EN6363QI 6A PowerSoC
Step-Down DC-DC Switching Converter with Integrated Inductor

DESCRIPTION
The EN6363QI is an Intel® Enpirion® Power System on a Chip (PowerSoC) DC-DC converter. It integrates the inductor, MOSFET switches, small-signal circuits and compensation in an advanced 4mm x 6mm x 2.5mm 34-pin QFN package.

The EN6363QI is specifically designed to meet the precise voltage and fast transient requirements of present and future high-performance, low-power processor, DSP, FPGA, memory boards and system level applications in distributed power architectures. The device’s advanced circuit techniques, high switching frequency, and proprietary integrated inductor technology deliver high-quality, ultra compact, non-isolated DC-DC conversion.

Intel Enpirion Power Solutions significantly help in system design and productivity by offering greatly simplified board design, layout and manufacturing requirements. In addition, a reduction in the number of components required for the complete power solution helps to enable an overall system cost saving.

All Enpirion products are RoHS compliant and lead-free manufacturing environment compatible.

FEATURES
- High Efficiency (Up to 95%)
- Excellent Ripple and EMI Performance
- Up to 6A Continuous Operating Current
- 2.7V to 6.6V Input Voltage Range
- 0.5% $V_{FB}$ Initial Accuracy
- 1.5% $V_{OUT}$ Accuracy (Line, Load, Temp)
- 2MHz Switching Frequency
- 60mm² Optimized Total Solution Size
- Programmable Soft-Start
- Power OK Indicator
- Thermal, Over-Current, Short Circuit, Under-Voltage and Pre-Bias Protections
- Pin Compatible with EN6340QI (4A)
- RoHS Compliant, MSL Level 3, 260°C Reflow

APPLICATIONS
- Point of Load Regulation for FPGAs, Distributed Power Architectures, Low-Power ASICs, Multi-Core, Communication Processors and DSPs
- Space Constrained Applications Needing High Power Density
- 5V/3.3V Bus Architectures Needing High Efficiency
Datasheet | Intel® Enpirion® Power Solutions: EN6363QI

ORDERING INFORMATION

<table>
<thead>
<tr>
<th>Part Number</th>
<th>Package Markings</th>
<th>Tj Rating</th>
<th>Package Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EN6363QI</td>
<td>EN6363QI</td>
<td>-40°C to +125°C</td>
<td>34-pin (4mm x 6mm x 2.5mm) QFN</td>
</tr>
<tr>
<td>EVB-EN6363QI</td>
<td>EN6363QI</td>
<td></td>
<td>QFN Evaluation Board</td>
</tr>
</tbody>
</table>


PIN FUNCTIONS

![Pin Diagram (Top View)]

**NOTE A**: NC pins are not to be electrically connected to each other or to any external signal, ground or voltage. However, they must be soldered to the PCB. Failure to follow this guideline may result in part malfunction or damage.

**NOTE B**: White ‘dot’ on top left is pin 1 indicator on top of the device package.

**NOTE C**: Keep-Out are No Connect pads that should not be electrically connected to each other or to any external signal, ground or voltage. They do not need to be soldered to the PCB.
## PIN DESCRIPTIONS

<table>
<thead>
<tr>
<th>PIN</th>
<th>NAME</th>
<th>TYPE</th>
<th>FUNCTION</th>
</tr>
</thead>
<tbody>
<tr>
<td>1, 2, 12, 30, 31, 32, 33, 34</td>
<td>NC(SW)</td>
<td>-</td>
<td>No Connect. These pins are internally connected to the common switching node of the internal MOSFETs. They must be soldered to PCB but not be electrically connected to any external signal, ground, or voltage. Failure to follow this guideline may result in device damage.</td>
</tr>
<tr>
<td>3, 4, 18, 19, 21, 22, 23</td>
<td>NC</td>
<td>-</td>
<td>No Connect. These pins must be soldered to PCB but not electrically connected to each other or to any external signal, voltage, or ground. These pins may be connected internally. Failure to follow this guideline may result in device damage.</td>
</tr>
<tr>
<td>5, 6, 7, 8, 9, 10, 11</td>
<td>VOUT</td>
<td>Power</td>
<td>Regulated converter output. Connect to the load and place output filter capacitor(s) between these pins and PGND pins. Refer to the Layout Recommendation section.</td>
</tr>
<tr>
<td>13, 14</td>
<td>PGND</td>
<td>Ground</td>
<td>Input/Output power ground. Connect to the ground electrode of the input and output filter capacitors. See VOUT and PVIN pin descriptions for more details.</td>
</tr>
<tr>
<td>15, 16, 17</td>
<td>PVIN</td>
<td>Power</td>
<td>Input power supply. Connect to input power supply. Decouple with input capacitor to PGND pin. Refer to the Layout Recommendation section.</td>
</tr>
<tr>
<td>20</td>
<td>ENABLE</td>
<td>Analog</td>
<td>Input Enable. Applying logic high or floating the ENABLE pin will enable the device and initiate a soft-start. Applying logic low disables the output and switching stops.</td>
</tr>
<tr>
<td>24</td>
<td>VFB</td>
<td>Analog</td>
<td>External feedback input pin. A resistor divider connects from the output to AGND. The mid-point of the resistor divider is connected to VFB. A feed-forward capacitor (C_A) and resistor (R_C) are required in parallel to the upper feedback resistor (R_A). The output voltage regulation is based on the VFB node voltage being equal to 0.6V.</td>
</tr>
<tr>
<td>25</td>
<td>SS</td>
<td>Analog</td>
<td>A soft-start capacitor is connected between this pin and AGND. The value of the capacitor controls the soft-start interval. Refer to Soft-Start Operation in the Functional Description section for more details.</td>
</tr>
<tr>
<td>26</td>
<td>AVIN</td>
<td>Power</td>
<td>Input power supply for the controller. Connect to input voltage at a quiet point. A 10Ω resistor is recommended between PVIN and AVIN for filtering. Refer to the Layout Recommendation section.</td>
</tr>
<tr>
<td>27, 29</td>
<td>AGND</td>
<td>Ground</td>
<td>Ground for internal control circuits. Connect to the power ground plane with a via right next to the pin.</td>
</tr>
<tr>
<td>28</td>
<td>POK</td>
<td>Digital</td>
<td>Power OK is an open drain transistor used for power system state indication. POK is logic high when V_{OUT} is within ±10% of V_{OUT} nominal and has an internal 100kΩ pull-up resistance to AVIN.</td>
</tr>
<tr>
<td>35</td>
<td>PGND</td>
<td>Ground</td>
<td>Power ground thermal pad. Not a perimeter pin. Connect thermal pad to the system GND plane for heat-sinking purposes. Refer to the Layout Recommendation section.</td>
</tr>
</tbody>
</table>
ABSOLUTE MAXIMUM RATINGS

