 | | 3.0 | | 3.3 | | |
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| Bus-hold low, sustaining current | $V_{IN} > V_{IL}$ (maximum) | 8 | — | 12 | — | 30 | — | 50 | — | 70 | — | 70 | — | μA |
| Bus-hold high, sustaining current | $V_{IN} < V_{IL}$ (minimum) | -8 | — | -12 | — | -30 | — | -50 | — | -70 | — | -70 | — | μA |
| Bus-hold low, overdrive current | $0 V < V_{IN} < V_{CCIO}$ | — | 125 | — | 175 | — | 200 | — | 300 | — | 500 | — | 500 | μA |

Table 2-5. Cyclone III LS Devices Bus Hold Parameters ⁽¹⁾

| Parameter | Condition | V_{CCIO} (V) | | | | | | | | | | | | Unit |
|----------------------------------|---------------------------|----------------|------|-------|-------|------|------|-----|------|-----|------|-----|------|---------|
| | | 1.2 | | 1.5 | | 1.8 | | 2.5 | | 3.0 | | 3.3 | | |
| | | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | Min | Max | |
| Bus-hold high, overdrive current | $0 V < V_{IN} < V_{CCIO}$ | — | -125 | — | -175 | — | -200 | — | -300 | — | -500 | — | -500 | μA |
| Bus-hold trip point | — | 0.3 | 0.9 | 0.375 | 1.125 | 0.68 | 1.07 | 0.7 | 1.7 | 0.8 | 2.0 | 0.8 | 2.0 | V |

Note to Table 2-5:

(1) Bus-hold trip points are based on calculated input voltages from the JEDEC standard.

OCT Specifications

Table 2-6 lists the variation of OCT without calibration across process, temperature, and voltage (PVT).

Table 2-6. Cyclone III LS Devices Series OCT without Calibration Specifications

| Description | V_{CCIO} (V) | Resistance Tolerance | | Unit |
|--------------------------------|----------------|----------------------|----------------|------|
| | | Commercial Max | Industrial Max | |
| Series OCT without calibration | 3.0 | ± 30 | ± 40 | % |
| | 2.5 | ± 30 | ± 40 | % |
| | 1.8 | ± 40 | ± 50 | % |
| | 1.5 | ± 50 | ± 50 | % |
| | 1.2 | ± 50 | ± 50 | % |

OCT calibration is automatically performed at device power-up for OCT enabled I/Os.

Table 2-7 lists the OCT calibration accuracy at device power-up.

Table 2-7. Cyclone III LS Devices Series OCT with Calibration at Device Power-Up Specifications

| Description | V_{CCIO} (V) | Calibration Accuracy | | Unit |
|--|----------------|----------------------|----------------|------|
| | | Commercial Max | Industrial Max | |
| Series Termination with power-up calibration | 3.0 | ± 10 | ± 10 | % |
| | 2.5 | ± 10 | ± 10 | % |
| | 1.8 | ± 10 | ± 10 | % |
| | 1.5 | ± 10 | ± 10 | % |
| | 1.2 | ± 10 | ± 10 | % |

OCT resistance may vary with the variation of temperature and voltage after power-up calibration. Use Table 2-8 and Equation 2-1 to determine the final OCT resistance considering the variations after power-up calibration.

Table 2-8 lists the percentage change of the OCT resistance with voltage and temperature.

Table 2-8. Cyclone III LS Devices OCT Variation After Calibration at Device Power-Up ⁽¹⁾

| Nominal Voltage | dR/dT (%/°C) | dR/dV (%/mV) |
|-----------------|--------------|--------------|
| 3.0 | 0.262 | -0.026 |
| 2.5 | 0.234 | -0.039 |
| 1.8 | 0.219 | -0.086 |
| 1.5 | 0.199 | -0.136 |
| 1.2 | 0.161 | -0.288 |

Note to Table 2-8:

(1) Use this table to calculate the final OCT resistance with the variation of temperature and voltage.

Equation 2-1. ^{(1), (2), (3), (4), (5), (6)}

$$\Delta R_V = (V_2 - V_1) \times 1000 \times dR/dV \text{ ——— (7)}$$

$$\Delta R_T = (T_2 - T_1) \times dR/dT \text{ ——— (8)}$$

$$\text{For } \Delta R_x < 0; MF_x = 1 / (|\Delta R_x|/100 + 1) \text{ ——— (9)}$$

$$\text{For } \Delta R_x > 0; MF_x = \Delta R_x/100 + 1 \text{ ——— (10)}$$

$$MF = MF_V \times MF_T \text{ ——— (11)}$$

$$R_{\text{final}} = R_{\text{initial}} \times MF \text{ ——— (12)}$$

Notes to Equation 2-1:

- (1) T_2 is the final temperature.
- (2) T_1 is the initial temperature.
- (3) MF is multiplication factor.
- (4) R_{final} is final resistance.
- (5) R_{initial} is initial resistance.
- (6) Subscript x refers to both V and T .
- (7) ΔR_V is variation of resistance with voltage.
- (8) ΔR_T is variation of resistance with temperature.
- (9) dR/dT is the percentage change of resistance with temperature.
- (10) dR/dV is the percentage change of resistance with voltage.
- (11) V_2 is final voltage.
- (12) V_1 is the initial voltage.

Example 2-1 shows you how to calculate the change of 50 Ω I/O impedance from 25°C at 3.0 V to 85°C at 3.15 V.

Example 2-1.

$$\Delta R_V = (3.15 - 3) \times 1000 \times -0.026 = -3.83$$

$$\Delta R_T = (85 - 25) \times 0.262 = 15.72$$

Because ΔR_V is negative,

$$MF_V = 1 / (3.83/100 + 1) = 0.963$$

Because ΔR_T is positive,

$$MF_T = 15.72/100 + 1 = 1.157$$

$$MF = 0.963 \times 1.157 = 1.114$$

$$R_{\text{final}} = 50 \times 1.114 = 55.71 \Omega$$

Pin Capacitance

Table 2-9 lists the pin capacitance for Cyclone III LS devices.

Table 2-9. Cyclone III LS Devices Pin Capacitance

| Symbol | Parameter | Typical – QFP | Typical – FBGA | Unit |
|---------------------|---|---------------|----------------|------|
| C_{IOTB} | Input capacitance on top/bottom I/O pins | 7 | 6 | pF |
| C_{IOLR} | Input capacitance on left/right I/O pins | 7 | 5 | pF |
| $C_{LVDSLRL}$ | Input capacitance on left/right I/O pins with true LVDS output | 8 | 7 | pF |
| C_{VREFLR} (1) | Input capacitance on left/right dual-purpose V_{REF} pin when used as V_{REF} or user I/O pin | 21 | 21 | pF |
| C_{VREFTB} (1) | Input capacitance on top/bottom dual-purpose V_{REF} pin when used as V_{REF} or user I/O pin | 23 | 23 | pF |
| C_{CLKTB} | Input capacitance on top/bottom dedicated clock input pins | 7 | 6 | pF |
| C_{CLKLR} | Input capacitance on left/right dedicated clock input pins | 6 | 5 | pF |

Note to Table 2-9:

- (1) When you use the V_{REF} pin as a regular input or output, you can expect a reduced performance of toggle rate and t_{CO} due to higher pin capacitance.

Internal Weak Pull-Up and Weak Pull-Down Resistor

Table 2-10 lists the weak pull-up and pull-down resistor values for Cyclone III LS devices.

Table 2-10. Cyclone III LS Devices Internal Weak Pull-Up Weak and Pull-Down Resistor ⁽¹⁾

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|-----------------|--|--|-----|-----|-----|------|
| R _{PU} | Value of I/O pin pull-up resistor before and during configuration, as well as user mode if the programmable pull-up resistor option is enabled | V _{CCIO} = 3.3 V ± 5% ^{(2), (3)} | 7 | 25 | 41 | kΩ |
| | | V _{CCIO} = 3.0 V ± 5% ^{(2), (3)} | 7 | 28 | 47 | kΩ |
| | | V _{CCIO} = 2.5 V ± 5% ^{(2), (3)} | 8 | 35 | 61 | kΩ |
| | | V _{CCIO} = 1.8 V ± 5% ^{(2), (3)} | 10 | 57 | 108 | kΩ |
| | | V _{CCIO} = 1.5 V ± 5% ^{(2), (3)} | 13 | 82 | 163 | kΩ |
| | | V _{CCIO} = 1.2 V ± 5% ^{(2), (3)} | 19 | 143 | 351 | kΩ |
| R _{PD} | Value of I/O pin pull-down resistor before and during configuration | V _{CCIO} = 3.3 V ± 5% ⁽⁴⁾ | 6 | 19 | 30 | kΩ |
| | | V _{CCIO} = 3.0 V ± 5% ⁽⁴⁾ | 6 | 22 | 36 | kΩ |
| | | V _{CCIO} = 2.5 V ± 5% ⁽⁴⁾ | 6 | 25 | 43 | kΩ |
| | | V _{CCIO} = 1.8 V ± 5% ⁽⁴⁾ | 7 | 35 | 71 | kΩ |
| | | V _{CCIO} = 1.5 V ± 5% ⁽⁴⁾ | 8 | 50 | 112 | kΩ |

Notes to Table 2-10:

- All I/O pins have an option to enable weak pull-up except the configuration, test, and JTAG pins. The weak pull-down feature is only available for JTAG TCK.
- Pin pull-up resistance values may be lower if an external source drives the pin higher than V_{CCIO}.
- $R_{PU} = (V_{CCIO} - V_I) / I_{R_{PU}}$
Minimum condition: -40°C; V_{CCIO} = V_{CC} + 5%, V_I = V_{CC} + 5% - 50 mV;
Typical condition: 25°C; V_{CCIO} = V_{CC}, V_I = 0 V;
Maximum condition: 125°C; V_{CCIO} = V_{CC} - 5%, V_I = 0 V; in which V_I refers to the input voltage at the I/O pin.
- $R_{PD} = V_I / I_{R_{PD}}$
Minimum condition: -40°C; V_{CCIO} = V_{CC} + 5%, V_I = 50 mV;
Typical condition: 25°C; V_{CCIO} = V_{CC}, V_I = V_{CC} - 5%;
Maximum condition: 125°C; V_{CCIO} = V_{CC} - 5%, V_I = V_{CC} - 5%; in which V_I refers to the input voltage at the I/O pin.

Hot Socketing

Table 2-11 lists the hot-socketing specifications for Cyclone III LS devices.

Table 2-11. Cyclone III Devices LS Hot-Socketing Specifications

| Symbol | Parameter | Maximum |
|------------------------|------------------------|---------------------|
| I _{IOPIN(DC)} | DC current per I/O pin | 300 μA |
| I _{IOPIN(AC)} | AC current per I/O pin | 8 mA ⁽¹⁾ |

Note to Table 2-11:

- The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, |I_{IOPIN}| = C dv/dt, in which C is I/O pin capacitance and dv/dt is the slew rate.

Schmitt Trigger Input

Cyclone III LS devices support Schmitt trigger input on TDI, TMS, TCK, nSTATUS, nCONFIG, nCE, CONF_DONE, and DCLK pins. A Schmitt trigger feature introduces hysteresis to the input signal for improved noise immunity, especially for signals with a slow edge rate. Table 2-12 lists the hysteresis specifications across supported V_{CCIO} range for Schmitt trigger inputs in Cyclone III LS devices.

Table 2-12. Hysteresis Specifications for Schmitt Trigger Input in Cyclone III LS Devices

| Symbol | Parameter | Conditions | Minimum | Typical | Maximum | Unit |
|---------------|--------------------------------------|---------------------------|---------|---------|---------|------|
| $V_{SCHMITT}$ | Hysteresis for Schmitt trigger input | $V_{CCIO} = 3.3\text{ V}$ | 200 | — | — | mV |
| | | $V_{CCIO} = 2.5\text{ V}$ | 200 | — | — | mV |
| | | $V_{CCIO} = 1.8\text{ V}$ | 140 | — | — | mV |
| | | $V_{CCIO} = 1.5\text{ V}$ | 110 | — | — | mV |

I/O Standard Specifications

The following tables list input voltage sensitivities (V_{IH} and V_{IL}), output voltage (V_{OH} and V_{OL}), and current drive characteristics (I_{OH} and I_{OL}) for various I/O standards supported by Cyclone III LS devices.

Table 2-13 through Table 2-18 provide Cyclone III LS devices I/O standard specifications.

Table 2-13. Cyclone III LS Devices Single-Ended I/O Standard Specifications ⁽¹⁾

| I/O Standard | V_{CCIO} (V) | | | V_{IL} (V) | | V_{IH} (V) | | V_{OL} (V) | V_{OH} (V) | I_{OL} (mA) | I_{OH} (mA) |
|--|----------------|-----|-------|--------------|-------------------|-------------------|------------------|-------------------|-------------------|---------------|---------------|
| | Min | Typ | Max | Min | Max | Min | Max | Max | Min | | |
| 3.3-V LVTTTL ⁽²⁾ | 3.135 | 3.3 | 3.465 | — | 0.8 | 1.7 | 3.6 | 0.45 | 2.4 | 4 | -4 |
| 3.3-V LVCMOS ⁽²⁾ | 3.135 | 3.3 | 3.465 | — | 0.8 | 1.7 | 3.6 | 0.2 | $V_{CCIO} - 0.2$ | 2 | -2 |
| 3.0-V LVTTTL ⁽²⁾ | 2.85 | 3.0 | 3.15 | -0.3 | 0.8 | 1.7 | $V_{CCIO} + 0.3$ | 0.45 | 2.4 | 4 | -4 |
| 3.0-V LVCMOS ⁽²⁾ | 2.85 | 3.0 | 3.15 | -0.3 | 0.8 | 1.7 | $V_{CCIO} + 0.3$ | 0.2 | $V_{CCIO} - 0.2$ | 0.1 | -0.1 |
| 2.5-V LVTTTL and LVCMOS ⁽²⁾ | 2.375 | 2.5 | 2.625 | -0.3 | 0.7 | 1.7 | 3.6 | 0.4 | 2.0 | 1 | -1 |
| 1.8-V LVTTTL and LVCMOS | 1.71 | 1.8 | 1.89 | -0.3 | $0.35 * V_{CCIO}$ | $0.65 * V_{CCIO}$ | 2.25 | 0.45 | $V_{CCIO} - 0.45$ | 2 | -2 |
| 1.5-V LVCMOS | 1.425 | 1.5 | 1.575 | -0.3 | $0.35 * V_{CCIO}$ | $0.65 * V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.25 * V_{CCIO}$ | $0.75 * V_{CCIO}$ | 2 | -2 |
| 1.2-V LVCMOS | 1.14 | 1.2 | 1.26 | -0.3 | $0.35 * V_{CCIO}$ | $0.65 * V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.25 * V_{CCIO}$ | $0.75 * V_{CCIO}$ | 2 | -2 |
| PCI | 2.85 | 3.0 | 3.15 | — | $0.30 * V_{CCIO}$ | $0.50 * V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.1 * V_{CCIO}$ | $0.9 * V_{CCIO}$ | 1.5 | -0.5 |
| PCI-X | 2.85 | 3.0 | 3.15 | — | $0.35 * V_{CCIO}$ | $0.50 * V_{CCIO}$ | $V_{CCIO} + 0.3$ | $0.1 * V_{CCIO}$ | $0.9 * V_{CCIO}$ | 1.5 | -0.5 |

Notes to Table 2-13:

- (1) AC load $CL = 10\text{ pF}$.
- (2) For more information about interfacing Cyclone III LS devices with 3.3-, 3.0-, and 2.5-V LVTTTL/LVCMOS I/O standards, refer to *AN 447: Interfacing Cyclone III and Cyclone IV Devices with 3.3/3.0/2.5-V LVTTTL and LVCMOS I/O Systems*.

Table 2-14. Cyclone III LS Devices Single-Ended SSTL and HSTL I/O Reference Voltage Specifications⁽⁴⁾

| I/O Standard | V _{CCIO} (V) | | | V _{REF} (V) | | | V _{TT} (V) ⁽³⁾ | | |
|---------------------|-----------------------|-----|-------|---|--|---|------------------------------------|-------------------------|-------------------------|
| | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max |
| SSTL-2 Class I, II | 2.375 | 2.5 | 2.625 | 1.19 | 1.25 | 1.31 | V _{REF} - 0.04 | V _{REF} | V _{REF} + 0.04 |
| SSTL-18 Class I, II | 1.7 | 1.8 | 1.9 | 0.833 | 0.9 | 0.969 | V _{REF} - 0.04 | V _{REF} | V _{REF} + 0.04 |
| HSTL-18 Class I, II | 1.71 | 1.8 | 1.89 | 0.85 | 0.9 | 0.95 | 0.85 | 0.9 | 0.95 |
| HSTL-15 Class I, II | 1.425 | 1.5 | 1.575 | 0.71 | 0.75 | 0.79 | 0.71 | 0.75 | 0.79 |
| HSTL-12 Class I, II | 1.14 | 1.2 | 1.26 | 0.48 * V _{CCIO} ⁽¹⁾ | 0.5 * V _{CCIO} ⁽¹⁾ | 0.52 * V _{CCIO} ⁽¹⁾ | — | 0.5 * V _{CCIO} | — |
| | | | | 0.47 * V _{CCIO} ⁽²⁾ | 0.5 * V _{CCIO} ⁽²⁾ | 0.53 * V _{CCIO} ⁽²⁾ | | | |

Notes to Table 2-14:

- (1) The value shown refers to the DC input reference voltage, V_{REF(DC)}.
- (2) The value shown refers to the AC input reference voltage, V_{REF(AC)}.
- (3) V_{TT} of the transmitting device must track V_{REF} of the receiving device.
- (4) For an explanation of the terms used in Table 2-14, refer to "Glossary" on page 2-26.