CAUTION: Absolute Maximum ratings are stress ratings only. Functional operation beyond the recommended operating conditions is not implied. Stress beyond the absolute maximum ratings may impair device life. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

### Absolute Maximum Pin Ratings

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>MIN</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>PVIN, AVIN, VOUT</td>
<td>-0.3</td>
<td>7.0</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>ENABLE, POK</td>
<td>-0.3</td>
<td>( V_{IN} + 0.3 )</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>VFB, SS</td>
<td>-0.3</td>
<td>2.5</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>NC(SW) Voltage DC</td>
<td>( V_{SW} )</td>
<td>7.0</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>NC(SW) Voltage Peak &lt; 5ns</td>
<td>( V_{SW_PEAK} )</td>
<td>-2.0</td>
<td>10.5</td>
<td>V</td>
</tr>
</tbody>
</table>

### Absolute Maximum Thermal Ratings

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>CONDITION</th>
<th>MIN</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maximum Operating Junction Temperature</td>
<td></td>
<td></td>
<td>+150</td>
<td>°C</td>
</tr>
<tr>
<td>Storage Temperature Range</td>
<td></td>
<td>-65</td>
<td>+150</td>
<td>°C</td>
</tr>
<tr>
<td>Reflow Peak Body Temperature (10 Sec) MSL3 JEDEC J-STD-020A</td>
<td></td>
<td></td>
<td>+260</td>
<td>°C</td>
</tr>
</tbody>
</table>

### Absolute Maximum ESD Ratings

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>CONDITION</th>
<th>MIN</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>HBM (Human Body Model)</td>
<td>±2000</td>
<td></td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>CDM (Charged Device Model)</td>
<td>±500</td>
<td></td>
<td>V</td>
<td></td>
</tr>
</tbody>
</table>

### RECOMMENDED OPERATING CONDITIONS

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>MIN</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input Voltage Range</td>
<td>( V_{IN} )</td>
<td>2.7</td>
<td>6.6</td>
<td>V</td>
</tr>
<tr>
<td>Output Voltage Range</td>
<td>( V_{OUT} )</td>
<td>0.6</td>
<td>( V_{IN} - V_{DO} )</td>
<td>V</td>
</tr>
<tr>
<td>Output Current Range</td>
<td>( I_{OUT} )</td>
<td>6</td>
<td>A</td>
<td></td>
</tr>
<tr>
<td>Operating Ambient Temperature Range</td>
<td>( T_{A} )</td>
<td>-40</td>
<td>+85</td>
<td>°C</td>
</tr>
<tr>
<td>Operating Junction Temperature</td>
<td>( T_{J} )</td>
<td>-40</td>
<td>+125</td>
<td>°C</td>
</tr>
</tbody>
</table>
# THERMAL CHARACTERISTICS

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>TYPICAL</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Thermal Shutdown</td>
<td>T_{SD}</td>
<td>160</td>
<td>ºC</td>
</tr>
<tr>
<td>Thermal Shutdown Hysteresis</td>
<td>T_{SDHYS}</td>
<td>25</td>
<td>ºC</td>
</tr>
<tr>
<td>Thermal Resistance: Junction to Ambient (0 LFM)</td>
<td>θ_{JA}</td>
<td>12.5</td>
<td>ºC/W</td>
</tr>
<tr>
<td>Thermal Resistance: Junction to Case (0 LFM)</td>
<td>θ_{JC}</td>
<td>1</td>
<td>ºC/W</td>
</tr>
</tbody>
</table>

(1) \(V_{DO}\) (dropout voltage) is defined as \((I_{LOAD} \times \text{Dropout Resistance})\). Please refer to Electrical Characteristics Table.

(2) Based on 2oz. external copper layers and proper thermal design in line with EIJ/JEDEC JESD51-7 standard for high thermal conductivity boards.
**ELECTRICAL CHARACTERISTICS**

NOTE: $V_{IN} = PVIN = AVIN = 5V$, Minimum and Maximum values are over operating ambient temperature range unless otherwise noted. Typical values are at $T_A = T_J = 25^\circ C$.