Table 2-15. Cyclone III LS Devices Single-Ended SSTL and HSTL I/O Standards Signal Specifications

| I/O Standard | V _{IL(DC)} (V) | | V _{IH(DC)} (V) | | V _{IL(AC)} (V) | | V _{IH(AC)} (V) | | V _{OL} (V) | V _{OH} (V) | I _{OL} (mA) | I _{OH} (mA) |
|------------------|-------------------------|--------------------------|--------------------------|--------------------------|-------------------------|-------------------------|-------------------------|--------------------------|--------------------------|--------------------------|----------------------|----------------------|
| | Min | Max | Min | Max | Min | Max | Min | Max | Max | Min | | |
| SSTL-2 Class I | — | V _{REF} - 0.18 | V _{REF} + 0.18 | — | — | V _{REF} - 0.35 | V _{REF} + 0.35 | — | V _{TT} - 0.57 | V _{TT} + 0.57 | 8.1 | -8.1 |
| SSTL-2 Class II | — | V _{REF} - 0.18 | V _{REF} + 0.18 | — | — | V _{REF} - 0.35 | V _{REF} + 0.35 | — | V _{TT} - 0.76 | V _{TT} + 0.76 | 16.4 | -16.4 |
| SSTL-18 Class I | — | V _{REF} - 0.125 | V _{REF} + 0.125 | — | — | V _{REF} - 0.25 | V _{REF} + 0.25 | — | V _{TT} - 0.475 | V _{TT} + 0.475 | 6.7 | -6.7 |
| SSTL-18 Class II | — | V _{REF} - 0.125 | V _{REF} + 0.125 | — | — | V _{REF} - 0.25 | V _{REF} + 0.25 | — | 0.28 | V _{CCIO} - 0.28 | 13.4 | -13.4 |
| HSTL-18 Class I | — | V _{REF} - 0.1 | V _{REF} + 0.1 | — | — | V _{REF} - 0.2 | V _{REF} + 0.2 | — | 0.4 | V _{CCIO} - 0.4 | 8 | -8 |
| HSTL-18 Class II | — | V _{REF} - 0.1 | V _{REF} + 0.1 | — | — | V _{REF} - 0.2 | V _{REF} + 0.2 | — | 0.4 | V _{CCIO} - 0.4 | 16 | -16 |
| HSTL-15 Class I | — | V _{REF} - 0.1 | V _{REF} + 0.1 | — | — | V _{REF} - 0.2 | V _{REF} + 0.2 | — | 0.4 | V _{CCIO} - 0.4 | 8 | -8 |
| HSTL-15 Class II | — | V _{REF} - 0.1 | V _{REF} + 0.1 | — | — | V _{REF} - 0.2 | V _{REF} + 0.2 | — | 0.4 | V _{CCIO} - 0.4 | 16 | -16 |
| HSTL-12 Class I | -0.15 | V _{REF} - 0.08 | V _{REF} + 0.08 | V _{CCIO} + 0.15 | -0.24 | V _{REF} - 0.15 | V _{REF} + 0.15 | V _{CCIO} + 0.24 | 0.25 × V _{CCIO} | 0.75 × V _{CCIO} | 8 | -8 |
| HSTL-12 Class II | -0.15 | V _{REF} - 0.08 | V _{REF} + 0.08 | V _{CCIO} + 0.15 | -0.24 | V _{REF} - 0.15 | V _{REF} + 0.15 | V _{CCIO} + 0.24 | 0.25 × V _{CCIO} | 0.75 × V _{CCIO} | 14 | -14 |


 For more information about receiver input and transmitter output waveforms, and for other differential I/O standards, refer to the *High-Speed Differential Interfaces in Cyclone III Devices* chapter.

Table 2-16. Cyclone III LS Devices Differential SSTL I/O Standard Specifications ⁽¹⁾

| I/O Standard | V _{CCIO} (V) | | | V _{Swing(DC)} (V) | | V _{X(AC)} (V) | | | V _{Swing(AC)} (V) | | V _{Ox(AC)} (V) | | |
|------------------------|-----------------------|-----|-------|----------------------------|-------------------|------------------------------|-----|------------------------------|----------------------------|-------------------|------------------------------|-----|------------------------------|
| | Min | Typ | Max | Min | Max | Min | Typ | Max | Min | Max | Min | Typ | Max |
| SSTL-2 Class I, II | 2.375 | 2.5 | 2.625 | 0.36 | V _{CCIO} | V _{CCIO} /2 - 0.2 | — | V _{CCIO} /2 + 0.2 | 0.7 | V _{CCIO} | V _{CCIO} /2 - 0.125 | — | V _{CCIO} /2 + 0.125 |
| SSTL-18 Class I, II | 1.7 | 1.8 | 1.90 | 0.25 | V _{CCIO} | V _{CCIO} /2 - 0.175 | — | V _{CCIO} /2 + 0.175 | 0.5 | V _{CCIO} | V _{CCIO} /2 - 0.125 | — | V _{CCIO} /2 + 0.125 |

Note to Table 2-16:

(1) Differential SSTL requires a V_{REF} input.

Table 2-17. Cyclone III LS Devices Differential HSTL I/O Standard Specifications ⁽¹⁾

| I/O Standard | V _{CCIO} (V) | | | V _{DIF(DC)} (V) | | V _{X(AC)} (V) | | | V _{CM(DC)} (V) | | | V _{DIF(AC)} (V) | |
|------------------------|-----------------------|-----|-------|--------------------------|-------------------|-----------------------------|-----|-----------------------------|-----------------------------|-----|-----------------------------|--------------------------|-----------------------------|
| | Min | Typ | Max | Min | Max | Min | Typ | Max | Min | Typ | Max | Min | Max |
| HSTL-18 Class I, II | 1.71 | 1.8 | 1.89 | 0.2 | — | 0.85 | — | 0.95 | 0.85 | — | 0.95 | 0.4 | — |
| HSTL-15 Class I, II | 1.425 | 1.5 | 1.575 | 0.2 | — | 0.71 | — | 0.79 | 0.71 | — | 0.79 | 0.4 | — |
| HSTL-12 Class I, II | 1.14 | 1.2 | 1.26 | 0.16 | V _{CCIO} | 0.48 * V _{CCIO} | — | 0.52 * V _{CCIO} | 0.48 * V _{CCIO} | — | 0.52 * V _{CCIO} | 0.3 | 0.48 * V _{CCIO} |

Note to Table 2-17:

(1) Differential HSTL requires a V_{REF} input.

Table 2-18. Differential I/O Standard Specifications ⁽¹⁾ (Part 1 of 2)

| I/O Standard | V _{CCIO} (V) | | | V _{ID} (mV) | | V _{ICM} (V) | | | V _{OD} (mV) ⁽²⁾ | | | V _{OS} (V) ⁽²⁾ | | |
|--|-----------------------|-----|-------|----------------------|-----|----------------------|--|------|-------------------------------------|-----|-----|------------------------------------|------|-------|
| | Min | Typ | Max | Min | Max | Min | Condition | Max | Min | Typ | Max | Min | Typ | Max |
| LVPECL (Row I/Os) ⁽³⁾ | 2.375 | 2.5 | 2.625 | 100 | — | 0 | D _{MAX} ≤ 500 Mbps | 1.85 | — | — | — | — | — | — |
| | | | | | | 0.5 | 500 Mbps ≤ D _{MAX} ≤ 700 Mbps | 1.85 | | | | | | |
| | | | | | | 1 | D _{MAX} > 700 Mbps | 1.6 | | | | | | |
| LVPECL (Column I/Os) ⁽³⁾ | 2.375 | 2.5 | 2.625 | 100 | — | 0 | D _{MAX} ≤ 500 Mbps | 1.85 | — | — | — | — | — | — |
| | | | | | | 0.5 | 500 Mbps ≤ D _{MAX} ≤ 700 Mbps | 1.85 | | | | | | |
| | | | | | | 1 | D _{MAX} > 700 Mbps | 1.6 | | | | | | |
| LVDS (Row I/Os) | 2.375 | 2.5 | 2.625 | 100 | — | 0 | D _{MAX} ≤ 500 Mbps | 1.85 | 247 | — | 600 | 1.125 | 1.25 | 1.375 |
| | | | | | | 0.5 | 500 Mbps ≤ D _{MAX} ≤ 700 Mbps | 1.85 | | | | | | |
| | | | | | | 1 | D _{MAX} > 700 Mbps | 1.6 | | | | | | |

Table 2–18. Differential I/O Standard Specifications ⁽¹⁾ (Part 2 of 2)

| I/O Standard | V _{CCIO} (V) | | | V _{ID} (mV) | | V _{ICM} (V) | | | V _{OD} (mV) ⁽²⁾ | | | V _{OS} (V) ⁽²⁾ | | |
|---|-----------------------|-----|-------|----------------------|-----|----------------------|---|------|-------------------------------------|-----|-----|------------------------------------|------|------|
| | Min | Typ | Max | Min | Max | Min | Condition | Max | Min | Typ | Max | Min | Typ | Max |
| LVDS (Column I/Os) | 2.375 | 2.5 | 2.625 | 100 | — | 0 | $D_{MAX} \leq 500$ Mbps | 1.85 | 247 | — | 600 | 1.125 | 1.25 | 1.35 |
| | | | | | | 0.5 | $500 \text{ Mbps} \leq D_{MAX} \leq 700$ Mbps | 1.85 | | | | | | |
| | | | | | | 1 | $D_{MAX} > 700$ Mbps | 1.6 | | | | | | |
| BLVDS (Row I/Os) ⁽⁴⁾ | 2.375 | 2.5 | 2.625 | 100 | — | — | — | — | — | — | — | — | — | — |
| BLVDS (Column I/Os) ⁽⁴⁾ | 2.375 | 2.5 | 2.625 | 100 | — | — | — | — | — | — | — | — | — | — |
| mini-LVDS (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 300 | — | 600 | 1.0 | 1.2 | 1.4 |
| mini-LVDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 300 | — | 600 | 1.0 | 1.2 | 1.4 |
| RSDS (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.5 |
| RSDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.5 |
| PPDS (Row I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.4 |
| PPDS (Column I/Os) ⁽⁵⁾ | 2.375 | 2.5 | 2.625 | — | — | — | — | — | 100 | 200 | 600 | 0.5 | 1.2 | 1.4 |

Notes to Table 2–18:


- (1) For an explanation of the terms used in Table 2–18, refer to “Transmitter Output Waveform” in “Glossary” on page 2–26.
- (2) R_L range: 90 ≤ R_L ≤ 110 Ω.
- (3) The LVPECL input standard is only supported at clock input. The output standard is not supported.
- (4) There is no fixed V_{ICM}, V_{OD}, and V_{OS} specification for BLVDS. They are dependent on the system topology.
- (5) Mini-LVDS, RSDS, and PPDS standards are only supported at output pins of Cyclone III LS devices.

Power Consumption

Use the following methods to estimate power for your design:

- The Excel-based EPE
- The Quartus II® PowerPlay power analyzer feature

Use the interactive Excel-based EPE before designing your device to get a magnitude estimate of the device power. The Quartus II PowerPlay power analyzer provides better quality estimates based on the specifics of the design after place-and-route is complete. The PowerPlay power analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities which, combined with detailed circuit models, can yield very accurate power estimates.

 For more information about power estimation tools, refer to the *Early Power Estimator User Guide* and the *PowerPlay Power Analysis* chapter in volume 3 of the *Quartus II Handbook*.

Switching Characteristics

This section describes performance characteristics of the core and periphery blocks for Cyclone III LS devices.

Core Performance Specifications

Table 2-19 through Table 2-25 describe the core performance specifications for Cyclone III LS devices.

Clock Tree Specifications

Table 2-19 lists the clock tree specifications for Cyclone III LS devices.

Table 2-19. Cyclone III LS Devices Clock Tree Performance

| Device | Performance | | | Unit |
|-----------|-------------|-----|-------|------|
| | C7 | C8 | I7 | |
| EP3CLS70 | 437.5 | 402 | 437.5 | MHz |
| EP3CLS100 | 437.5 | 402 | 437.5 | MHz |
| EP3CLS150 | 437.5 | 402 | 437.5 | MHz |
| EP3CLS200 | 437.5 | 402 | 437.5 | MHz |

PLL Specifications

Table 2-20 lists the PLL specifications for Cyclone III LS devices when operating in the commercial junction temperature range (0°C to 85°C) and the industrial junction temperature range (-40°C to 100°C). For more information about the PLL block, refer to “PLL Block” in “Glossary” on page 2-26.

Table 2-20. Cyclone III LS Devices PLL Specifications ⁽⁴⁾ (Part 1 of 2)

| Symbol | Parameter | Min | Typ | Max | Unit |
|------------------------------------|--|-----|-----|------|------|
| f_{IN} ⁽¹⁾ | Input clock frequency | 5 | — | 450 | MHz |
| f_{INPFD} | PFD input frequency | 5 | — | 325 | MHz |
| f_{VCO} ⁽⁶⁾ | PLL internal VCO operating range | 600 | — | 1300 | MHz |
| f_{INDUTY} | Input clock duty cycle | 40 | — | 60 | % |
| $t_{INJITTER_CCJ}$ ⁽⁵⁾ | Input clock cycle-to-cycle jitter for $F_{INPFD} \geq 100$ MHz | — | — | 0.15 | UI |
| | Input clock cycle-to-cycle jitter for $F_{INPFD} < 100$ MHz | — | — | ±750 | ps |

Table 2-20. Cyclone III LS Devices PLL Specifications ⁽⁴⁾ (Part 2 of 2)

| Symbol | Parameter | Min | Typ | Max | Unit |
|---|--|-----|--------------------|----------|----------------|
| f_{OUT_EXT} (external clock output) ⁽¹⁾ | PLL output frequency | — | — | 450 | MHz |
| f_{OUT} (to global clock) | PLL output frequency (–7 speed grade) | — | — | 450 | MHz |
| | PLL output frequency (–8 speed grade) | — | — | 402.5 | MHz |
| $t_{OUTDUTY}$ | Duty cycle for external clock output (when set to 50%) | 45 | 50 | 55 | % |
| t_{LOCK} | Time required to lock from end of device configuration | — | — | 1 | ms |
| t_{DLOCK} | Time required to lock dynamically (after switchover, reconfiguring any non-post-scale counters/delays or areset is deasserted) | — | — | 1 | ms |
| $t_{OUTJITTER_PERIOD_DEDCLK}$ ⁽³⁾ | Dedicated clock output period jitter $F_{OUT} \geq 100$ MHz | — | — | 300 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 30 | mUI |
| $t_{OUTJITTER_CCJ_DEDCLK}$ ⁽³⁾ | Dedicated clock output cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz | — | — | 300 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 30 | mUI |
| $t_{OUTJITTER_PERIOD_IO}$ ⁽³⁾ | Regular I/O period jitter $F_{OUT} \geq 100$ MHz | — | — | 650 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 75 | mUI |
| $t_{OUTJITTER_CCJ_IO}$ ⁽³⁾ | Regular I/O cycle-to-cycle jitter $F_{OUT} \geq 100$ MHz | — | — | 650 | ps |
| | $F_{OUT} < 100$ MHz | — | — | 75 | mUI |
| t_{PLL_PSERR} | Accuracy of PLL phase shift | — | — | ± 50 | ps |
| t_{ARESET} | Minimum pulse width on areset signal. | 10 | — | — | ns |
| $t_{CONFIGPLL}$ | Time required to reconfigure scan chains for PLLs | — | 3.5 ⁽²⁾ | — | scanclk cycles |
| $f_{SCANCLK}$ | scanclk frequency | — | — | 100 | MHz |

Notes to Table 2-20:

- (1) This parameter is limited in the Quartus II software by the I/O maximum frequency. The maximum I/O frequency is different for each I/O standard.
- (2) With 100-MHz scanclk frequency.
- (3) Peak-to-peak jitter with a probability level of 10^{-12} (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL, when an input jitter of 30 ps is applied.
- (4) V_{CCD_PLL} must be connected to V_{CCINT} through the decoupling capacitor and ferrite bead.
- (5) A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source, which is less than 200 ps.
- (6) The V_{CO} frequency reported by the Quartus II software in the PLL summary section of the compilation report takes into consideration the V_{CO} post-scale counter K value. Therefore, if the counter K has a value of 2, the frequency reported can be lower than the f_{VCO} specification.

Embedded Multiplier Specifications

Table 2–21 lists the embedded multiplier specifications for Cyclone III LS devices.

Table 2–21. Cyclone III LS Devices Embedded Multiplier Specifications

| Mode | Resources Used | | EP3CLS70, EP3CLS100, EP3CLS150, and EP3CLS200 Performance | | Unit |
|------------------------|-----------------------|--|---|-----|------|
| | Number of Multipliers | | C7 and I7 | C8 | |
| 9 × 9-bit multiplier | 1 | | 300 | 260 | MHz |
| 18 × 18-bit multiplier | 1 | | 250 | 200 | MHz |

Memory Block Specifications

Table 2–22 lists the M9K memory block and logic element (LE) specifications for Cyclone III LS devices.

Table 2–22. Cyclone III LS Devices Memory Block Performance Specifications

| Memory | Mode | Resources Used | | EP3CLS70, EP3CLS100, EP3CLS150, and EP3CLS200 Performance | | Unit |
|-----------|------------------------------------|----------------|---------------|---|-----|------|
| | | LEs | M9K Memory | C7 and I7 | C8 | |
| M9K Block | FIFO 256 × 36 | 47 | 1 | 274 | 238 | MHz |
| | Single-port 256 × 36 | 0 | 1 | 274 | 238 | MHz |
| | Simple dual-port 256 × 36 CLK | 0 | 1 | 274 | 238 | MHz |
| | True dual port 512 × 18 single CLK | 0 | 1 | 274 | 238 | MHz |

Configuration and JTAG Specifications

Table 2–23 lists the configuration mode specifications for Cyclone III LS devices.

Table 2–23. Cyclone III LS Devices Configuration Mode Specifications

| Programming Mode | DCLK f_{MAX} | Unit |
|-----------------------------|----------------|------|
| Passive Serial (PS) | 133 | MHz |
| Fast Passive Parallel (FPP) | 100 | MHz |

Table 2–24 lists the active configuration mode specifications for Cyclone III LS devices.

Table 2–24. Cyclone III LS Devices Active Configuration Mode Specifications

| Programming Mode | DCLK Range | Unit |
|--------------------|------------|------|
| Active Serial (AS) | 20 to 40 | MHz |

Table 2-25 lists the JTAG timing parameters and values for Cyclone III LS devices.

Table 2-25. Cyclone III LS Devices JTAG Timing Parameters ⁽¹⁾

| Symbol | Parameter | Min | Max | Unit |
|-----------------|---|-----|-----|------|
| t_{JCP} | TCK clock period | 40 | — | ns |
| t_{JCH} | TCK clock high time | 20 | — | ns |
| t_{JCL} | TCK clock low time | 20 | — | ns |
| t_{JPSU_TDI} | JTAG port setup time for TDI | 2 | — | ns |
| t_{JPSU_TMS} | JTAG port setup time for TMS | 3 | — | ns |
| t_{JPH} | JTAG port hold time | 10 | — | ns |
| t_{JPCO} | JTAG port clock to output ⁽²⁾ | — | 16 | ns |
| t_{JPZX} | JTAG port high impedance to valid output ⁽²⁾ | — | 15 | ns |
| t_{JPXZ} | JTAG port valid output to high impedance ⁽²⁾ | — | 15 | ns |
| t_{JSSU} | Capture register setup time | 5 | — | ns |
| t_{JSH} | Capture register hold time | 10 | — | ns |
| t_{JSCO} | Update register clock to output | — | 25 | ns |
| t_{JSZX} | Update register high impedance to valid output | — | 25 | ns |
| t_{JSXZ} | Update register valid output to high impedance | — | 25 | ns |

Notes to Table 2-25:

- (1) For more information, refer to “JTAG Waveform” in “Glossary” on page 2-26.
- (2) The specification shown is for the 3.3-, 3.0-, and 2.5-V LVTTTL/LVCMOS operation of the JTAG pins. For the 1.8-V LVTTTL/LVCMOS and the 1.5-V LVC MOS, the JTAG port clock to output time is 16 ns.

Periphery Performance

This section describes periphery performance, including high-speed I/O, external memory interface, and IOE programmable delay.