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Input Voltage</td>
<td>$V_{IN}$</td>
<td>$PVIN = AVIN$</td>
<td>2.7</td>
<td>6.6</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>Under Voltage Lock-Out – $V_{IN}$ Rising</td>
<td>$V_{UVLO}$</td>
<td>Voltage above which UVLO is not asserted</td>
<td>2.2</td>
<td>2.3</td>
<td>2.4</td>
<td>V</td>
</tr>
<tr>
<td>Under Voltage Lock-Out – $V_{IN}$ Falling</td>
<td>$V_{UVLO}$</td>
<td>Voltage below which UVLO is asserted</td>
<td>1.7</td>
<td>2.075</td>
<td>2.2</td>
<td>V</td>
</tr>
<tr>
<td>Under Voltage Lock-Out Hysteresis</td>
<td>$V_{UVLOHYS}$</td>
<td></td>
<td></td>
<td></td>
<td>225</td>
<td>mV</td>
</tr>
<tr>
<td>Shut-Down Supply Current</td>
<td>$I_S$</td>
<td>$ENABLE = 0V$</td>
<td>500</td>
<td>700</td>
<td></td>
<td>µA</td>
</tr>
<tr>
<td>AVIN Quiescent Current</td>
<td>$I_{AVIN}$</td>
<td>AVIN only</td>
<td>3.5</td>
<td>10</td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td>No Load Quiescent Current</td>
<td>$I_{VINQ}$</td>
<td>$PVIN$ and $AVIN$ $V_{OUT} = 1.2V$</td>
<td>40</td>
<td></td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td>Feedback Pin Voltage (3)</td>
<td>$V_{FB}$</td>
<td>$V_{OUT} = 0.6V, I_{LOAD} = 0$, $T_A = 25^\circ C$</td>
<td>0.597</td>
<td>0.6</td>
<td>0.603</td>
<td>V</td>
</tr>
<tr>
<td>Feedback Pin Voltage (Line, Load, Temp.)</td>
<td>$V_{FB}$</td>
<td>$2.7V \leq V_{IN} \leq 6.6V$ 0A $\leq I_{LOAD} \leq 6A$ $-40^\circ C \leq T_A \leq 85^\circ C$</td>
<td>0.591</td>
<td>0.6</td>
<td>0.609</td>
<td>V</td>
</tr>
<tr>
<td>Feedback pin Input Leakage Current (4)</td>
<td>$I_{FB}$</td>
<td>VFB pin input leakage current</td>
<td>-10</td>
<td></td>
<td>10</td>
<td>nA</td>
</tr>
<tr>
<td>$V_{OUT}$ Rise Time Range (4)</td>
<td>$t_{RISE}$</td>
<td>Capacitor programmable</td>
<td>0.2</td>
<td>20</td>
<td></td>
<td>ms</td>
</tr>
<tr>
<td>Soft Start Capacitance Range (4)</td>
<td>$C_{SS,RANGE}$</td>
<td></td>
<td>10</td>
<td>100</td>
<td></td>
<td>nF</td>
</tr>
<tr>
<td>Soft-Start Charging Current</td>
<td>$I_{SS}$</td>
<td></td>
<td>3.5</td>
<td>5</td>
<td>6.5</td>
<td>µA</td>
</tr>
<tr>
<td>Drop-Out Voltage (4)</td>
<td>$V_{DO}$</td>
<td>$V_{INMIN} - V_{OUT}$ at full load</td>
<td>300</td>
<td>480</td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td>Drop-Out Resistance (4)</td>
<td>$R_{DO}$</td>
<td>Input to output resistance</td>
<td>50</td>
<td>80</td>
<td></td>
<td>mΩ</td>
</tr>
<tr>
<td>Continuous Output Current</td>
<td>$I_{OUT}$</td>
<td></td>
<td>0</td>
<td>6</td>
<td>8.5</td>
<td>A</td>
</tr>
<tr>
<td>Over Current Trip Level</td>
<td>$I_{OCP}$</td>
<td>$V_{IN} = 5V, V_{OUT} = 1.2V$</td>
<td>6.5</td>
<td>8.5</td>
<td></td>
<td>A</td>
</tr>
</tbody>
</table>
### Table of Values

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>TEST CONDITIONS</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNITS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Current Limit Retry Time (^{(4)})</td>
<td>(T_{CL_TRY})</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Precision Disable Threshold</td>
<td>(V_{DISABLE})</td>
<td>ENABLE pin logic going low</td>
<td>0.95</td>
<td>1.01</td>
<td>1.07</td>
<td>V</td>
</tr>
<tr>
<td>Precision Enable Threshold</td>
<td>(V_{EN})</td>
<td>ENABLE pin logic going high</td>
<td>1.08</td>
<td>1.12</td>
<td>1.16</td>
<td>V</td>
</tr>
<tr>
<td>ENABLE Hysteresis</td>
<td>(EN_{HYS})</td>
<td></td>
<td></td>
<td></td>
<td>110</td>
<td>mV</td>
</tr>
<tr>
<td>ENABLE Pin Input Current</td>
<td>(I_{EN})</td>
<td>Device not switching; ENABLE pin has ~(110)k(\Omega) pull down</td>
<td>40</td>
<td>90</td>
<td></td>
<td>(\mu A)</td>
</tr>
<tr>
<td>ENABLE Pull-Up Resistance</td>
<td>(R_{EN_UP})</td>
<td>Not a passive element and changes with (VIN)</td>
<td>190</td>
<td></td>
<td></td>
<td>k(\Omega)</td>
</tr>
<tr>
<td>ENABLE Pull-Down Resistance</td>
<td>(R_{EN_DOWN})</td>
<td>Not a passive element and changes with (VIN)</td>
<td>110</td>
<td></td>
<td></td>
<td>k(\Omega)</td>
</tr>
<tr>
<td>Switching Frequency</td>
<td>(F_{SW})</td>
<td>Free running frequency of oscillator</td>
<td>1.8</td>
<td>2.0</td>
<td>2.2</td>
<td>MHz</td>
</tr>
<tr>
<td>POK High Range</td>
<td>(POK_RANGE)</td>
<td>Typical percentage range within (V_{OUT}) nominal when POK is asserted high</td>
<td>(\pm 10)</td>
<td></td>
<td></td>
<td>%</td>
</tr>
<tr>
<td>POK Low Voltage</td>
<td>(V_{POKL})</td>
<td>With 4mA current sink into POK</td>
<td>0.4</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>POK High Voltage</td>
<td>(V_{POKH})</td>
<td>(2.7V \leq V_{IN} \leq 6.6V)</td>
<td>(V_{IN})</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td>POK Pin Leakage Current (^{(4)})</td>
<td>(I_{POKH})</td>
<td>POK is high</td>
<td>1</td>
<td></td>
<td></td>
<td>(\mu A)</td>
</tr>
</tbody>
</table>

\(^{(3)}\) The VFB pin is a sensitive node. Do not touch VFB while the device is in regulation.