I/O performance supports several systems interfacing, for example, the high-speed I/O interface, external memory interface, and PCI/PCI-X bus interface. I/O using SSTL-18 Class I termination standard can achieve up to the stated DDR2 SDRAM interfacing speed with typical DDR2 SDRAM memory interface setup. I/O using general purpose I/O standards such as 3.0, 2.5, 1.8, or 1.5 LVTTTL/LVCMOS are capable of typical 200 MHz interfacing frequency with 10 pF load.



Actual achievable frequency depends on design- and system-specific factors. Perform HSPICE/IBIS simulations based on your specific design and system setup to determine the maximum achievable frequency in your system.

High-Speed I/O Specification

Table 2-26 through Table 2-31 list the high-speed I/O timing for Cyclone III LS devices. For more information about the definitions of high-speed timing specifications, refer to “Glossary” on page 2-26.

Table 2-26. Cyclone III LS Devices RSDS Transmitter Timing Specification ⁽¹⁾, ⁽²⁾

| Symbol | Modes | C7 and I7 | | | C8 | | | Unit |
|--|---|-----------|-----|-------|-----|-----|-------|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| f_{HCLK} (input clock frequency) | x10 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | x8 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | x7 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | x4 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | x2 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | x1 | 5 | — | 311 | 5 | — | 311 | MHz |
| Device operation in Mbps | x10 | 100 | — | 311 | 100 | — | 311 | Mbps |
| | x8 | 80 | — | 311 | 80 | — | 311 | Mbps |
| | x7 | 70 | — | 311 | 70 | — | 311 | Mbps |
| | x4 | 40 | — | 311 | 40 | — | 311 | Mbps |
| | x2 | 20 | — | 311 | 20 | — | 311 | Mbps |
| | x1 | 10 | — | 311 | 10 | — | 311 | Mbps |
| t_{DUTY} | — | 45 | — | 55 | 45 | — | 55 | % |
| TCCS | — | — | — | 200 | — | — | 200 | ps |
| Output jitter (peak to peak) | — | — | — | 500 | — | — | 550 | ps |
| t_{RISE} | 20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$ | — | 500 | — | — | 500 | — | ps |
| t_{FALL} | 20 – 80%, $C_{\text{LOAD}} = 5 \text{ pF}$ | — | 500 | — | — | 500 | — | ps |
| $t_{\text{LOCK}}^{(3)}$ | — | — | — | 1 | — | — | 1 | ms |

Notes to Table 2-26:

- (1) Applicable for true RSDS and Emulated RSDS with three-resistor network transmitters.
- (2) True RSDS transmitter is only supported at the output pin of the Row I/O (Banks 1, 2, 5, and 6). Emulated RSDS with three-resistor network transmitter is supported at the output pin of all I/O banks.
- (3) t_{LOCK} is the time required for the PLL to lock from the end of device configuration.

Table 2-27. Cyclone III LS Devices Emulated RSDS with One-Resistor Network Transmitter Timing Specifications ⁽¹⁾

| Symbol | Modes | C7 and I7 | | | C8 | | | Unit |
|--|---------------------------------------|-----------|-----|-----|-----|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| f _{HSCLK} (input clock frequency) | ×10 | 5 | — | 85 | 5 | — | 85 | MHz |
| | ×8 | 5 | — | 85 | 5 | — | 85 | MHz |
| | ×7 | 5 | — | 85 | 5 | — | 85 | MHz |
| | ×4 | 5 | — | 85 | 5 | — | 85 | MHz |
| | ×2 | 5 | — | 85 | 5 | — | 85 | MHz |
| | ×1 | 5 | — | 170 | 5 | — | 170 | MHz |
| Device operation in Mbps | ×10 | 100 | — | 170 | 100 | — | 170 | Mbps |
| | ×8 | 80 | — | 170 | 80 | — | 170 | Mbps |
| | ×7 | 70 | — | 170 | 70 | — | 170 | Mbps |
| | ×4 | 40 | — | 170 | 40 | — | 170 | Mbps |
| | ×2 | 20 | — | 170 | 20 | — | 170 | Mbps |
| | ×1 | 10 | — | 170 | 10 | — | 170 | Mbps |
| t _{DUTY} | — | 45 | — | 55 | 45 | — | 55 | % |
| TCCS | — | — | — | 200 | — | — | 200 | ps |
| Output jitter (peak to peak) | — | — | — | 500 | — | — | 550 | ps |
| t _{RISE} | 20 – 80%, C _{LOAD} = 5 pF | — | 500 | — | — | 500 | — | ps |
| t _{FALL} | 20 – 80%, C _{LOAD} = 5 pF | — | 500 | — | — | 500 | — | ps |
| t _{LOCK} ⁽²⁾ | — | — | — | 1 | — | — | 1 | ms |

Notes to Table 2-27:

- (1) Emulated RSDS with one-resistor network transmitter is supported at the output pin of all I/O banks.
- (2) t_{LOCK} is the time required for the PLL to lock from the end of device configuration.

Table 2-28. Cyclone III LS Devices Mini-LVDS Transmitter Timing Specification ^{(1), (2)} (Part 1 of 2)

| Symbol | Modes | C7 and I7 | | | C8 | | | Unit |
|--|-------|-----------|-----|-------|-----|-----|-------|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| f _{HSCLK} (input clock frequency) | ×10 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | ×8 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | ×7 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | ×4 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | ×2 | 5 | — | 155.5 | 5 | — | 155.5 | MHz |
| | ×1 | 5 | — | 311 | 5 | — | 311 | MHz |

Table 2-28. Cyclone III LS Devices Mini-LVDS Transmitter Timing Specification ^{(1), (2)} (Part 2 of 2)

| Symbol | Modes | C7 and I7 | | | C8 | | | Unit |
|----------------------------------|---------------------------------------|-----------|-----|-----|-----|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Device operation in Mbps | ×10 | 100 | — | 311 | 100 | — | 311 | Mbps |
| | ×8 | 80 | — | 311 | 80 | — | 311 | Mbps |
| | ×7 | 70 | — | 311 | 70 | — | 311 | Mbps |
| | ×4 | 40 | — | 311 | 40 | — | 311 | Mbps |
| | ×2 | 20 | — | 311 | 20 | — | 311 | Mbps |
| | ×1 | 10 | — | 311 | 10 | — | 311 | Mbps |
| t _{DUTY} | — | 45 | — | 55 | 45 | — | 55 | % |
| TCCS | — | — | — | 200 | — | — | 200 | ps |
| Output jitter (peak to peak) | — | — | — | 500 | — | — | 550 | ps |
| t _{RISE} | 20 – 80%, C _{LOAD} = 5 pF | — | 500 | — | — | 500 | — | ps |
| t _{FALL} | 20 – 80%, C _{LOAD} = 5 pF | — | 500 | — | — | 500 | — | ps |
| t _{LOCK} ⁽³⁾ | — | — | — | 1 | — | — | 1 | ms |

Notes to Table 2-28:

- (1) Applicable for true and emulated mini-LVDS with three-resistor network transmitter.
- (2) True mini-LVDS transmitter is only supported at the output pin of the Row I/O (Banks 1, 2, 5, and 6). Emulated mini-LVDS with three-resistor network transmitter is supported at the output pin of all I/O banks.
- (3) t_{LOCK} is the time required for the PLL to lock from the end of device configuration.

Table 2-29. Cyclone III LS Devices True LVDS Transmitter Timing Specifications ⁽¹⁾

| Symbol | Modes | C7 and I7 | | C8 | | Unit |
|--|-------|-----------|-------|-----|-------|------|
| | | Min | Max | Min | Max | |
| f _{HSCLK} (input clock frequency) | ×10 | 5 | 370 | 5 | 320 | MHz |
| | ×8 | 5 | 370 | 5 | 320 | MHz |
| | ×7 | 5 | 370 | 5 | 320 | MHz |
| | ×4 | 5 | 370 | 5 | 320 | MHz |
| | ×2 | 5 | 370 | 5 | 320 | MHz |
| | ×1 | 5 | 402.5 | 5 | 402.5 | MHz |
| HSIODR | ×10 | 100 | 740 | 100 | 640 | Mbps |
| | ×8 | 80 | 740 | 80 | 640 | Mbps |
| | ×7 | 70 | 740 | 70 | 640 | Mbps |
| | ×4 | 40 | 740 | 40 | 640 | Mbps |
| | ×2 | 20 | 740 | 20 | 640 | Mbps |
| | ×1 | 10 | 402.5 | 10 | 402.5 | Mbps |
| t _{DUTY} | — | 45 | 55 | 45 | 55 | % |
| TCCS | — | — | 200 | — | 200 | ps |
| Output jitter (peak to peak) | — | — | 500 | — | 550 | ps |
| t _{LOCK} ⁽²⁾ | — | — | 1 | — | 1 | ms |

Notes to Table 2-29:

- (1) True LVDS transmitter is only supported at the output pin of the Row I/O (Banks 1, 2, 5, and 6).
- (2) t_{LOCK} is the time required for the PLL to lock from the end of device configuration.

Table 2-30. Cyclone III LS Devices Emulated LVDS with Three-Resistor Network Transmitter Timing Specifications ⁽¹⁾ (Part 1 of 2)

| Symbol | Modes | C7 and I7 | | C8 | | Unit |
|--|-------|-----------|-------|-----|-------|------|
| | | Min | Max | Min | Max | |
| f _{HSCLK} (input clock frequency) | ×10 | 5 | 320 | 5 | 275 | MHz |
| | ×8 | 5 | 320 | 5 | 275 | MHz |
| | ×7 | 5 | 320 | 5 | 275 | MHz |
| | ×4 | 5 | 320 | 5 | 275 | MHz |
| | ×2 | 5 | 320 | 5 | 275 | MHz |
| | ×1 | 5 | 402.5 | 5 | 402.5 | MHz |
| HSIODR | ×10 | 100 | 640 | 100 | 550 | Mbps |
| | ×8 | 80 | 640 | 80 | 550 | Mbps |
| | ×7 | 70 | 640 | 70 | 550 | Mbps |
| | ×4 | 40 | 640 | 40 | 550 | Mbps |
| | ×2 | 20 | 640 | 20 | 550 | Mbps |
| | ×1 | 10 | 402.5 | 10 | 402.5 | Mbps |
| t _{DUTY} | — | 45 | 55 | 45 | 55 | % |

Table 2-30. Cyclone III LS Devices Emulated LVDS with Three-Resistor Network Transmitter Timing Specifications ⁽¹⁾ (Part 2 of 2)

| Symbol | Modes | C7 and I7 | | C8 | | Unit |
|----------------------------------|-------|-----------|-----|-----|-----|------|
| | | Min | Max | Min | Max | |
| TCCS | — | — | 200 | — | 200 | ps |
| Output jitter (peak to peak) | — | — | 500 | — | 550 | ps |
| t_{LOCK} ⁽²⁾ | — | — | 1 | — | 1 | ms |

Notes to Table 2-30:

- (1) Emulated LVDS with three-resistor network transmitter is supported at the output pin of all I/O banks.
(2) t_{LOCK} is the time required for the PLL to lock from the end of device configuration.

Table 2-31. Cyclone III LS Devices LVDS Receiver Timing Specifications ⁽¹⁾

| Symbol | Modes | C7 and I7 | | C8 | | Unit |
|---|-------|-----------|-------|-----|-------|------|
| | | Min | Max | Min | Max | |
| f_{HCLK} (input clock frequency) | ×10 | 5 | 370 | 5 | 320 | MHz |
| | ×8 | 5 | 370 | 5 | 320 | MHz |
| | ×7 | 5 | 370 | 5 | 320 | MHz |
| | ×4 | 5 | 370 | 5 | 320 | MHz |
| | ×2 | 5 | 370 | 5 | 320 | MHz |
| | ×1 | 5 | 402.5 | 5 | 402.5 | MHz |
| HSIODR | ×10 | 100 | 740 | 100 | 640 | Mbps |
| | ×8 | 80 | 740 | 80 | 640 | Mbps |
| | ×7 | 70 | 740 | 70 | 640 | Mbps |
| | ×4 | 40 | 740 | 40 | 640 | Mbps |
| | ×2 | 20 | 740 | 20 | 640 | Mbps |
| | ×1 | 10 | 402.5 | 10 | 402.5 | Mbps |
| SW | — | — | 400 | — | 400 | % |
| Input jitter tolerance | — | — | 500 | — | 550 | ps |
| t_{LOCK} ⁽²⁾ | — | — | 1 | — | 1 | ps |

Notes to Table 2-31:

- (1) True LVDS receiver is supported at all banks.
(2) t_{LOCK} is the time required for the PLL to lock from the end of device configuration.

External Memory Interface Specifications

Cyclone III LS devices support external memory interfaces up to 200 MHz. The external memory interfaces for Cyclone III LS devices are auto-calibrating and easy to implement.

Table 2-32 and Table 2-33 list the external memory interface specifications for Cyclone III LS devices and are useful when performing memory interface timing analysis.


 For more information about external memory system performance specifications, board design guidelines, timing analysis, simulation, and debugging information, refer to *Literature: External Memory Interfaces*.

Table 2-32. FPGA Sampling Window (SW) Requirement—Read Side ⁽¹⁾

| Memory Standard | Column I/Os (ps) | | Row I/Os (ps) | | Wraparound Mode (ps) | |
|-----------------|------------------|------|---------------|------|----------------------|------|
| | Setup | Hold | Setup | Hold | Setup | Hold |
| C7 | | | | | | |
| DDR2 SDRAM | 705 | 650 | 770 | 715 | 985 | 930 |
| DDR SDRAM | 675 | 620 | 795 | 740 | 970 | 915 |
| QDRII SRAM | 900 | 845 | 910 | 855 | 1085 | 1030 |
| C8 | | | | | | |
| DDR2 SDRAM | 785 | 720 | 930 | 870 | 1115 | 1055 |
| DDR SDRAM | 800 | 740 | 915 | 855 | 1185 | 1125 |
| QDRII SRAM | 1050 | 990 | 1065 | 1005 | 1210 | 1150 |
| I7 | | | | | | |
| DDR2 SDRAM | 765 | 710 | 855 | 800 | 1040 | 985 |
| DDR SDRAM | 745 | 690 | 880 | 825 | 1000 | 945 |
| QDRII SRAM | 945 | 890 | 955 | 900 | 1130 | 1075 |

Note to Table 2-32:

(1) Column I/Os refer to top and bottom I/Os. Row I/Os refer to right and left I/Os. Wraparound mode refers to the combination of column and row I/Os.

Table 2-33. Cyclone III LS Devices Transmitter Channel-to-Channel Skew (TCCS)—Write Side ⁽¹⁾ (Part 1 of 2)

| Memory Standard | I/O Standard | Column I/Os (ps) | | Row I/Os (ps) | | Wraparound Mode (ps) | |
|-----------------|---------------------|------------------|-----|---------------|-----|----------------------|-----|
| | | Lead | Lag | Lead | Lag | Lead | Lag |
| C7 | | | | | | | |
| DDR2 SDRAM | SSTL-18 Class I | 915 | 410 | 915 | 410 | 1015 | 510 |
| | SSTL-18 Class II | 1025 | 545 | 1025 | 545 | 1125 | 645 |
| DDR SDRAM | SSTL-2 Class I | 880 | 340 | 880 | 340 | 980 | 440 |
| | SSTL-2 Class II | 1010 | 380 | 1010 | 380 | 1010 | 480 |
| QDRII SRAM | 1.8-V HSTL Class I | 910 | 450 | 910 | 450 | 1010 | 550 |
| | 1.8-V HSTL Class II | 1010 | 570 | 1010 | 570 | 1110 | 670 |
| C8 | | | | | | | |
| DDR2 SDRAM | SSTL-18 Class I | 1040 | 440 | 1040 | 440 | 1140 | 540 |
| | SSTL-18 Class II | 1180 | 600 | 1180 | 600 | 1280 | 700 |
| DDR SDRAM | SSTL-2 Class I | 1010 | 360 | 1010 | 360 | 1110 | 460 |
| | SSTL-2 Class II | 1160 | 410 | 1160 | 410 | 1260 | 510 |
| QDRII SRAM | 1.8-V HSTL Class I | 1040 | 490 | 1040 | 490 | 1140 | 590 |
| | 1.8-V HSTL Class II | 1190 | 630 | 1190 | 630 | 1290 | 730 |

Table 2-33. Cyclone III LS Devices Transmitter Channel-to-Channel Skew (TCCS)—Write Side ⁽¹⁾ (Part 2 of 2)

| Memory Standard | I/O Standard | Column I/Os (ps) | | Row I/Os (ps) | | Wraparound Mode (ps) | |
|-----------------|---------------------|------------------|-----|---------------|-----|----------------------|-----|
| | | Lead | Lag | Lead | Lag | Lead | Lag |
| 17 | | | | | | | |
| DDR2 SDRAM | SSTL-18 Class I | 961 | 431 | 961 | 431 | 1061 | 531 |
| | SSTL-18 Class II | 1076 | 572 | 1076 | 572 | 1176 | 672 |
| DDR SDRAM | SSTL-2 Class I | 924 | 357 | 924 | 357 | 1024 | 457 |
| | SSTL-2 Class II | 1061 | 399 | 1061 | 399 | 1161 | 499 |
| QDR II SRAM | 1.8-V HSTL Class I | 956 | 473 | 956 | 473 | 1056 | 573 |
| | 1.8-V HSTL Class II | 1061 | 599 | 1061 | 599 | 1161 | 699 |

Note to Table 2-33:

- (1) Column I/O banks refer to top and bottom I/Os. Row I/O banks refer to right and left I/Os. Wraparound mode refers to the combination of column and row I/Os.

Table 2-34 lists the Cyclone III LS devices memory output clock jitter specifications.

Table 2-34. Cyclone III LS Devices Memory Output Clock Jitter Specifications ^{(1), (2)}

| Parameter | Symbol | Min | Max | Unit |
|------------------------------|------------------|------|-----|------|
| Clock period jitter | t_{JIT} (per) | -125 | 125 | ps |
| Cycle-to-cycle period jitter | t_{JIT} (cc) | -200 | 200 | ps |
| Duty cycle jitter | t_{JIT} (duty) | -150 | 150 | ps |

Notes to Table 2-34:

- (1) The memory output clock jitter measurements are for 200 consecutive clock cycles, as specified in the JEDEC DDR2 standard.
(2) The clock jitter specification applies to memory output clock pins generated using DDIO circuits clocked by a PLL output routed on a global clock network.

Duty Cycle Distortion Specification

Table 2-35 lists the worst case duty cycle distortion for Cyclone III LS devices.

Table 2-35. Duty Cycle Distortion on Cyclone III LS Devices I/O Pins ^{(1), (2)}

| Symbol | C7, I7 | | C8 | | Unit |
|-------------------|--------|-----|-----|-----|------|
| | Min | Max | Min | Max | |
| Output Duty Cycle | 45 | 55 | 45 | 55 | % |

Notes to Table 2-35:

- (1) The duty cycle distortion specification applies to clock outputs from the PLLs, global clock tree, and I/O element (IOE) driving the dedicated and general purpose I/O pins.
(2) Cyclone III LS devices meet the DCD specifications at the maximum output toggle rate for each combination of the I/O standard and current strength.