\(^{(4)}\) Parameter not production tested but is guaranteed by design.
TYPICAL PERFORMANCE CURVES

Efficiency vs. Output Current

Output Voltage vs. Output Current

Output Voltage vs. Output Current

Output Voltage vs. Output Current
TYPICAL PERFORMANCE CURVES (CONTINUED)

Output Voltage vs. Output Current

Output Voltage vs. Output Current

Output Voltage vs. Temperature

Output Voltage vs. Temperature

Output Voltage vs. Temperature

Output Voltage vs. Temperature
TYPICAL PERFORMANCE CURVES (CONTINUED)

Input Voltage vs. Output Voltage

No Thermal Derating

EMI Performance

CONDITIONS
V_{IN} = 5.0V
V_{OUT} = 1.8V
TA = 25°C
LOAD = 0.01A

CONDITIONS
V_{OUT} = 1.8V
TA = 0°C
LOAD = 2A

CONDITIONS
V_{OUT} = 1.8V
TA = 25°C
LOAD = 4A

CONDITIONS
V_{OUT} = 1.8V
TA = 85°C
LOAD = 6A

CONDITIONS
V_{IN} = 5.0V
V_{OUT} = 3.3V
LOAD = 4A

CONDITIONS
V_{IN} = 5.0V
V_{OUT} = 1.0V
LOAD = 1Ω

CONDITIONS
V_{IN} = 5.0V
V_{OUT, NOM} = 1.2V
LOAD = 0.33Ω

CONDITIONS
V_{IN} = 5.0V
V_{OUT, NOM} = 3.3V
LOAD = 1Ω

CISPR 22 Class B 10m

LEVEL (dBµV/m)
FREQUENCY (MHz)
TYPICAL PERFORMANCE CHARACTERISTICS

Output Ripple at 20MHz Bandwidth

- **VOUT = 1.0V** (AC Coupled)
  - 10mV / DIV
- **VOUT = 1.8V** (AC Coupled)
  - 10mV / DIV
- **VOUT = 3.3V** (AC Coupled)
  - 10mV / DIV

**CONDITIONS**
- **VIN = 5V**
- **COUT = 2x100µF**
- **No Load**

Output Ripple at 500MHz Bandwidth

- **VOUT = 1.0V** (AC Coupled)
  - 10mV / DIV
- **VOUT = 1.8V** (AC Coupled)
  - 10mV / DIV
- **VOUT = 3.3V** (AC Coupled)
  - 10mV / DIV

**CONDITIONS**
- **VIN = 5V**
- **COUT = 2 x (100µF, 22µF, 10µF, 4.7µF, 2.2µF, 1µF, 0.1µF)**

Load Transient 0 to 6A

- **VOUT (AC Coupled)**
  - **LOAD = 0A**
  - **LOAD = 6A**

**CONDITIONS**
- **VIN = 3.3V**
- **VOUT = 1.2V**
- **CA = 47pF**
- **COUT = 4x100µF**

Improved Load Transient 0 to 6A

- **VOUT (AC Coupled)**
  - **LOAD = 0A**
  - **LOAD = 6A**

**CONDITIONS**
- **VIN = 3.3V**
- **VOUT = 1.2V**
- **CA = 47pF**
- **COUT = 4x100µF**
TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)

Load Transient 0 to 6A

CONNECTIONS
VIN = 5V
VOUT = 1.2V
CA = 15pF
COUT = 4x100µF
LOAD = 0A
6A

Load Transient 0 to 6A

CONNECTIONS
VIN = 5V
VOUT = 1.2V
CA = 47pF
COUT = 4x100µF
LOAD = 0A
6A

LOAD Transient 0 to 6A

CONNECTIONS
VIN = 5V
VOUT = 3.3V
CA = 10pF
COUT = 2x100µF
LOAD = 0A
6A

Improved Load Transient 0 to 6A

CONNECTIONS
VIN = 5V
VOUT = 1.2V
CA = 47pF
COUT = 4x100µF
LOAD = 0A
6A

Improved Load Transient 0 to 6A

CONNECTIONS
VIN = 5V
VOUT = 3.3V
CA = 33pF
COUT = 4x100µF
LOAD = 0A
6A

Startup and Shutdown at No Load

CONNECTIONS
VIN = 5V
VOUT = 3.3V
CA = 10pF
COUT = 2 x 100µF
LOAD = 0A
6A

Startup and Shutdown at 6A Load

CONNECTIONS
VIN = 5V
VOUT = 3.3V
CA = 10pF
COUT = 2 x 100µF
LOAD = 0A
6A
**TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)**