OCT Calibration Timing Specification

Table 2–36 lists the duration of calibration for series OCT with calibration at device power-up for Cyclone III LS devices.

Table 2–36. Cyclone III LS Devices Timing Specification for Series OCT with Calibration at Device Power-Up ⁽¹⁾

| Symbol | Description | Maximum | Unit |
|---------------------|--|---------|------|
| t _{OCTCAL} | Duration of series OCT with calibration at device power-up | 20 | μs |

Note to Table 2–36:

(1) OCT calibration takes place after device configuration, before entering user mode.

IOE Programmable Delay

Table 2–37 and Table 2–38 list the IOE programmable delay for Cyclone III LS devices.

Table 2–37. Cyclone III LS Devices IOE Programmable Delay on the Column Pins ^{(1), (2)}

| Parameter | Paths Affected | Number of setting | Min Offset | Max Offset | | | | | Unit |
|---|-----------------------------|-------------------|------------|-------------|-------|-------------|-------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | |
| | | | | I7 | C7 | C7 | C8 | I7 | |
| Input delay from the pin to the internal cells | Pad to I/O dataout to core | 7 | 0 | 1.211 | 1.314 | 2.339 | 2.416 | 2.397 | ns |
| Input delay from the pin to the input register | Pad to I/O input register | 8 | 0 | 1.203 | 1.307 | 2.387 | 2.540 | 2.430 | ns |
| Delay from the output register to the output pin | I/O output register to pad | 2 | 0 | 0.518 | 0.559 | 1.065 | 1.151 | 1.082 | ns |
| Input delay from the dual-purpose clock pin to the fan-out destinations | Pad to global clock network | 12 | 0 | 0.533 | 0.56 | 1.077 | 1.182 | 1.087 | ns |

Notes to Table 2–37:

- (1) The incremental values for the settings are generally linear. For the exact values of each setting, use the latest version of the Quartus II software.
- (2) The minimum and maximum offset timing numbers refer to the 0 setting available in the Quartus II software.

Table 2–38. Cyclone III LS Devices IOE Programmable Delay on Row Pins ^{(1), (2)}

| Parameter | Paths Affected | Number of setting | Min Offset | Max Offset | | | | | Unit |
|--|----------------------------|-------------------|------------|-------------|-------|-------------|-------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | |
| | | | | I7 | C7 | C7 | C8 | I7 | |
| Input delay from the pin to the internal cells | Pad to I/O dataout to core | 7 | 0 | 1.209 | 1.314 | 2.352 | 2.514 | 2.432 | ns |
| Input delay from the pin to the input register | Pad to I/O input register | 8 | 0 | 1.207 | 1.312 | 2.402 | 2.558 | 2.447 | ns |
| Delay from the output register to the output pin | I/O output register to pad | 2 | 0 | 0.549 | 0.595 | 1.135 | 1.226 | 1.151 | ns |

Table 2-38. Cyclone III LS Devices IOE Programmable Delay on Row Pins ⁽¹⁾, ⁽²⁾

| Parameter | Paths Affected | Number of setting | Min Offset | Max Offset | | | | | Unit |
|---|-----------------------------|-------------------|------------|-------------|------|-------------|------|-------|------|
| | | | | Fast Corner | | Slow Corner | | | |
| | | | | I7 | C7 | C7 | C8 | I7 | |
| Input delay from the dual-purpose clock pin to the fan-out destinations | Pad to global clock network | 12 | 0 | 0.52 | 0.54 | 1.052 | 1.16 | 1.061 | ns |

Notes to Table 2-38:

- (1) The incremental values for the settings are generally linear. For the exact values of each setting, use the latest version of the Quartus II software.
(2) The minimum and maximum offset timing numbers refer to the 0 setting available in the Quartus II software.


I/O Timing

DirectDrive technology and MultiTrack interconnect ensure predictable performance, accurate simulation, and accurate timing analysis across all Cyclone III LS device densities and speed grades.


Use the following methods to determine I/O timing:

- The Excel-based I/O timing
- The Quartus II Timing Analyzer

Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used before designing the FPGA to get a timing budget estimation as part of the link timing analysis. The Quartus II Timing Analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after place-and-route is complete.

-  For more information about the Excel-based I/O timing spreadsheet, refer to the [Cyclone III Devices Literature](#) page on the Altera website.

All specifications are representative of worst-case supply voltage and junction temperature conditions. Altera characterizes timing delays at the worst-case process, minimum voltage, and maximum temperature for input register setup time (t_{SU}) and hold time (t_H).

-  For more information about timing delay from the FPGA output to the receiving device for system-timing analysis, refer to [AN 366: Understanding I/O Output Timing for Altera Devices](#).

Glossary

Table 2-39 lists the glossary for this chapter.

Table 2-39. Glossary (Part 1 of 6)

| Letter | Term | Definitions |
|--------|------|-------------|
| A | — | — |
| B | — | — |
| C | — | — |

Table 2-39. Glossary (Part 2 of 6)


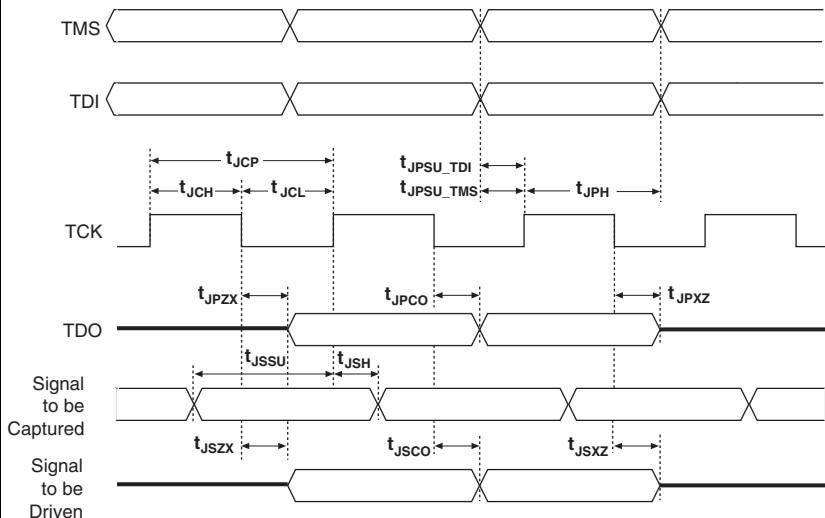
| Letter | Term | Definitions |
|--------|--|---|
| D | — | — |
| E | — | — |
| F | f_{HSCLK} | High-speed I/O Block: High-speed receiver and transmitter input and output clock frequency. |
| G | GCLK | Input pin directly to the global clock network. |
| | GCLK PLL | Input pin to the global clock network through the PLL. |
| H | HSIODR | High-speed I/O Block: Maximum and minimum LVDS data transfer rate ($HSIODR = 1/TUI$). |
| I | Input Waveforms for the SSTL Differential I/O Standard |  |
| J | JTAG Waveform |  |
| K | — | — |
| L | — | — |
| M | — | — |
| N | — | — |
| O | — | — |

Table 2-39. Glossary (Part 3 of 6)

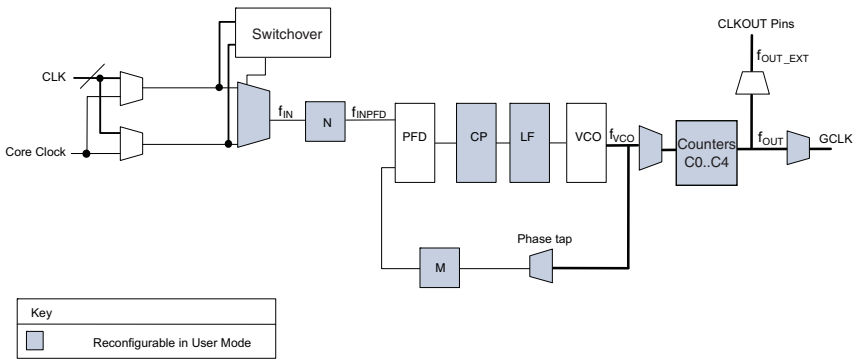
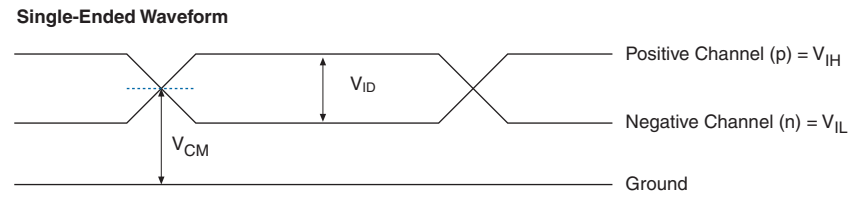
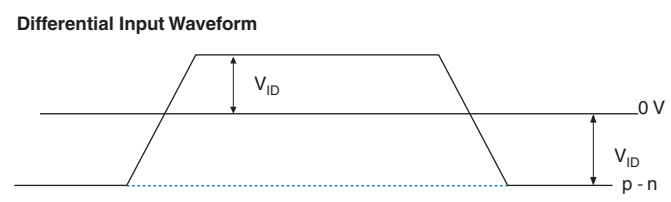
| Letter | Term | Definitions |
|--------|---|---|
| P | PLL Block | <p>The following block diagram highlights the PLL specification parameters.</p>  <p>Key</p> <ul style="list-style-type: none"> Reconfigurable in User Mode |
| Q | — | — |
| R | <p>R_L</p> <p>Receiver Input Waveform</p> <p>RSKM (Receiver input skew margin)</p> | <p>Receiver differential input discrete resistor (external to the Cyclone III LS device)</p> <p>Receiver Input Waveform for LVDS and LVPECL Differential Standards</p> <p>Single-Ended Waveform</p>  <p>Positive Channel (p) = V_{IH}</p> <p>Negative Channel (n) = V_{IL}</p> <p>Ground</p> <p>Differential Input Waveform</p>  <p>0 V</p> <p>V_{ID}</p> <p>V_{ID}</p> <p>p - n</p> <p>High-speed I/O Block: The total margin left after accounting for the sampling window and TCCS. $RSKM = (TUI - SW - TCCS) / 2$</p> |

Table 2-39. Glossary (Part 4 of 6)

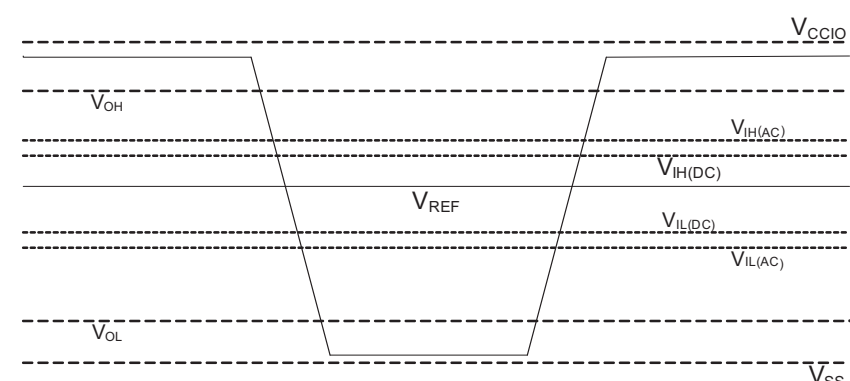
| Letter | Term | Definitions |
|--------|--|---|
| S | Single-ended Voltage referenced I/O Standard |  <p>The JEDEC standard for SSTI and HSTL I/O standards defines both the AC and DC input signal values.</p> <ul style="list-style-type: none"> ■ The AC values indicate the voltage levels at which the receiver must meet its timing specifications. ■ The DC values indicate the voltage levels at which the final logic state of the receiver is unambiguously defined. <p>After the receiver input crosses the AC value, the receiver changes to the new logic state. The new logic state is then maintained as long as the input stays beyond the DC threshold. This approach is intended to provide predictable receiver timing in the presence of input waveform ringing.</p> |
| | SW (Sampling Window) | High-speed I/O Block: The period of time during which the data must be valid to capture it correctly. The setup and hold times determine the ideal strobe position in the sampling window. |
| T | t_C | High-speed receiver and transmitter input and output clock period. |
| | TCCS (Channel-to-channel-skew) | High-speed I/O Block: The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew. The clock is included in the TCCS measurement. |
| | t_{cin} | Delay from the clock pad to the I/O input register. |
| | t_{CO} | Delay from the clock pad to the I/O output. |
| | t_{cout} | Delay from the clock pad to the I/O output register. |
| | t_{DUTY} | High-speed I/O Block: Duty cycle on the high-speed transmitter output clock. |
| | t_{FALL} | Signal high-to-low transition time (80 to 20%). |
| | t_H | Input register hold time. |
| | Timing Unit Interval (TUI) | High-speed I/O block: The timing budget allowed for skew, propagation delays, and the data sampling window. $(TUI = 1/(\text{Receiver Input Clock Frequency Multiplication Factor}) = t_C/W)$. |
| | $t_{INJITTER}$ | Period jitter on the PLL clock input. |
| | $t_{OUTJITTER_DEDCLK}$ | Period jitter on the dedicated clock output driven by a PLL. |
| | $t_{OUTJITTER_IO}$ | Period jitter on the general purpose I/O driven by a PLL. |
| | t_{pllcin} | Delay from the PLL inclk pad to the I/O input register. |
| | $t_{pllcout}$ | Delay from the PLL inclk pad to the I/O output register. |

Table 2-39. Glossary (Part 5 of 6)

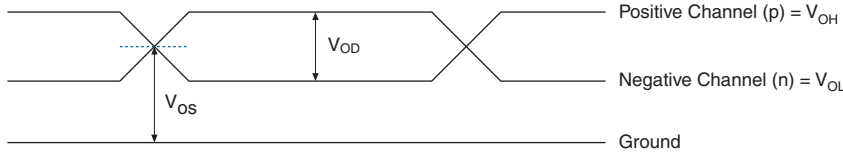
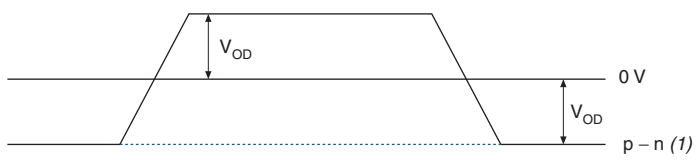
| Letter | Term | Definitions |
|----------|-----------------------------|--|
| | Transmitter Output Waveform | <p>Transmitter output waveforms for the LVDS, mini-LVDS, PPDS, and RSDS differential I/O standards</p> <p>Single-Ended Waveform</p>  <p>Positive Channel (p) = V_{OH} Negative Channel (n) = V_{OL} Ground</p> <p>Differential Waveform (Mathematical Function of Positive & Negative Channel)</p>  <p>0 V $p - n (I)$</p> |
| | t_{RISE} | Signal low-to-high transition time (20–80%). |
| | t_{SU} | Input register setup time. |
| U | — | — |

Table 2-39. Glossary (Part 6 of 6)

| Letter | Term | Definitions |
|-----------------|--|---|
| V | $V_{CM(DC)}$ | DC common mode input voltage. |
| | $V_{DIF(AC)}$ | AC differential Input Voltage—The minimum AC input differential voltage required for switching. |
| | $V_{DIF(DC)}$ | DC differential Input Voltage—The minimum DC input differential voltage required for switching. |
| | V_{ICM} | Input Common Mode Voltage—The common mode of the differential signal at the receiver. |
| | V_{ID} | Input differential Voltage Swing—The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver. |
| | V_{IH} | Voltage Input High—The minimum positive voltage applied to the input that is accepted by the device as a logic high. |
| | $V_{IH(AC)}$ | High-level AC input voltage. |
| | $V_{IH(DC)}$ | High-level DC input voltage. |
| | V_{IL} | Voltage Input Low—The maximum positive voltage applied to the input that is accepted by the device as a logic low. |
| | $V_{IL(AC)}$ | Low-level AC input voltage. |
| | $V_{IL(DC)}$ | Low-level DC input voltage. |
| | V_{IN} | DC input voltage. |
| | V_{OCM} | Output Common Mode Voltage—The common mode of the differential signal at the transmitter. |
| | V_{OD} | Output differential Voltage Swing—The difference in voltage between the positive and complementary conductors of a differential transmission at the transmitter. $V_{OD} = V_{OH} - V_{OL}$. |
| | V_{OH} | Voltage Output High—The maximum positive voltage from an output that the device considers will be accepted as the minimum positive high level. |
| | V_{OL} | Voltage Output Low—The maximum positive voltage from an output that the device considers will be accepted as the maximum positive low level. |
| | V_{OS} | Output offset voltage— $V_{OS} = (V_{OH} + V_{OL}) / 2$. |
| | $V_{OX(AC)}$ | AC differential Output cross point voltage—The voltage at which the differential output signals must cross. |
| | V_{REF} | Reference voltage for the SSTL and HSTL I/O standards. |
| | $V_{REF(AC)}$ | AC input reference voltage for the SSTL and HSTL I/O standards. $V_{REF(AC)} = V_{REF(DC)} + \text{noise}$. The peak-to-peak AC noise on V_{REF} must not exceed 2% of $V_{REF(DC)}$. |
| $V_{REF(DC)}$ | DC input reference voltage for the SSTL and HSTL I/O standards. | |
| $V_{SWING(AC)}$ | AC differential Input Voltage—AC Input differential voltage required for switching. Refer to Input Waveforms for the SSTL Differential I/O Standard. | |
| $V_{SWING(DC)}$ | DC differential Input Voltage—DC Input differential voltage required for switching. Refer to Input Waveforms for the SSTL Differential I/O Standard. | |
| V_{TT} | Termination voltage for the SSTL and HSTL I/O standards. | |
| $V_{X(AC)}$ | AC differential Input cross point Voltage—The voltage at which the differential input signals must cross. | |
| W | — | — |
| X | — | — |
| Y | — | — |
| Z | — | — |

Document Revision History

Table 2-40 lists the revision history for this document.

Table 2-40. Document Revision History

| Date | Version | Changes |
|---------------|---------|---|
| July 2012 | 1.4 | <ul style="list-style-type: none"> ■ Updated minimum f_{HSCLK} value to 5 MHz. ■ Updated absolute maximum T_J to 125 °C in Table 2-1. ■ Finalized all preliminary information. |
| December 2011 | 1.3 | <ul style="list-style-type: none"> ■ Updated “Supply Current” on page 2-5, “Periphery Performance” on page 2-17, and “External Memory Interface Specifications” on page 2-22. ■ Updated Table 2-1, Table 2-3, Table 2-13, Table 2-16, Table 2-17, Table 2-20, and Table 2-25. |
| December 2009 | 1.2 | <ul style="list-style-type: none"> ■ Updated Table 2-19 through Table 2-34, Table 2-37, and Table 2-38. ■ Updated the “Periphery Performance” on page 2-17 section. ■ Minor changes to the text. |
| July 2009 | 1.1 | Minor edit to the hyperlinks. |
| June 2009 | 1.0 | Initial release. |