**PVIN Startup at No Load**
- **CONDITIONS**
  - VIN = 5V
  - VOUT = 3.3V
  - CA = 10pF
  - COUT = 2 x 100µF

**PVIN Shutdown at No Load**
- **CONDITIONS**
  - VIN = 5V
  - VOUT = 3.3V
  - CA = 10pF
  - COUT = 2 x 100µF

**PVIN Startup at 6A Load**
- **CONDITIONS**
  - VIN = 5V
  - VOUT = 1V
  - CA = 15pF
  - COUT = 2 x 100µF

**PVIN Shutdown at 6A Load**
- **CONDITIONS**
  - VIN = 5V
  - VOUT = 1V
  - CA = 15pF
  - COUT = 2 x 100µF

**Pre-Bias Startup**
- **CONDITIONS**
  - VIN = 5V
  - VOUT = 1V
  - POK = 50% Pre-Bias
  - 10% Pre-Bias
  - 90% Pre-Bias
TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)

Short Circuit and Recovery

 CONDITIONS
VIN = 6.6V, VOUT = 3.3V

POK
"Re-Try"

VOUT
VSW
LOAD

 CONDITIONS
VIN = 6.6V, VOUT = 3.3V

POK

VOUT
VSW
SS
**FUNCTIONAL DESCRIPTION**

**Synchronous DC-DC Step-Down PowerSoC**

The EN6363QI is a synchronous DC-DC PowerSoC with integrated power MOSFET switches and integrated inductor. The nominal input voltage range is 2.7V to 6.6V. The output voltage is programmed using an external resistor divider network. The control loop is voltage-mode with a type III compensation network. Much of the compensation circuitry is internal to the device, but a phase-lead capacitor and resistor are required to complete the compensation network. The type III voltage mode architecture with integrated compensation maximizes loop bandwidth without increasing complexity. This architecture is designed to maintain stability with excellent gain and phase margin and improve transient response. The enhanced voltage mode architecture also provides high noise immunity at light load and maintains excellent line and load regulation. Up to 6A of continuous output current can be drawn from this converter. The 2MHz switching frequency allows the use of smaller case size input and output capacitors within a small footprint.
The EN6363QI architecture includes the following features.

**Operational Features:**
- Precision enable circuit with tight threshold range
- Soft-start circuit allowing controlled startup when the converter is initially powered up
- Power OK circuit indicating the output voltage is greater than 90% of programmed value

**Protection Features:**
- Over-current protection from short circuit or excessive load current
- Thermal shutdown with hysteresis to prevent over temperature stress
- Output voltage pre-bias startup protection for smooth monotonic startup
- Under-voltage lockout protection to prevent under-voltage operation

**Precision Enable Operation**

The enable (ENABLE) pin provides a mean to startup or to shutdown the device. When the ENABLE pin is asserted high, the device will undergo a normal soft-start where the output will rise monotonically into regulation. Asserting a logic low on this pin will deactivate the device by turning off the internal power switches and the POK flag will also be pulled low. The ENABLE pin is connected through an internal divider network to AVIN and AGND. If left floating, the ENABLE voltage will be equal to the AVIN voltage and the value set by the divider network ratio (~2.5):

\[ V_{EN\ (FLOATING)} \approx AVIN / 2.5 \]

The precision enable circuit ensures the device will enable or disable within a tight voltage range for both high or low logic. In order to ensure a known state the ENABLE pin should be pulled high or low. See the Electrical Characteristics Table for technical specifications for the ENABLE pin.

**Soft-Start Operation**

The soft-start circuitry will reduce inrush current during startup as the regulator charges the output voltage up to nominal level gradually. The output rise time is controlled by the soft-start capacitor, which is placed between the SS pin and the AGND pin. When the part is enabled, the soft-start (SS) current generator charges the SS capacitor in a linear manner. Once the voltage on the SS capacitor reaches 0.6V, the controller selects the internal bandgap voltage as the reference. The voltage across the SS capacitor will continue ramping up until it reaches around 1.27V. The rise time is defined as the time needed by the output voltage to go from zero to the programmed value. The rise time \( t_{RISE} \) is given by the following equation:

\[ t_{RISE} [ms] = C_{SS} [nF] \times 0.13 \]

With a 10nF soft-start capacitance on the SS pin, the soft-start rise time will be set to 1.3ms. The recommended range for the value of the SS capacitor is between 10nF and 100nF. Note that excessive bulk capacitance on the output can cause an over current event on startup if the soft-start time is too low. Refer to the Compensation and Transient Response section for details on proper bulk capacitance usage.

**POK Operation**

The Power OK (POK) is an open drain signal (with internal 100kΩ pull-up to AVIN) to indicate if the output voltage is within the specified range. POK is asserted high when the rising output voltage exceeds 90% of the programmed output voltage. For a stronger pull-up, an external resistor may be connected to AVIN. If the
nominal output voltage falls outside the set range (typically 90% to 110% of nominal) the POK signal will be asserted low by an internal 4mA pull-down transistor.

**Over-Current Protection (OCP)**

The current limit function is achieved by sensing the current flowing through the topside power PFET. When the sensed current exceeds the over current trip point (see Electrical Characteristics Table), both power FETs are turned off for the remainder of the switching cycle. If the over-current condition is removed, the over-current protection circuit will enable normal PWM operation. In the event the OCP circuit trips at least 7 consecutive PWM cycles, the device enters a retry mode; the device is disabled for about 17ms and restarted with a normal soft-start. This cycle can continue indefinitely as long as the over current condition persists. The OCP circuit will disable operation and protect the device from excessive current during operation without compromising the full load capability of the device.

**Thermal Protection**

The thermal shutdown circuit disables the device operation (switching stops) when the junction temperature exceeds 160°C. When the junction temperature drops by approximately 25°C, the converter will re-start with a normal soft-start. By preventing operation at excessive temperatures, the thermal shutdown circuit will protect the device from over-stress.

**Pre-Bias Startup Protection**

The EN6363QI supports startup into a pre-biased output. A proprietary circuit ensures the output voltage rises from the pre-bias voltage level to the programmed output voltage on startup. During this soft-start period, the voltage rise is monotonic for output voltage range from 0% to 90% of nominal. If the pre-bias voltage is above 90% on startup, there might be a slight dip (~3%) in output voltage before it rises monotonically. If the pre-bias voltage is above 100% of nominal during startup, the device will not switch until the soft-start period is over. Note that when the device begins switching and the pre-bias output voltage is higher than nominal, the bottomside NFET will discharge the output quickly (but limited to 2-cycles to prevent excessive current) to bring the voltage back into regulation. The pre-bias protection circuit is designed to prevent improper behavior on startup regardless of the pre-bias output voltage during soft-start.

**Input Under-Voltage Lock-Out (UVLO)**

When the device input voltage falls below UVLO, switching is disabled to prevent operation at insufficient voltage levels. During startup, the UVLO circuit ensures that the converter will not start switching until the input voltage is above the specified minimum voltage. Hysteresis and input de-glitch circuits are incorporated in order to ensure high noise immunity and prevent a false trigger in the UVLO voltage region.

**APPLICATION INFORMATION**

**Output Voltage Setting**

The EN6363QI output voltage is programmed using a simple resistor divider network (R_A and R_B). Figure 5 shows the resistor divider configuration.
Figure 5: V\text{OUT} Resistor Divider & Compensation Capacitor

The recommended R\text{A} resistor value is 249kΩ and the feedback voltage is typically 0.6V. Depending on the output voltage (V\text{OUT}), the R\text{B} resistor value may be calculated as shown in Figure 5. Since the accuracy of the output voltage setting is dependent upon the feedback voltage and the external resistors, 1% or better resistors are recommended. The external compensation capacitor (C\text{A}) and resistor (R\text{C}) is also required in parallel with R\text{A}. Depending on input and output voltage, the recommended external compensation values are shown in Table 1.

Table 1: External Compensation Recommendations

<table>
<thead>
<tr>
<th>V\text{IN}</th>
<th>V\text{OUT}</th>
<th>R\text{B}</th>
<th>C\text{A}</th>
<th>R\text{A}</th>
<th>R\text{C}</th>
<th>C\text{OUT} (0805)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3.3V</td>
<td>0.6V</td>
<td>OPEN</td>
<td>18pF</td>
<td>249kΩ</td>
<td>10kΩ</td>
<td>2 x 100µF</td>
</tr>
<tr>
<td></td>
<td>0.9V</td>
<td>590kΩ</td>
<td>18pF</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>1.0V</td>
<td>374kΩ</td>
<td>18pF</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>1.2V</td>
<td>249kΩ</td>
<td>15pF</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>1.5V</td>
<td>165kΩ</td>
<td>15pF</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>1.8V</td>
<td>124kΩ</td>
<td>15pF</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>2.5V</td>
<td>78.7kΩ</td>
<td>12pF</td>
<td></td>
<td></td>
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</tr>
<tr>
<td>5V</td>
<td>0.6V</td>
<td>OPEN</td>
<td>15pF</td>
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</tr>
<tr>
<td></td>
<td>0.9V</td>
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<td>1.2V</td>
<td>249kΩ</td>
<td>15pF</td>
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<tr>
<td></td>
<td>1.5V</td>
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<td></td>
<td>1.8V</td>
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<td></td>
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<tr>
<td></td>
<td>2.5V</td>
<td>78.7kΩ</td>
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<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3.3V</td>
<td>54.9kΩ</td>
<td>10pF</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>0.9V</td>
<td>590kΩ</td>
<td>15pF</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>1.0V</td>
<td>374kΩ</td>
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<tr>
<td></td>
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<td>3.3V</td>
<td>54.9kΩ</td>
<td>10pF</td>
<td></td>
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</table>
Compensation and Transient Response

The EN6363QI uses an enhanced type III voltage mode control architecture. Most of the compensation is internal, which simplifies the design. In some applications, improved transient performance may be desired with additional output capacitors (C_{OUT}). In such an instance, the phase-lead capacitor (C_A) can be adjusted depending on the total output capacitance. Using Table 1 as the reference for C_A, if C_{OUT} is increased, then the C_A should also be increased. The relationship is linearly shown below:

$$\Delta C_{OUT} \approx +100\mu F \rightarrow \Delta C_A \approx +10pF$$

As C_{OUT} increases and the C_A value is adjusted, the device bandwidth will reach its optimization level (at around 1/10th of the switching frequency). As shown in Table 1, the recommended C_A value is lower for the 5V input than 3.3V input. This is to ensure that the loop bandwidth is not over extended due to the increased gain at the higher input voltage range. The C_A value may be extrapolated for other input voltages. The limitation for adjusting the compensation is based on diminished return. Further adjustments by increasing C_{OUT} and increasing C_A may not yield better transient response or in some situations cause lower gain and phase margin. Over compensating with excessive output capacitance may also cause the device to trigger current limit on startup due to the energy required to charge the output up to regulation level. Due to such limitations, the recommended maximum output capacitance (C_{OUT_MAX}) is 400\mu F and the recommended maximum phase-lead capacitance (C_{A_MAX}) is 47pF.

Input Capacitor Selection

The input of synchronous buck regulators can be very noisy and should be decoupled properly in order to ensure stable operation. In addition, input parasitic line inductance can attribute to higher input voltage ripple. The EN6363QI requires a minimum of 2 x 47\mu F 0805 input capacitors. As the distance of the input power source to the input of the EN6363QI is increased, it is recommended to increase input capacitance in order to mitigate the line inductance from the source. Low-ESR ceramic capacitors should be used. The dielectric must be X5R or X7R rated and the size must be at least 0805 (EIA) due to derating. Y5V or equivalent dielectric formulations must not be used as these lose too much capacitance with frequency, temperature and bias voltage. In some applications, lower value capacitors are needed in parallel with the larger capacitors in order to provide high frequency decoupling. Larger electrolytic or tantalum bulk capacitors may be used in conjunction to increase total input capacitance but should not be used solely as a replacement for the ceramic capacitors.

<table>
<thead>
<tr>
<th>DESCRIPTION</th>
<th>MFG</th>
<th>P/N</th>
</tr>
</thead>
<tbody>
<tr>
<td>47\mu F ±20%, 10V X5R, 0805</td>
<td>Taiyo Yuden</td>
<td>LMK212BBJ476MG-T</td>
</tr>
<tr>
<td></td>
<td>Murata</td>
<td>GRM21BR61A476ME15L</td>
</tr>
<tr>
<td></td>
<td>TDK</td>
<td>C2012X5R1A476M125AC</td>
</tr>
</tbody>
</table>

Output Capacitor Selection

The output ripple of a synchronous buck converter can be attributed to its inductance, switching frequency and output decoupling. The EN6363QI requires a minimum of 2 x 100\mu F 0805 output capacitors. Low ESR ceramic capacitors should be used. The dielectric must be X5R or X7R rated and the size must be at least 0805 (EIA) due to derating. Y5V or equivalent dielectric formulations must not be used as these lose too much capacitance with frequency, temperature and bias voltage.
### Output Capacitors

<table>
<thead>
<tr>
<th>DESCRIPTION</th>
<th>MFG</th>
<th>P/N</th>
</tr>
</thead>
<tbody>
<tr>
<td>100µF ±20%, 6.3V, X5R, 0805</td>
<td>Murata</td>
<td>GRM21BR60J107ME15L</td>
</tr>
</tbody>
</table>

Output ripple voltage is determined by the aggregate output capacitor impedance. Output impedance, denoted as \( Z \), is comprised of effective series resistance (ESR) and effective series inductance (ESL):

\[
Z = ESR + ESL
\]

The resonant frequency of a ceramic capacitor is inversely proportional to the capacitance. Lower capacitance corresponds to higher resonant frequency. When two capacitors are placed in parallel, the benefit of both are combined. It is beneficial to decouple the output with capacitors of various capacitance and size. Placing them all in parallel reduces the impedance and will hence result in lower output ripple.

\[
\frac{1}{Z_{Total}} = \frac{1}{Z_1} + \frac{1}{Z_2} + \ldots + \frac{1}{Z_n}
\]

**THERMAL CONSIDERATIONS**

Thermal considerations are important elements of power supply design. Whenever there are power losses in a system, the heat that is generated by the power dissipation needs to be taken into account. The Intel Enpirion PowerSoC technology helps alleviate some of those concerns.

The EN6363QI DC-DC converter is packaged in a 4mm x 6mm x 2.5mm 34-pin QFN package. The QFN package is constructed with copper lead frames that have exposed thermal pads. The exposed thermal pad on the package should be soldered directly on to a copper ground pad on the printed circuit board (PCB) to act as a heat sink. The recommended maximum junction temperature for continuous operation is 125°C. Continuous operation above 125°C may reduce long-term reliability. The device has a thermal overload protection circuit designed to turn off the device at an approximate junction temperature value of 160°C.

The following example and calculations illustrate the thermal performance of the EN6363QI with the following parameters:

- \( V_{IN} = 5V \)
- \( V_{OUT} = 3.3V \)
- \( I_{OUT} = 6A \)

First, calculate the output power.

\[
P_{OUT} = V_{OUT} \times I_{OUT} = 3.3V \times 6A = 19.8W
\]

Next, determine the input power based on the efficiency (\( \eta \)) shown in Figure 6.
For $V_{IN} = 5V$, $V_{OUT} = 3.3V$ at 6A, $\eta \approx 91\%$

$$\eta = \frac{P_{OUT}}{P_{IN}} = 91\% \approx 0.91$$

$$P_{IN} = \frac{P_{OUT}}{\eta}$$

$$P_{IN} \approx 19.8W / 0.91 \approx 21.76W \approx 21.8W$$

The power dissipation ($P_D$) is the power loss in the system and can be calculated by subtracting the output power from the input power.

$$P_D = P_{IN} - P_{OUT}$$

$$= 21.8W - 19.8W \approx 2W$$

With the power dissipation known, the temperature rise in the device may be estimated based on the theta JA value ($\theta_{JA}$). The $\theta_{JA}$ parameter estimates how much the temperature will rise in the device for every watt of power dissipation. The EN6363QI has a $\theta_{JA}$ value of 12.5°C/W without airflow.

Determine the change in temperature ($\Delta T$) based on $P_D$ and $\theta_{JA}$.

$$\Delta T = P_D \times \theta_{JA}$$

$$\Delta T \approx 2W \times 12.5°C/W \approx 25°C$$

The junction temperature ($T_J$) of the device is approximately the ambient temperature ($T_A$) plus the change in temperature. We assume the initial ambient temperature to be 25°C.

$$T_J = T_A + \Delta T$$

$$T_J \approx 25°C + 25°C \approx 50°C$$

The maximum operating junction temperature ($T_{JMAX}$) of the device is 125°C, so the device can operate at a higher ambient temperature. The maximum ambient temperature ($T_{AMAX}$) allowed can be calculated.

$$T_{AMAX} = T_{JMAX} - P_D \times \theta_{JA}$$

$$\approx 125°C - 25°C \approx 100°C$$

The maximum ambient temperature the device can reach is 100°C given the input and output conditions. Note that the efficiency will be slightly lower at higher temperatures and this calculation is an estimate.
APPLICATION CIRCUITS

Figure 7: Smallest Solution Size Application Circuit for $V_{OUT} = 1.8V$

Figure 8: Improved Transient Response Application Circuit for $V_{OUT} = 1.8V$
LAYOUT RECOMMENDATIONS

Figure 9 shows critical components and layer 1 traces of a recommended minimum footprint EN6363QI layout. ENABLE and other small signal pins need to be connected and routed according to specific customer application. Visit the Enpirion Power Solutions website at www.altera.com/powersoc for more information regarding layout. Please refer to this Figure 9 while reading the layout recommendations in this section.

**Figure 9: Top PCB Layer Critical Components and Copper for Minimum Footprint (Top View)**

**Recommendation 1:** Input and output filter capacitors should be placed on the same side of the PCB, and as close to the EN6363QI package as possible. They should be connected to the device with very short and wide traces. Do not use thermal reliefs or spokes when connecting the capacitor pads to the respective nodes. The Voltage and GND traces between the capacitors and the EN6363QI should be as close to each other as possible so that the gap between the two nodes is minimized, even under the capacitors.

**Recommendation 2:** Half of the PGND pins are dedicated to the input circuit and the other half to the output circuit. The slit shown in Figure 9 separating the input and output GND circuits helps minimize noise coupling between the converter input and output switching loops.

**Recommendation 3:** The system ground plane should be on the 2nd layer (below the surface layer). This ground plane should be continuous and un-interrupted.

**Recommendation 4:** The large thermal pad underneath the device must be connected to the system ground plane through as many vias as possible. The drill diameter of the vias should be 0.33mm, and the vias must have at least 1-oz. copper plating on the inside wall, making the finished hole size around 0.2mm to 0.26mm. Do not use thermal reliefs or spokes to connect the vias to the ground plane. This connection provides the path for heat dissipation from the converter. Please see Figure 9.
Recommendation 5: Multiple small vias (the same size as the thermal vias discussed in recommendation 4 should be used to connect ground terminal of the input capacitor and output capacitors to the system ground plane. Put the vias under the capacitors along the edge of the GND copper closest to the Voltage copper. Please see Figure 9. These vias connect the input/output filter capacitors to the GND plane, and help reduce parasitic inductances in the input and output current loops. If the vias cannot be placed under $C_{IN}$ and $C_{OUT}$, then put them just outside the capacitors along the GND slit separating the two components. Do not use thermal reliefs or spokes to connect these vias to the ground plane.

Recommendation 6: AVIN is the power supply for the internal small-signal control circuits. It should be connected to the input voltage at a quiet point. In Figure 9 this connection is made at the input capacitor furthest from the PVIN pin and on the input source side. Avoid connecting AVIN near the PVIN pin even though it is the same node as the input ripple is higher there.

Recommendation 7: The $V_{OUT}$ sense point should be connected at the last output filter capacitor furthest from the VOUT pins. Keep the sense trace as short as possible in order to avoid noise coupling into the control loop.

Recommendation 8: Keep $R_A$, $C_A$, $R_C$ and $R_B$ close to the VFB pin (see Figure 9). The VFB pin is a high-impedance, sensitive node. Keep the trace to this pin as short as possible. Whenever possible, connect $R_B$ directly to the AGND pin instead of going through the GND plane. The AGND should connect to the PGND at a single point from the AGND pin to the PGND plane on the 2nd layer.

Recommendation 9: The layer 1 metal under the device must not be more than shown in Figure 9. See the following section regarding Exposed Metal on Bottom of Package. As with any switch-mode DC-DC converter, try not to run sensitive signal or control lines underneath the converter package on other layers.
DESIGN CONSIDERATIONS FOR LEAD-FRAME BASED MODULES

Exposed Metal on Bottom of Package

Lead-frames offer many advantages in thermal performance such as in reduced electrical lead resistance and in overall footprint; however, they do require some special considerations.

In the assembly process lead frame construction requires some of the lead-frame cantilevers be exposed at the point where wire-bond or internal passives are attached for mechanical support. This results in several small pads being exposed on the bottom of the package, as shown in Figure 10.

Only the thermal pad and the perimeter pads are to be mechanically or electrically connected to the board. The PCB top layer under the EN6363QI should be clear of any metal (copper pours, traces, or vias) except for the thermal pad. The “shaded-out” area in Figure 10 represents the area that should be clear of any metal on the top layer of the PCB. Any layer 1 metal under the shaded-out area runs the risk of undesirable shorted connections even if it is covered by solder mask.

The solder stencil aperture should be smaller than the PCB ground pad. This will prevent excess solder from causing bridging between adjacent pins or other exposed metal under the package. See Figure 11 for details.

![Figure 10: Lead-Frame exposed metal (Bottom View)](image)

Shaded area highlights exposed metal that is not to be mechanically or electrically connected to the PCB.
Figure 11: Landing Pattern with Solder Stencil (Top View)

The solder stencil aperture for the thermal PGND pad is shown in Figure 11 and is based on Enpirion power product manufacturing specifications.
PACKAGE DIMENSIONS

Figure 12: EN6363QI Package Dimensions

REVISION HISTORY

<table>
<thead>
<tr>
<th>Rev</th>
<th>Date</th>
<th>Change(s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td>June, 2017</td>
<td>Initial Release</td>
</tr>
<tr>
<td>B</td>
<td>Aug, 2017</td>
<td>Updated EMI Performance Curves on page 10 from 3m to 10m</td>
</tr>
<tr>
<td>C</td>
<td>March, 2018</td>
<td>Updated minimum operating VOUT to 0.6V from 0.75V</td>
</tr>
</tbody>
</table>

WHERE TO GET MORE INFORMATION

For more information about Intel® and Enpirion® PowerSoCs, visit:

www.altera.com/enpirion